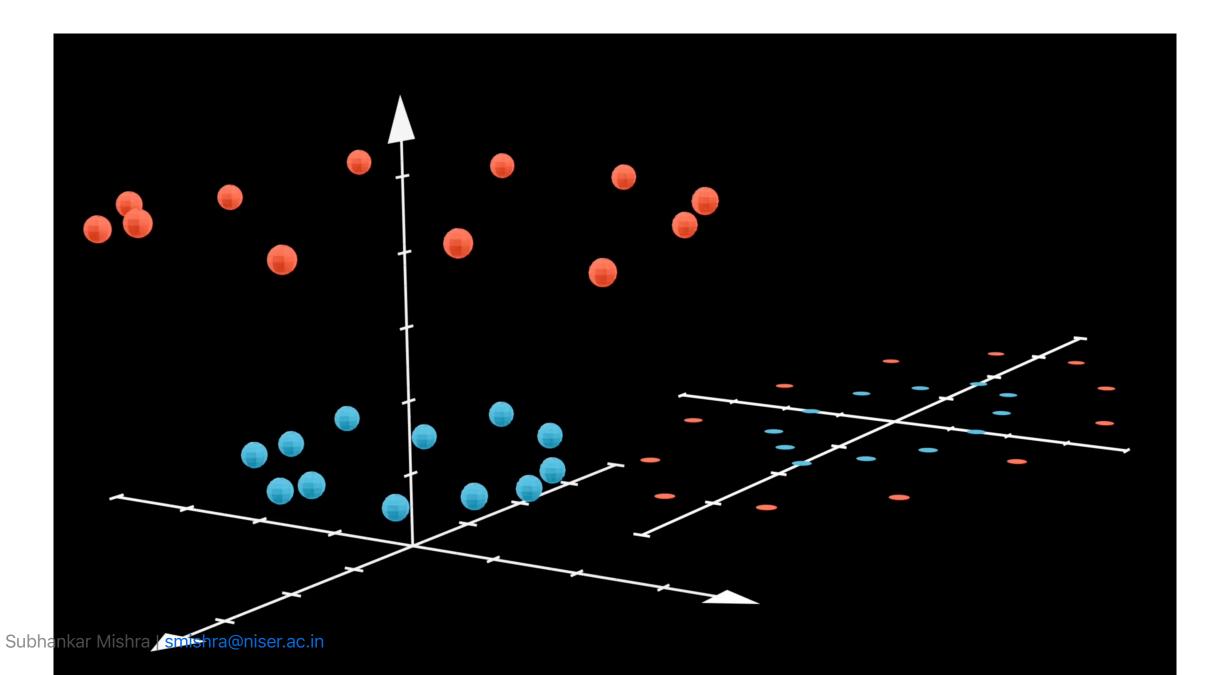
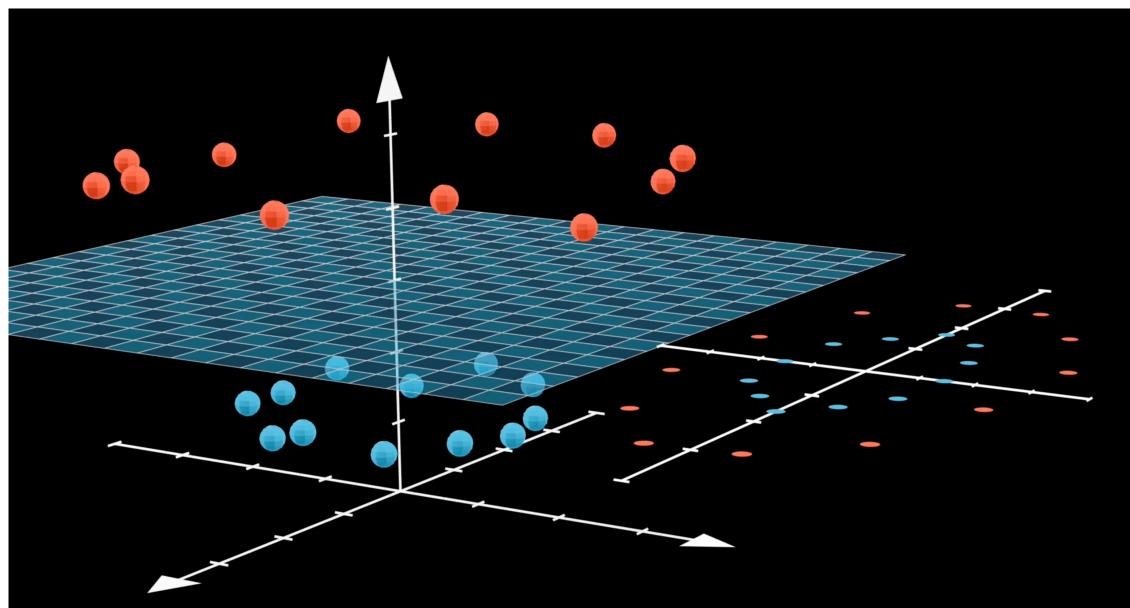
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# **SVM Recap**

