

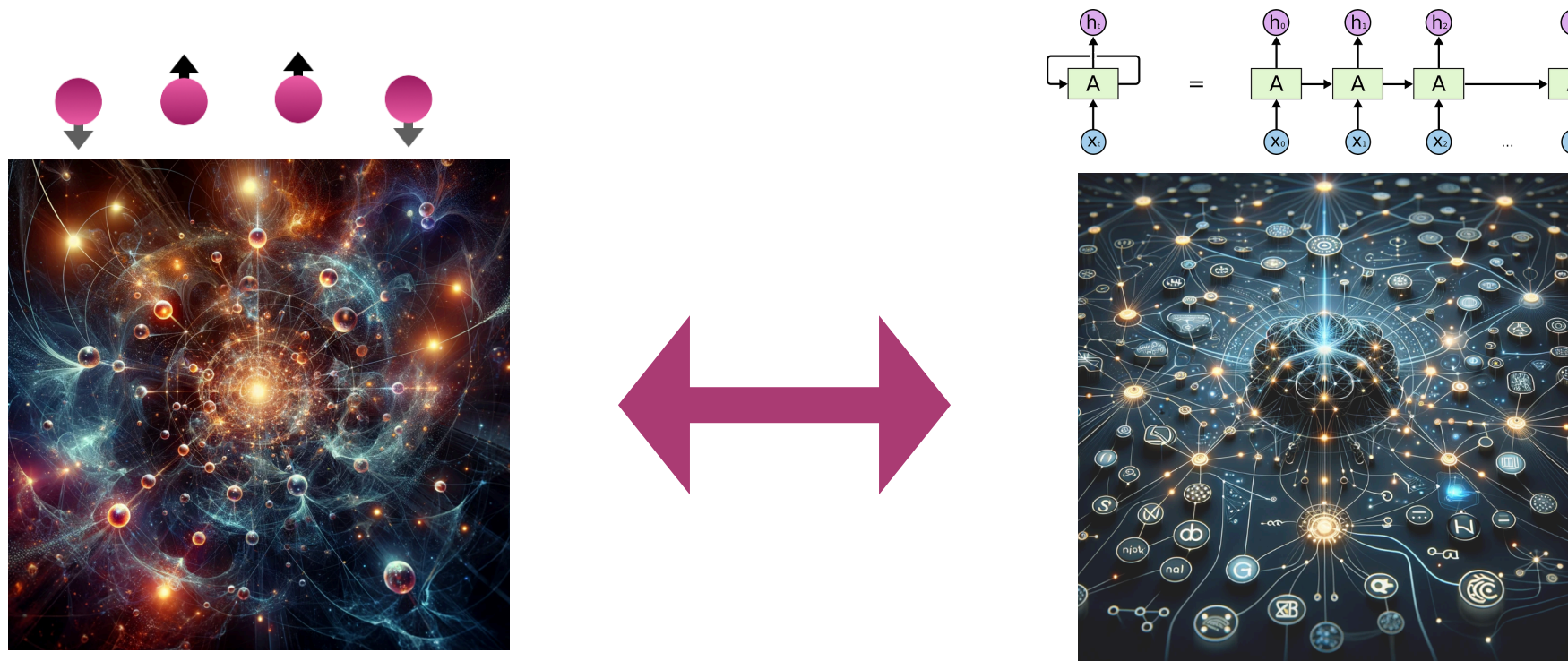
# From explainable NLP to quantum dynamics prediction:

A two-way synergy between many-body quantum physics and temporal machine learning models

Thiparat Chotibut (Thip)

Chula Intelligent and Complex Systems Research Unit,  
Chulalongkorn University, Bangkok, Thailand

April 18, 2024  
CS Katha Barta



CHICS



จุฬาลงกรณ์  
มหาวิทยาลัย  
CHULALONGKORN UNIVERSITY



# Chulalongkorn University, Bangkok





# Chulalongkorn University, Bangkok





# Chula Intelligent & Complex Systems

Welcome!

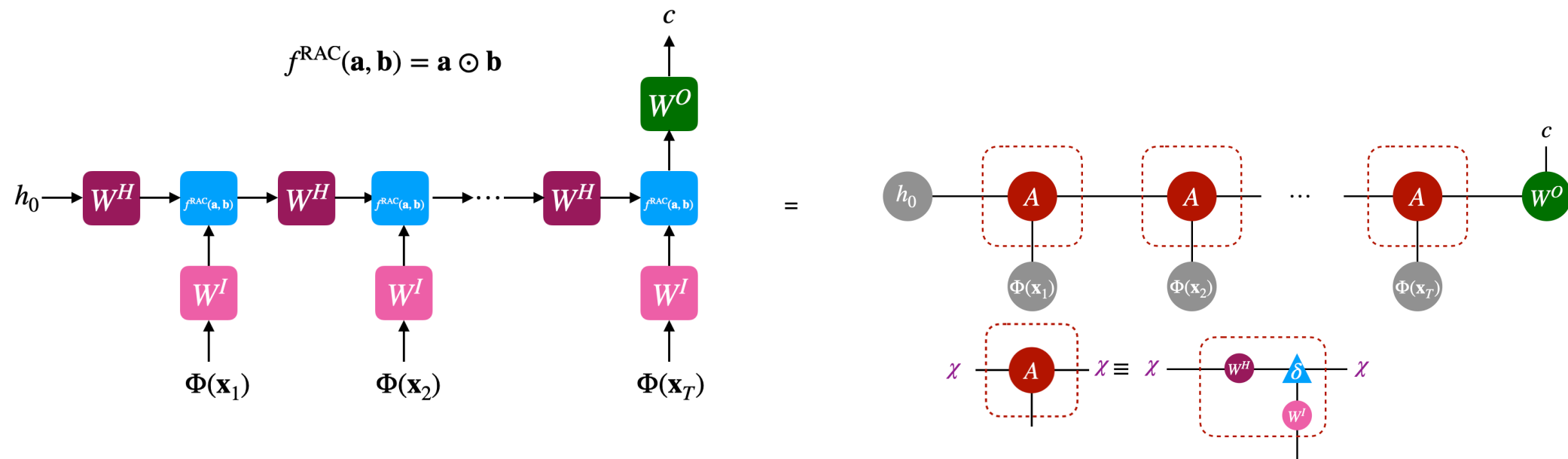
Our research lab investigates scientific frontiers at the intersection of complex systems and intelligent systems. See more details in [research & publications](#).





