# Studying the interior evolution of rocky exoplanets using machine learning

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#### Abstract

With the advancements of observation techniques, many Earth-like exoplanets have been discovered. But, these techniques can only probe exoplanetary atmospheres and thus, the mechanisms of interior are difficult to quantify. Studying timeevolution of interiors of these exoplanets might give us a better understanding of how planets like Earth formed. We present a machine-learning based approach to investigate and predict time-evolution of interiors of rocky exoplanets using neural networks (NN).

### 1 Introduction

The past two decades have proved to be the heyday for exoplanetary science. Thousands of planets have been discovered and characterized, and now the focus is shifting towards habitability and life. Most exoplanets are too far from us and any direct mission is unfeasible in human lifetime. Thus, one can only analyse their atmospheric spectrum. However, the atmosphere is always in interaction with the interior. As the interior cannot be probed with any means as of now, we are left with analytical models to predict how interiors may affect the atmospheres. There are two approaches for developing models to study exoplanetary interiors. The first concerns with the prediction of the interior structure, that is, composition and radial variation of the interior and then studying how it interacts with the atmosphere. This approach has been investigated the most as of now (Bower et al. [2018], Lorenzo [2018], Suissa et al. [2018], Wang et al. [2019], Huang et al. [2022] and many more). The second approach involves looking at the big picture, i.e., the time-evolution of the interior structure. This approach is more comprehensive, and can provide insight how planets like ours, came into being. Very few analytical models exist which simulate time-evolution of exoplanetary interiors. Furthermore, they are limited in their working; with multiple factors coming into play, the complexity also increases.

In recent times, machine-learning based approaches are being used as substitute for analytical models as they are often less computationally intensive and might go beyond limitations. Recently, Zhao and Ni [2021, 2022] used mixture density networks (MDNs) to predict interior structures of rocky and gaseous exoplanets. This involved using analytical models of Lorenzo [2018] for rocky exoplanets and adapted equations of hydrostatic equilibrium and rotation for gaseous planets to train the MDN.

In this paper, we have tried to go with a similar approach for modeling the interior evolution of exoplanets. Here we describe a machine-learning surrogate model for interior evolution using the code package VPLanet first described in Barnes et al. [2020].

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# 2 Exoplanet Interiors and VPLanet

VPLanet is a software package developed to simulate the fundamental aspects of planetary evolution over Gyr timescales, focusing on Earth-like habitable worlds (Barnes et al. [2020]). It can model the atmospheric, internal, orbital, rotational, stellar, and galactic processes and mimic existing results. In this work, we use the MagmOc, an interior evolution module of VPLanet which uses simple physics to model the evolution of a solar system like rocky exoplanet right from its formation to atmospheric desiccation. This module is based on the previous work by Schaefer et al. [2016] and Elkins-Tanton [2008], and includes various parameters such as stellar heat, radioactive decay, and tidal interactions.

The simulation starts with a completely molten mantle that solidifies with time, causing change in various physical properties such as mantle potential temperature, water content in melt and atmosphere, escape of gases, etc. MagmOc is coupled with the STELLAR code of VPLanet which couples the stellar evolution too with the planet evolution. The code computes the evolution of the mantle potential temperature, solidification radius, water mass in the solid, magma ocean and atmosphere, oxygen mass in the solid, magma ocean and atmosphere, atmospheric pressure due to  $H_2O$  and  $O_2$ , Mass fraction of FeO and Fe<sub>2</sub>O<sub>3</sub> in the magma ocean, atmospheric net flux and the tidal and radiogenic heat sources. A typical run for the planet TOI776 b is shown in figure 1.

TOI-776 b:  $M_{H_{2}O}^{ini}$  = 10.0 TO, *e* = 0.06, Abundance of  ${}^{40}K$  = 1.0 × Earth

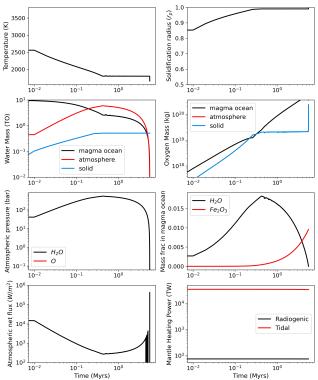


Figure 1: VPLanet simulation for TOI776 b, a super earth planet with mass about 4 times of Earth

and radius of 1.85 times of earth at a initial water mass of 10 TO. The figure shows how various properties of the planet must have evolved till the desiccation of the panet's atmosphere.

The code can run the simulation till complete desiccation of the atmosphere or till the planet reaches habitable zone. However, it takes several minutes to run till the desiccation, and sometimes hours to simulate till the habitable zone, especially when the proportion of water is high or the planet is far from the host star. In these cases, the output file becomes large in size. We aim to produce a surrogate model to the code using machine learning to reduce the runtime of the models.

# **3** Neural Networks

Neural networks are a class of machine learning algorithms inspired by the human brain, designed to solve a variety of complex problems. They consist of interconnected layers of artificial neurons where each neuron receives input from one or more neurons in the previous layer, and produces an output that is transmitted to one or more neurons in the next layer. By adjusting the strength of these connections, the neural network can learn to recognise patterns in the input data and make predictions or classifications based on those patterns.