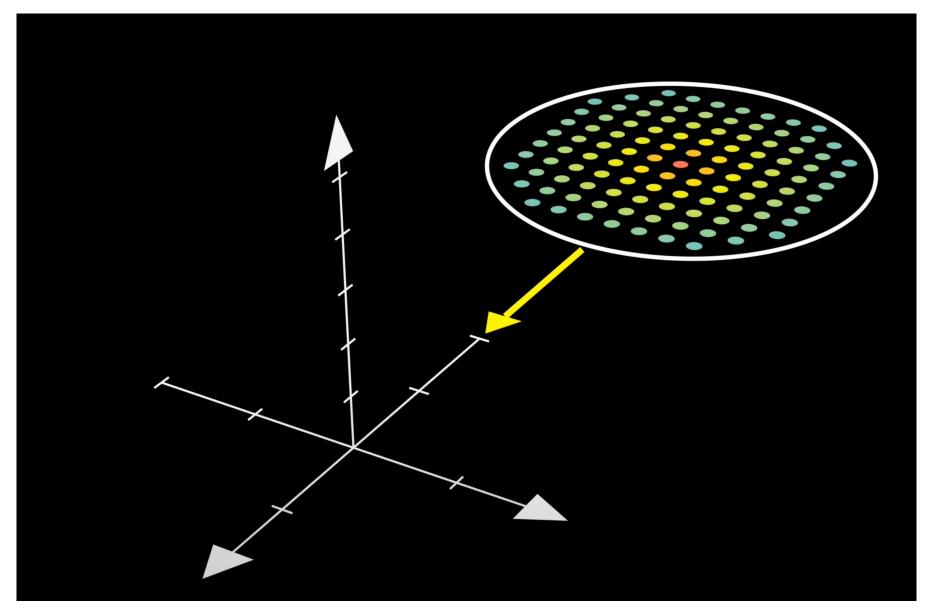


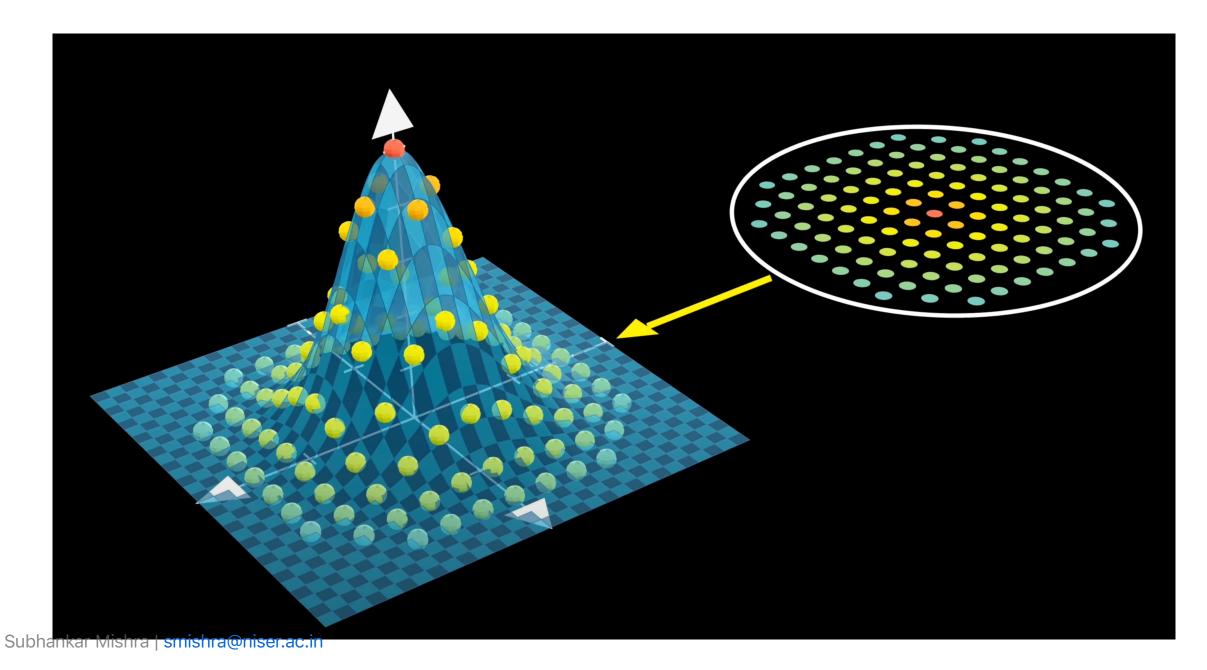


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#### **RBF Kernel**

$$k(\mathbf{x},\mathbf{x}') = \exp\left(-rac{||\mathbf{x}-\mathbf{x}'||^2}{2\sigma^2}
ight)$$





# 3.5 k-Nearest Neighbors (kNN)

A Non-parametric Learning Algorithm

## What is k-Nearest Neighbors?

- Non-parametric learning algorithm
- Instance-based learning (lazy learning)
- Keeps all training examples in memory
- No explicit model building phase
- Makes predictions based on similarity to training examples

**Key Characteristic**: Unlike other algorithms that discard training data after model building, kNN retains all training data for prediction.

## The kNN Learning Principle

## **Inductive Bias: Nearby Points Have Similar Labels**

Consider a test point among training examples (positive and negative). Most likely, you'd predict the label based on nearby points.

**kNN's Core Assumption**: Examples that are close in feature space should have similar labels.

## The Algorithm:

- 1. **Training**: Simply store all training examples
- 2. **Prediction**: Find the training example x most similar to test example  $\hat{x}$
- 3. Decision: Predict the same label as the nearest neighbor

#### The Problem with k=1

### **Issue: Overfitting to Label Noise**

- Single nearest neighbor can be an outlier
- Cannot consider "preponderance of evidence"
- Makes unnecessary errors due to noisy labels

## Solution: Use Multiple Neighbors (k > 1)

- Consider k nearest neighbors