# Outline

## Part 1: Quantum Meets Language



J. Tangpanitanon, ..., T. Chotibut

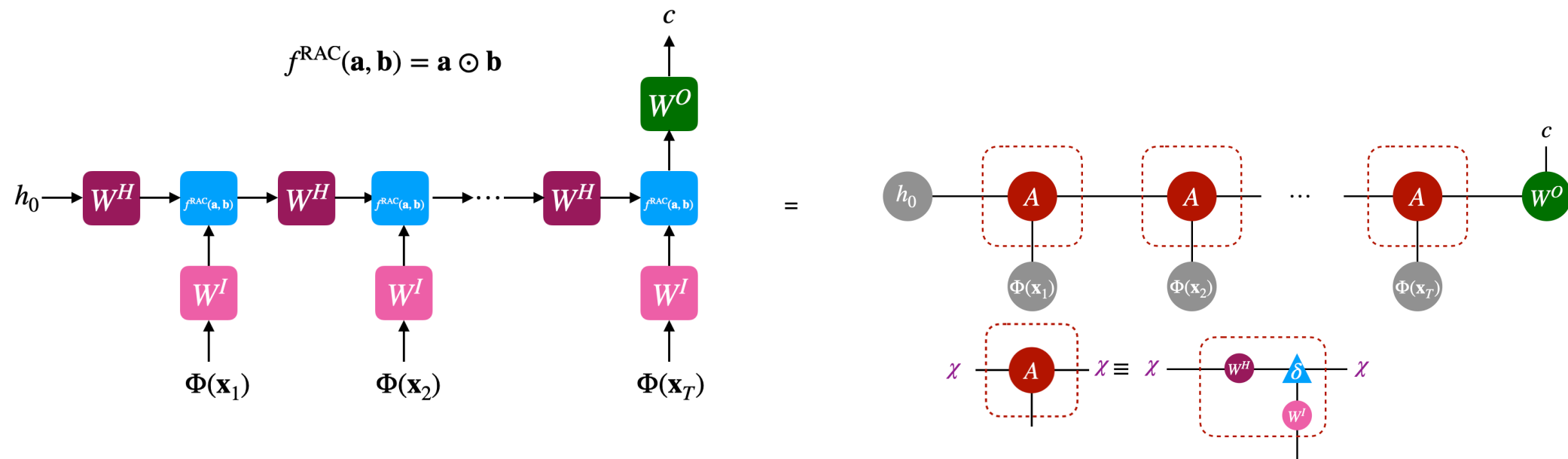


NJP 2022



# Outline

## Part 1: Quantum Meets Language

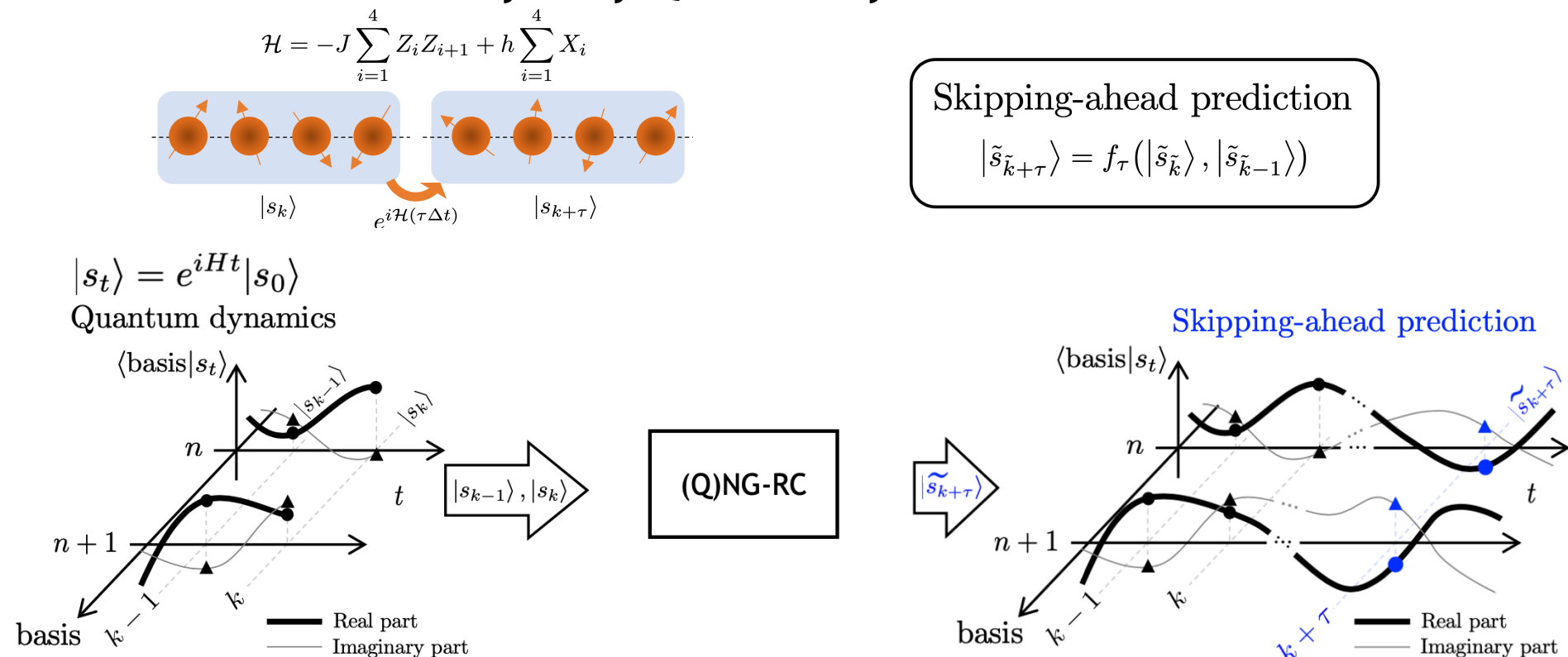


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NJP 2022

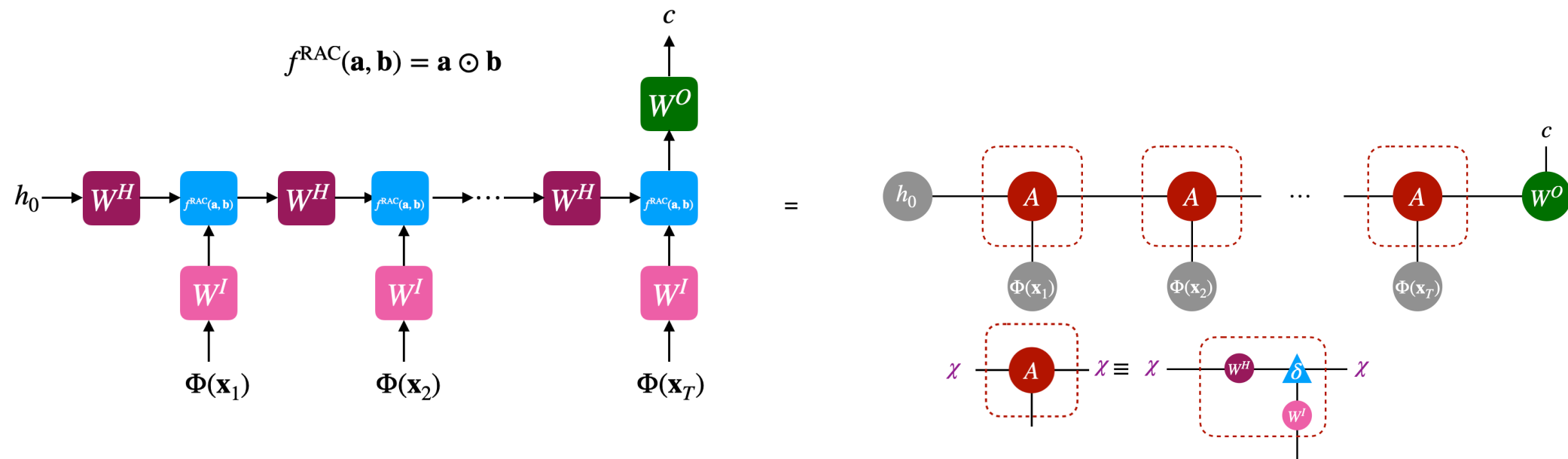
## Part 2: Next Generation Reservoir Computing (NG-RC) for Many-body Quantum Dynamics Prediction