Multi-layer perceptron (MLP) is a type of neural network used for supervised learning. It is composed of input, hidden, and output layers of nodes, and each node is connected to every node in the next layer. The network uses weights and biases to adjust the strengths of connections between nodes, which are updated during training using an optimization algorithms. The main feature of using MLP in our model is that it can handle both linear and nonlinear relationships between inputs and outputs, making it a powerful tool for our work.

# 4 Implementation of the model

#### 4.1 Dataset

Instead of using all output parameters of MagmOc, we selected five which are the most fundamental to govern the evolution of the system, viz., the mass of the star  $m_s$  (in  $M_{sun}$  units), the star-planet distance a (semi major axis of the orbit in AU), mass of the planet  $m_p$  (in  $M_{earth}$  units), radius of the planet  $r_p$  (in  $R_{earth}$  units), and the initial water content on the magma ocean  $m_w$  (in TO= terrestrial ocean units, 1TO=1.39 × 10<sup>21</sup> kg). Note that  $r_p$  was calculated using values of  $m_p$  at constant density of 4000 kgm<sup>-3</sup>. The density of the magma ocean melt is kept constant at a density of 4000 kgm<sup>-3</sup>.

The complete dataset consists of three parts, first part based on the TRAPPIST planetary system ( $m_s = \{0.1, 0.2\}; a = \{0.01, 0.03, 0.06\}; m_p = (0.5, 1, \dots, 3.5, 4); r_p$ , and  $m_w = \{1.0, 2.0\}$ ), second part based on our solar system ( $m_s = \{0.8, 1.0, 1.2\}; a = \{0.1, 0.5, 1.0\}; m_p = (0.5, 1, \dots, 3.5, 4); r_p$ , and  $m_w = \{0.5, 1.0, 2.0\}$ ), and third part covers the intermediate values so that our model can be trained on most of the permutations to model Earth-sized exoplanets that can potentially host life.

The output of the simulation is stored in arrays containing the evolution of the parameters in each row in two separate text files for both the evolution of the star and the planet. We split the data randomly in the ratio of 80:20 for training:testing data.

# 4.2 Methodology

We started by training our datasets with a three hidden-layer MLP model from sklearn (Pedregosa et al. [2011]). The model contains 16 nodes in each layer. The input parameters include the five parameters mentioned in section 4.1 and an additional property whose evolution in the next step has to be evaluated. The activation function used in the model is relu with the adam optimizer. With a maximum iterations of 10000, the code optimizes for the given set of input parameters in few seconds. The code can be found at our GitHub repository.

We ran our model on the first dataset for trial basis as this was our smallest dataset in terms of size. Since each successive row of the output files represents a time-series evolution of the fate of planet, MLP was used to predict the second row of the evolution series given the five input parameters and the first row of the time-series (which is first 1000 years of evolution).

We train the model on to predict six planetary properties: (1) mantle potential temperature, (2) Net flux coming out of the atmosphere, (3) Pressure of water in the atmosphere, (4) mass of water in the magma ocean and the atmosphere combined, (5) mass of  $O_2$  in the magma ocean and the atmosphere combined, and (6) the mass of  $H_2$  escaping into space. The results are shown in figure 2.

When we trained the model to predict the  $11^{th}$  row given the  $10^{th}$  row, the accuracy improved significantly as shown in figure 3. We see that in figure 2, the accuracy of some of the properties is negative, indicating imperfect correlation between training and test data. However, in figure 3, we get a better correlation and higher accuracy solution. We claim that this behaviour occurs because initially, the variation in the evolving parameters is not effective due to which the model is not able to

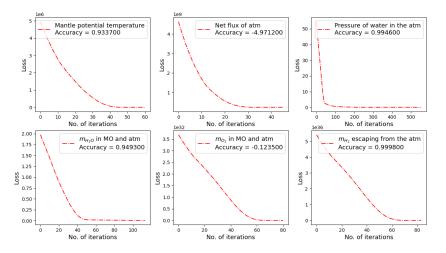


Figure 2: Loss function vs iterations of various output parameters when trained on  $2^{nd}$  row

correctly predict the output. However, when it is trained on the later data, the variation in most of the parameters is at the peak, and hence the model gives a good output.

We also tried to apply RNN and LSTM as part of our baselines, but the structure of our data limited us as RNN are more commonly used for test and image data. However, we plan to explore RNN more efficiently in the next half of the semester.

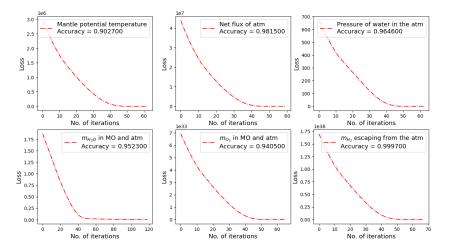


Figure 3: Loss function vs iterations of various output parameters when trained on 11<sup>th</sup> row

# 5 Future works

The complete plan is to develop a model that gets the five input parameters and predict the evolution over the entire timescale of the planet. For this, we plan to train the model using MLP to predict the first few rows and proceed with RNN thereafter. This is because the RNN consumes more memory and lacks accuracy for uncertain data like ours. Moreover, as this is a time-series data, we have an extra component to take care while training the model.

In the second half of the semester, we plan to optimize all the parameters for the first row with increased accuracy using MLP and RNN for the entire dataset. We will also look for the possibility of exploring other NN algorithms if required. The next step would be to apply the complete model on dataset (3) and achieve higher accuracy. Thereafter we may explore for a more detailed dataset varying more input parameters (that have been fixed to Earth-like values presently).

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