

Hierarchical Density-Based Clustering

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Clustering Analysis

- Clustering is an interesting problem of **unsupervised learning** \rightarrow cluster analysis does not use category labels that tag objects with prior identifiers.
- Deals with data structure partitioning in space.
- Forms the basis of exploratory data analysis (EDA.)



Figure 1. Dataset in 2D space



Condensing the Cluster Tree





(a) Dendrogram before Pruning



Classification of Clustering Algorithms

- Flat clustering creates a set of clusters that hold no inherent relationship to one another.
- Hierarchical clustering creates a family of sets of clusters.
- **Centroid-based/Parametric clustering** initializes centroids around which clusters form.
- **Density-based/Non-Parametric clustering** prepares clusters by quantifying density.

Clustering Type	Flat	Hierarchical
Centroid	K-means	Ward Complete-Linkage
Density	DBSCAN	HDBSCAN

- K-means:
- **suffers** from the choice of parameter *K*
- makes an assumption about the data distribution: the Gaussian-ball assumption
- DBSCAN:
- gets rid of the Gaussian-ball assumption
- the resolution parameter is **arbitrary** though
- Ward Complete-Linkage
- Gaussian-ball **assumption** creeps in; the hierarchical tree needs to be cut somewhere

Hierarchical Density-Based Spatial Clustering of Applications with Noise

- The protocol for **HDBSCAN** is as follows:
- Transformation of the dataset to mutual reachability space
- Constructing of a minimum spanning tree (MST)
- Preparation of a dendrogram for the MST
- Pruning of the dendrogram based on minimum cluster size

- Figure 4. Pruning the Dendrogram based on Minimum Cluster Size
- This step **condenses** down the large and complicated cluster hierarchy into a <u>smaller tree</u>.
- To do this, the algorithm takes in a parameter: the **minimum number of points that constitute a** cluster (min_cls_size.)
- Starting from the root, it is checked if one of the new clusters created by a split has fewer points than min_cls_size:
- If yes, the larger cluster retains the cluster identity
- If no, it is a **true cluster split**

Extraction of Clusters

We want to choose clusters that have a **long lifetime**.







(a) Extracted clusters

(b) Three clusters v/s Two clusters

Figure 5. Extracting stable clusters

• Extraction of clusters

Transformation of Space



Figure 2. Visualization of the Distance Transformation

 $d_{mreach-k}(a,b) = max\{core_k(a), core_k(b), d(a,b)\}$

- The entire dataset transformed to **mutual reachability space** by defining the distance between any two points as $d_{mreach-k}(a, b)$.
- This transformation has the effect of **tightening** clusters, rendering the algorithm more robust to noise.
- This transformation also has the effect of closely approximating the the hierarchy of level sets of whatever true density distribution the points were sampled from [1].

Preparation of the Minimum Spanning Tree

The stability of a cluster is defined as: $S = \sum_{p \in cluster} (\lambda_p - \lambda_{birth})$

- λ denotes $\frac{1}{distance}$
- λ_p denotes the λ value when the **point fell out of the cluster**.
- λ_{birth} denotes the λ value when the cluster split off and became independent.
- Starting from the leaf, it is checked if $S_{left}^i + S_{right}^i > S^{i-1}$:
 - If yes, the children are true clusters
 - Otherwise, the parent cluster is true

HDBSCAN in Action: An Application to Noisy, Nested Data



(a) Noisy *Two Moons*





(b) *K*-means

Figure 6. Performance of *K*-means & DBSCAN on *Two Moons*

(c) DBSCAN ($\eta = 4, \epsilon = 0.1$)







(c) HDBSCAN (min_cls_size = 400)

• A minimum spanning tree is a subset of the edges of a connected, edge-weighted undirected graph that connects all the vertices without cycles and ensures minimum possible total edge weight. • Standard algorithms to do so include **Prim's** [2] and **Kruskal's** [3] algorithms.



Figure 3. Conversion of the Dataset to the Minimum Spanning Tree

Figure 7. Performance of DBSCAN & HDBSCAN on Noisy Two Moons

Closing Remarks

- *K*-means fails to cluster nested datasets due to the Gaussian-ball assumption.
- DBSCAN handles nested datasets well. However, it is not robust to noise.
- HDBSCAN can handle noisy, nested data. It also performs well for clusters of varying densities.

References

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[3] J. B. Kruskal, "On the shortest spanning subtree of a graph and the traveling salesman problem," Proceedings of the American Mathematical society, vol. 7, no. 1, pp. 48–50, 1956.