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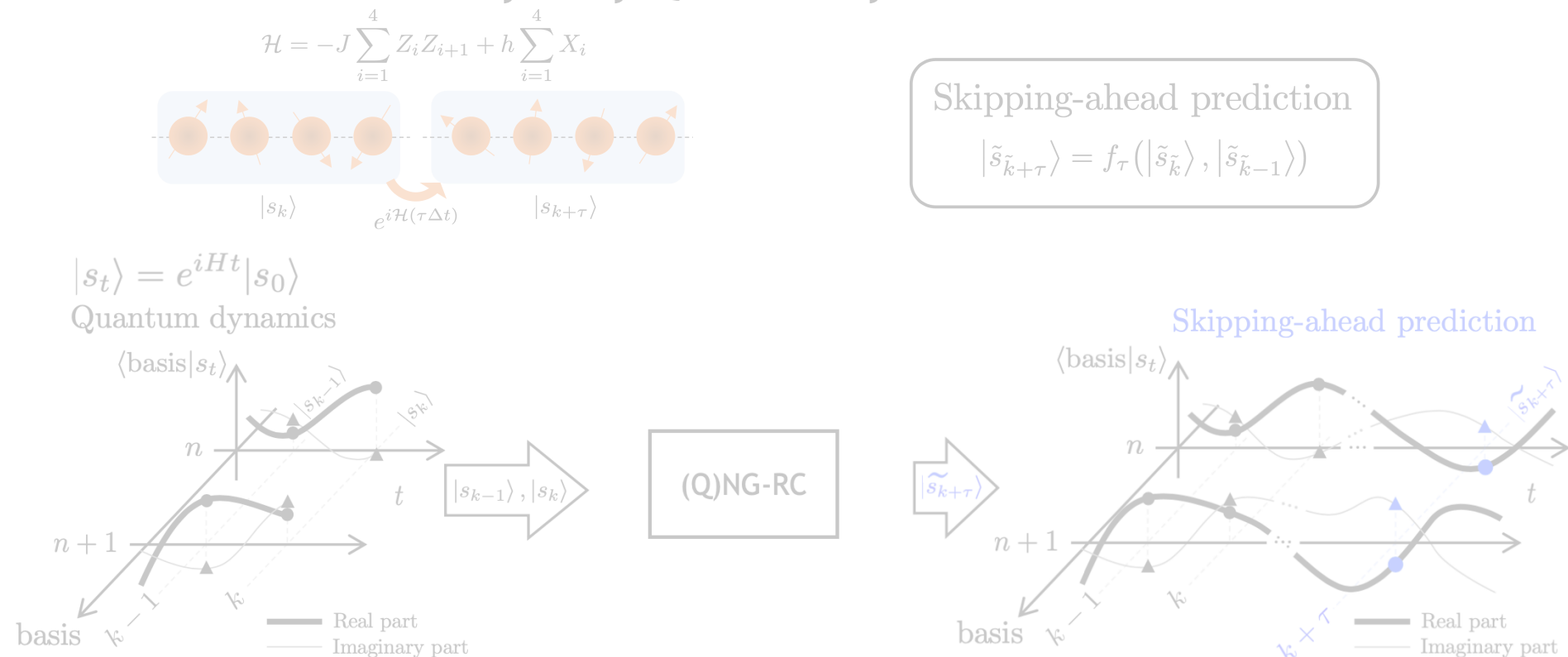


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NJP 2022

## Part 2: Next Generation Reservoir Computing (NG-RC) for Many-body Quantum Dynamics Prediction





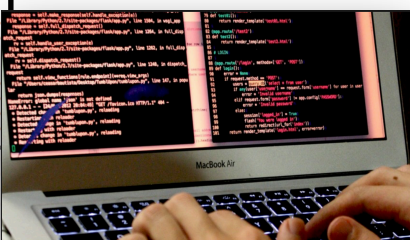
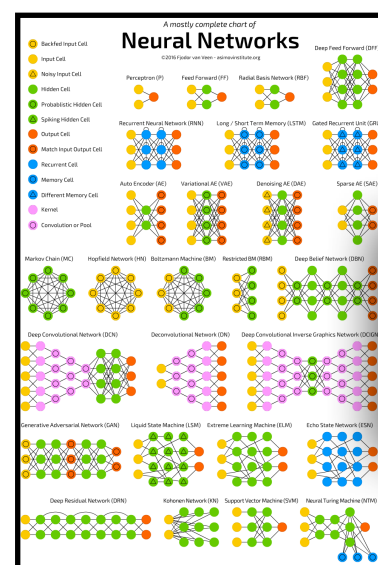
# 'AI IS THE NEW ELECTRICITY'