- Let them vote on the correct class
- Majority wins!

**Example**: For k=3, if 2 neighbors are positive and 1 is negative, predict positive.

## **kNN Algorithm Pseudocode**

```
Algorithm: KNN-Predict(D, K, \hat{x})
1: S ← []
                                          // empty list
2: for n = 1 to N do
3: S \leftarrow S \oplus (d(xn, \hat{x}), n) // store distance to training example n
4: end for
5: S ← sort(S)
                                         // put lowest-distance objects first
6: ŷ ← 0
7: for k = 1 to K do
8: \langle dist, n \rangle \leftarrow Sk
                                        // kth closest data point
9: \hat{y} \leftarrow \hat{y} + yn
                                        // vote according to label
10: end for
                                         // return +1 if \hat{y} > 0, -1 if \hat{y} < 0
11: return sign(ŷ)
```

**Note**: No explicit training phase - just store the data!

## **Geometric Intuition**

## Thinking of Examples as Vectors

The biggest advantage of representing examples as vectors in high-dimensional space is that it allows us to apply **geometric concepts** to machine learning.

**Example**: Distance between  $\langle 2, 3 \rangle$  and  $\langle 6, 1 \rangle$ :

$$d = \sqrt{(2-6)^2 + (3-1)^2} = \sqrt{16 + 4} = \sqrt{20} \approx 4.24$$

#### **General Euclidean Distance** in D dimensions:

$$d(a, b) = \sqrt{[\Sigma(ai - bi)^2]}$$

This geometric thinking enables us to measure similarity and make predictions based on proximity.

