# CS460 - Project

# Machine Learning Based Digital Holographic Microscopy

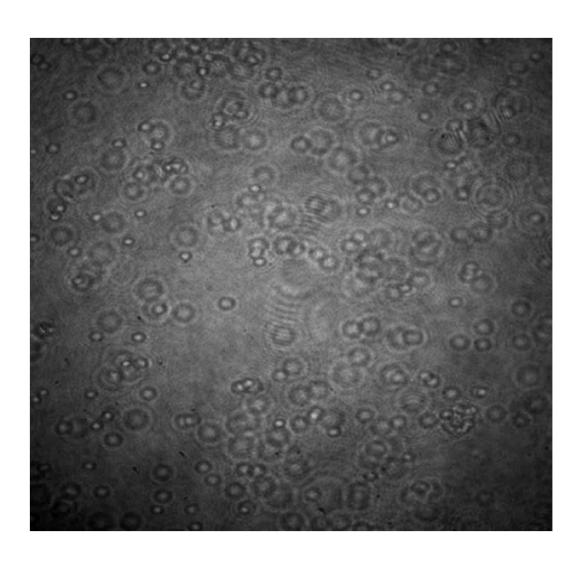
Group – 12 Aviral Verma

*Idea:* Using machine learning models to predict and track micro-particles in 3D in using the Digital Holographic Microscopy.

### Targets achieved:

- Generated Synthetic data corresponding to experimental data
- Studied and reproduced the existing works.

# Experimental Video:

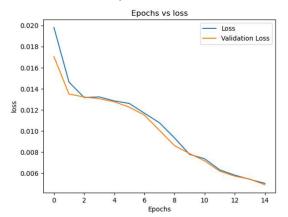


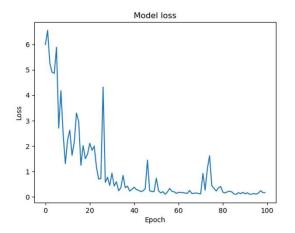
#### Reproduced Results:

**U-Net** 

#### Model used:

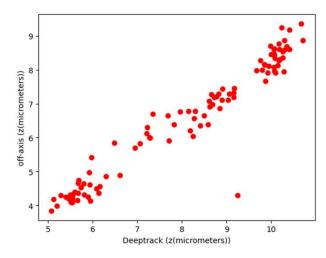
- 1. U-net
- 2. Localization and detection from Symmetries, Translations And Rotations (LodeSTAR)

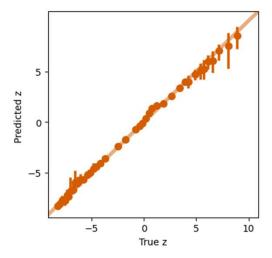




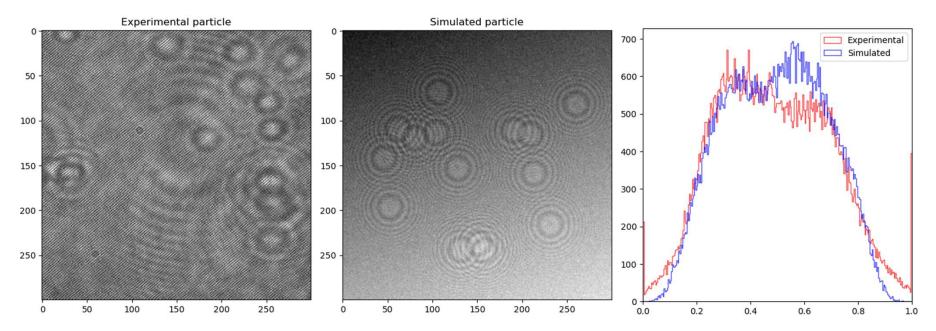
LodeSTAR

Values are predicted using existing Numerical Algorithms and Machine Learning.





### Simulated Data -



### Problems:

- 1. No. of Features in the U-Net (377)
- 2. Data Representation in LodeSTAR.

### Main References:

- Benjamin Midtvedt, Saga Helgadottir, Aykut Argun, Jesús Pineda, Daniel Midtvedt, Giovanni Volpe. "*Quantitative Digital Microscopy with Deep Learning*." Applied Physics Reviews 8 (2021), 011310. <a href="https://doi.org/10.1063/5.0034891">https://doi.org/10.1063/5.0034891</a>
- Ciraulo, B., Garcia-Guirado, J., de Miguel, I. et al. Long-range optofluidic control with plasmon heating. Nat. Commun. 12, 2001 (2021). https://doi.org/10.1038/s41467-021-22280-3
- Midtvedt, B., Pineda, J., Skärberg, F. et al. **Single-shot self-supervised object detection in microscopy**. Nat Commun **13**, 7492 (2022). https://doi.org/10.1038/s41467-022-35004-y