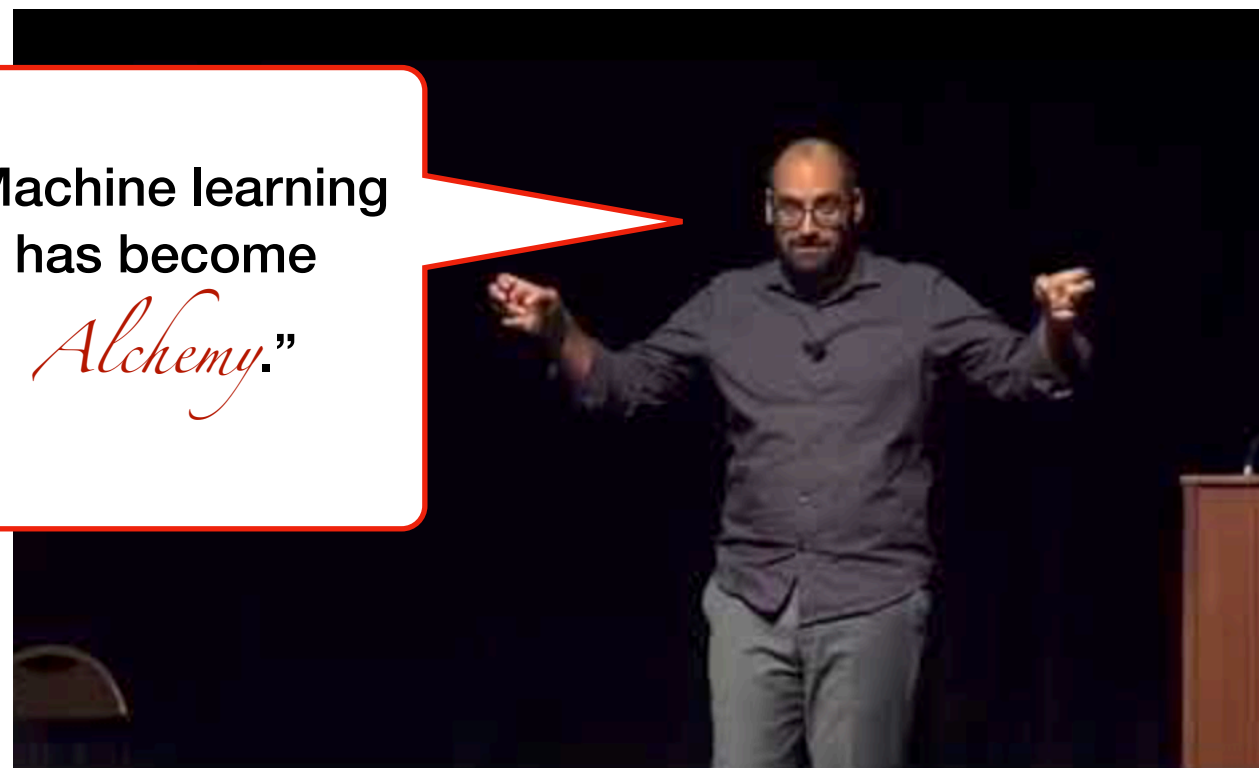
"Just as electricity transformed almost everything 100 years ago, today I actually have a hard time thinking of an industry that I don't think AI will transform in the next several years."

**Andrew Ng**

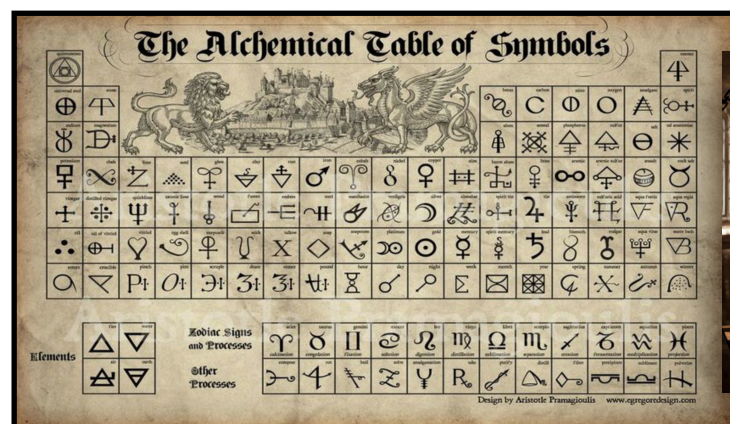
Former chief scientist at Baidu, Co-founder at Coursera



"Machine learning  
has become  
*Alchemy*."



Ali Rahimi (Google) at NIPS 2017





# Statistical Sequence Modeling

Next word prediction



$$P(x_n | x_{n-1}, \dots, x_1)$$



# Statistical Sequence Modeling

Next word prediction



$$P(x_n | x_{n-1}, \dots, x_1)$$

Sentiment Analysis

“This is a great movie!!”  $\sigma = +1$   
“This is a boring movie...”  $\sigma = -1$

$$P(\sigma | x_n, \dots, x_1)$$



# Statistical Sequence Modeling

In Deep Learning era, typically parametrised by Recurrent Neural Networks (RNNs).

Next word prediction



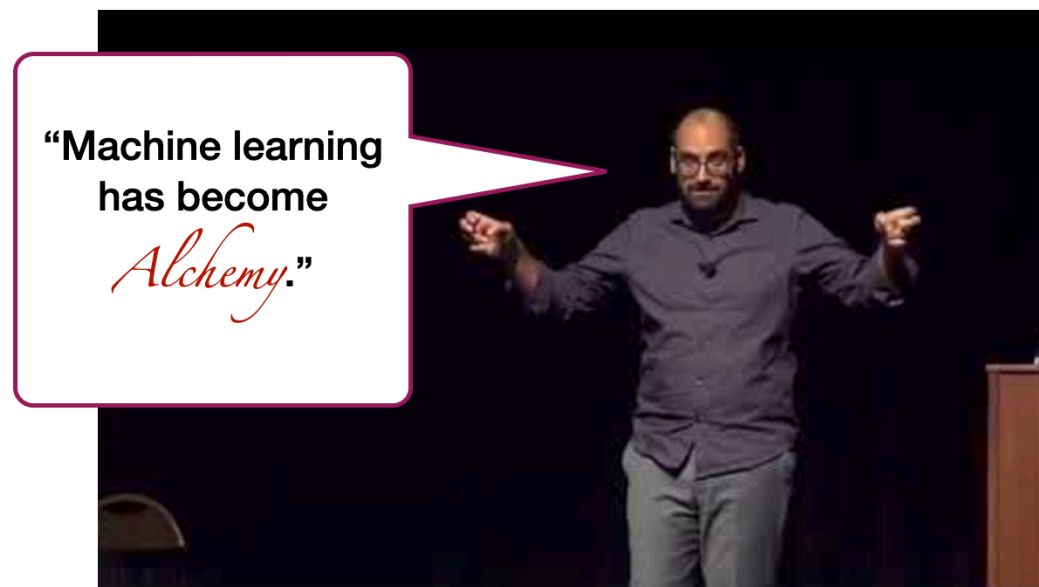
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$$P(\sigma | x_n, \dots, x_1)$$

Lack explainability!