#### **Distance Functions**

The **closeness** of two points is measured by a distance function:

#### 1. Euclidean Distance

$$d(xi, xj) = \sqrt{(\Sigma(xi^{(l)} - xj^{(l)})^2)}$$

## 2. Cosine Similarity

$$s(xi, xk) = cos(\theta(xi, xk)) = (\Sigma xi^{(j)} * xk^{(j)}) / (\sqrt{\Sigma(xi^{(j)})^2} * \sqrt{\Sigma(xk^{(j)})^2})$$

Cosine Distance =  $-1 \times cosine similarity$ 

#### **Distance Functions**

#### **Other Common Metrics:**

- Manhattan Distance: Sum of absolute differences
- Chebyshev Distance: Maximum difference across dimensions
- Hamming Distance: For categorical data

## **Choosing K: The Bias-Variance Trade-off**

#### The Big Question: How to Choose K?

- **K** = **1**: Risk of overfitting to noise
- K = N: Always predicts majority class (underfitting)
- K is a hyperparameter that controls bias-variance trade-off

#### **Guidelines:**

- Small K: More sensitive to noise, complex decision boundaries
- Large K: Smoother decision boundaries, may miss local patterns
- Use cross-validation to find optimal K
- Try odd values to avoid ties in voting

### **kNN's Inductive Bias & Feature Problems**

### **Core Assumptions:**

- 1. Locality: Nearby points should have the same label
- 2. Feature Equality: All features are equally important!

#### **kNN's Inductive Bias & Feature Problems**

#### The Feature Scale Problem:

#### **Classifying Cricket Players by Position**

- Features: Age (years) and Annual Income (₹ lakhs)
- Age: 18-40 years (small range)
- Income: 50-15,000 lakhs (huge range!)
- Distance dominated by income differences
- Age becomes irrelevant despite being important for position classification

Without normalization: A 25-year-old earning ₹500 lakhs appears "closer" to a 35-year-old earning ₹600 lakhs than to a 24-year-old earning ₹100 lakhs, even though age might be more relevant for playing position!

### **kNN's Inductive Bias & Feature Problems**

#### **Contrast with Decision Trees:**

- **Decision Trees**: Find the most useful features
- kNN: Uses every feature equally, ignores importance

Implication: kNN struggles with irrelevant features and different scales

## **kNN: Advantages & Disadvantages**

### Advantages:

- Simple to understand and implement
- No assumptions about data distribution
- **Effective** for non-linear problems
- Locally adaptive: Decision boundaries follow data density

### Disadvantages:

- Memory intensive: Stores all training data
- Computationally expensive: Distance calculations for every prediction
- Sensitive to irrelevant features (curse of dimensionality)
- Sensitive to feature scale: Requires preprocessing

## **kNN: Fails**

#### When kNN Fails:

- High-dimensional data: All points become equidistant
- Irrelevant features: Noise dominates signal
- Large datasets: Memory and computation challenges

#### **Practical Guidelines**

#### When to use kNN:

- Small to medium datasets
- Non-linear relationships
- Local patterns important
- No clear parametric model

## **Essential Preprocessing:**

- Feature scaling: Normalize/standardize features
- Feature selection: Remove irrelevant features
- **Dimensionality reduction**: PCA for high dimensions

#### **Practical Guidelines**

### **Choosing k:**

- Use cross-validation to find optimal k
- Try odd values to avoid ties in voting
- Small k: Complex boundaries, sensitive to noise
- Large k: Smooth boundaries, may miss patterns

## **Summary & Key Takeaways**

#### kNN in a Nutshell:

- Non-parametric: No assumptions about data distribution
- Instance-based: Uses all training data for prediction
- Distance-dependent: Choice of metric is crucial
- Locally adaptive: Decision boundaries adapt to data density

#### **Critical Success Factors:**

- 1. Proper feature scaling (normalize/standardize)
- 2. Appropriate k selection (use cross-validation)
- 3. Relevant distance metric for your data type
- 4. Feature selection to remove noise

## **Summary & Key Takeaways**

### **Implementation Optimizations:**

- KD-trees/Ball trees: Fast neighbor search
- Approximate methods: Trade accuracy for speed

Simple yet powerful, but preprocessing and hyperparameter tuning are essential!

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References

For SVM Pictures

RBF Kernel Explained: Mapping Data to Infinite Dimensions