Ali Rahimi (Google) at NIPS 2017

# Sequence Modeling and Many-body Quantum Physics

## Statistical Sequence Modeling

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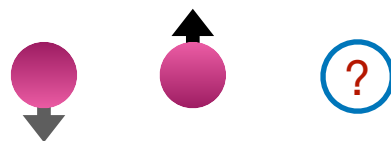
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$$P(\sigma | x_n, \dots, x_1)$$

Lack explainability!

## Many-body Quantum Physics

1-D Spin Chain



MPS, DMRG



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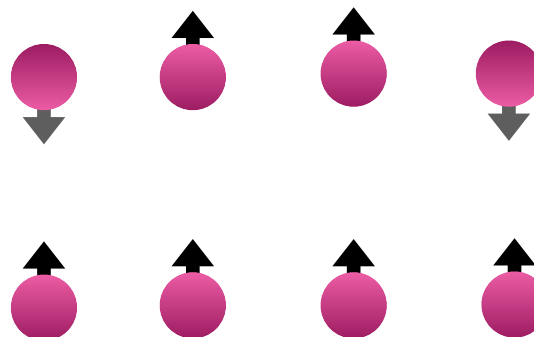
$$P(x_n | x_{n-1}, \dots, x_1)$$

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## Many-body Quantum Physics

1-D Spin Chain



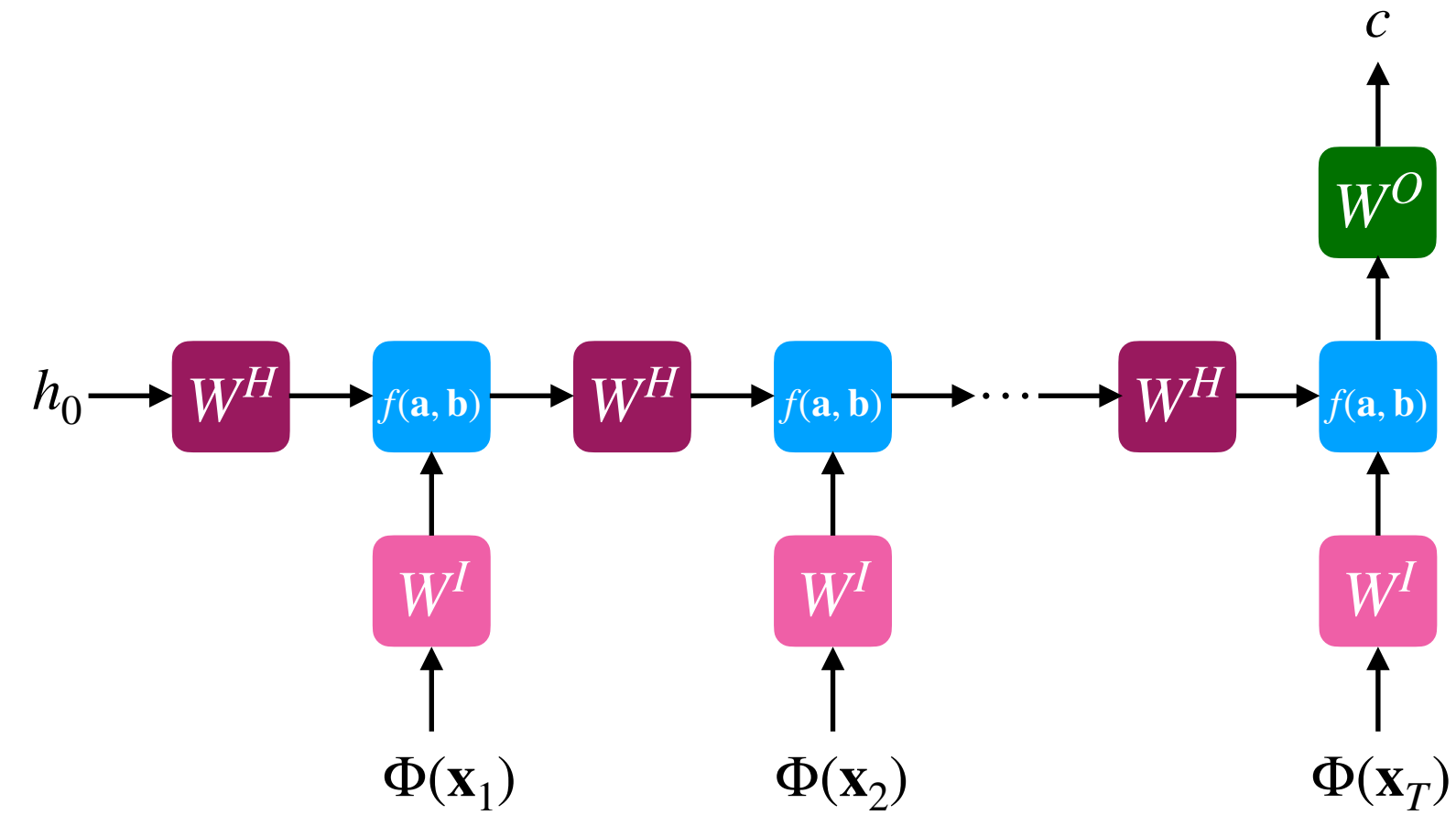
Classification of Phase of Matters

MPS, DMRG

“Ferromagnets”

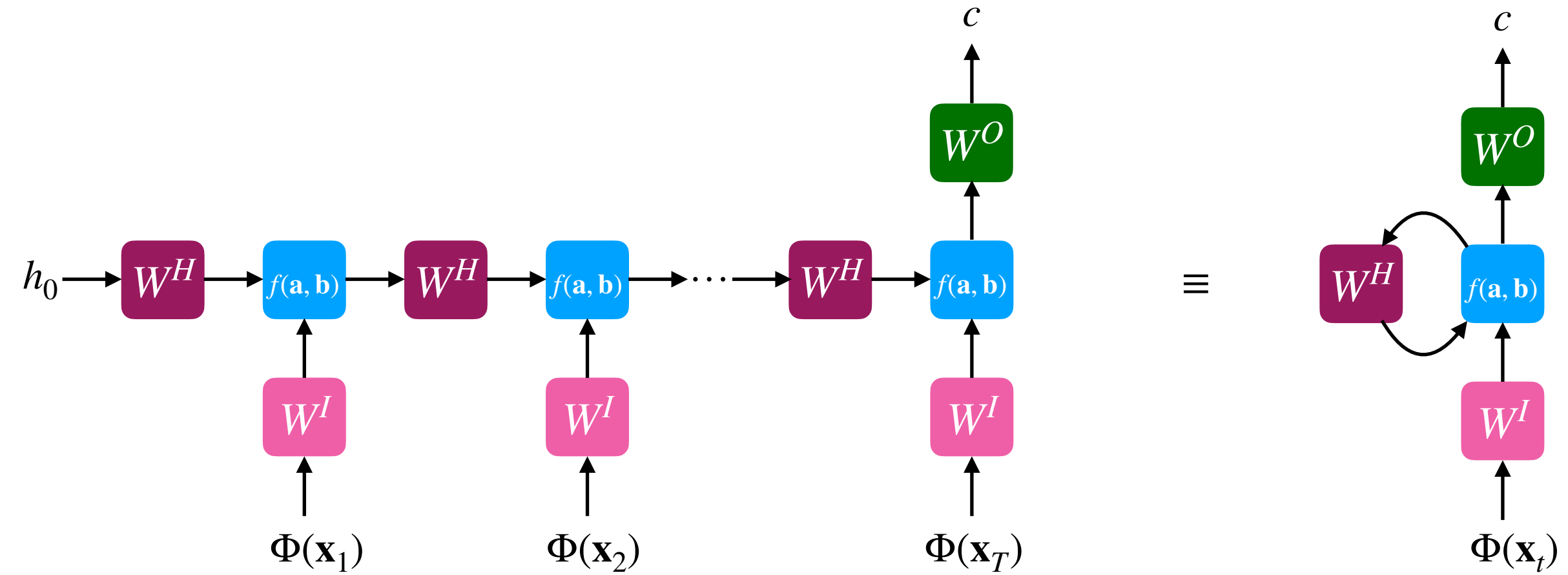
Relatively well developed

# Shallow Recurrent Neural Networks (RNNs) Architecture for Sentiment Analysis

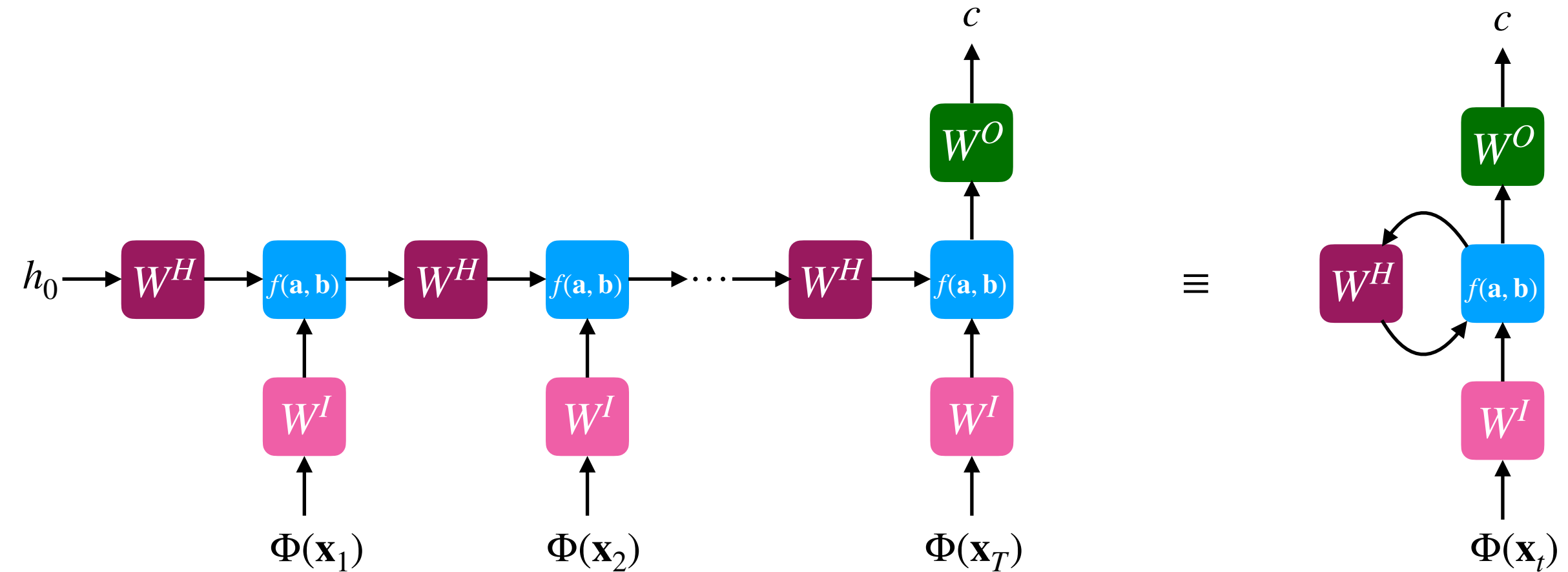




# Shallow Recurrent Neural Networks (RNNs) Architecture for Sentiment Analysis



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$$\mathbf{h}^t = f\left(W^H \mathbf{h}^{t-1}, W^I \Phi(\mathbf{x}_t)\right)$$

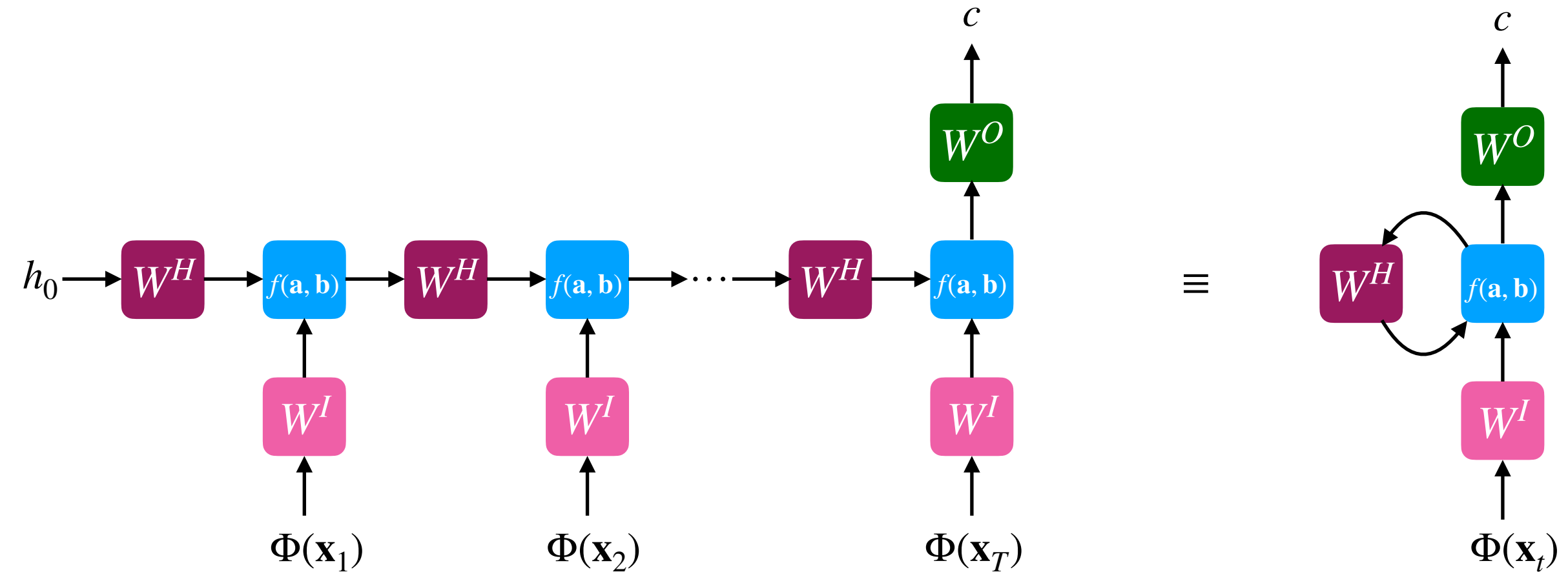
$$c = \sigma(W^O \mathbf{h}^T)$$

$$\approx P(c | x_T, \dots, x_1)$$

$f(\mathbf{a}, \mathbf{b})$  is typically a highly non-linear function, which makes the analysis of iterated non-linear map in RNNs difficult.



# Shallow Recurrent Neural Networks (RNNs) Architecture for Sentiment Analysis



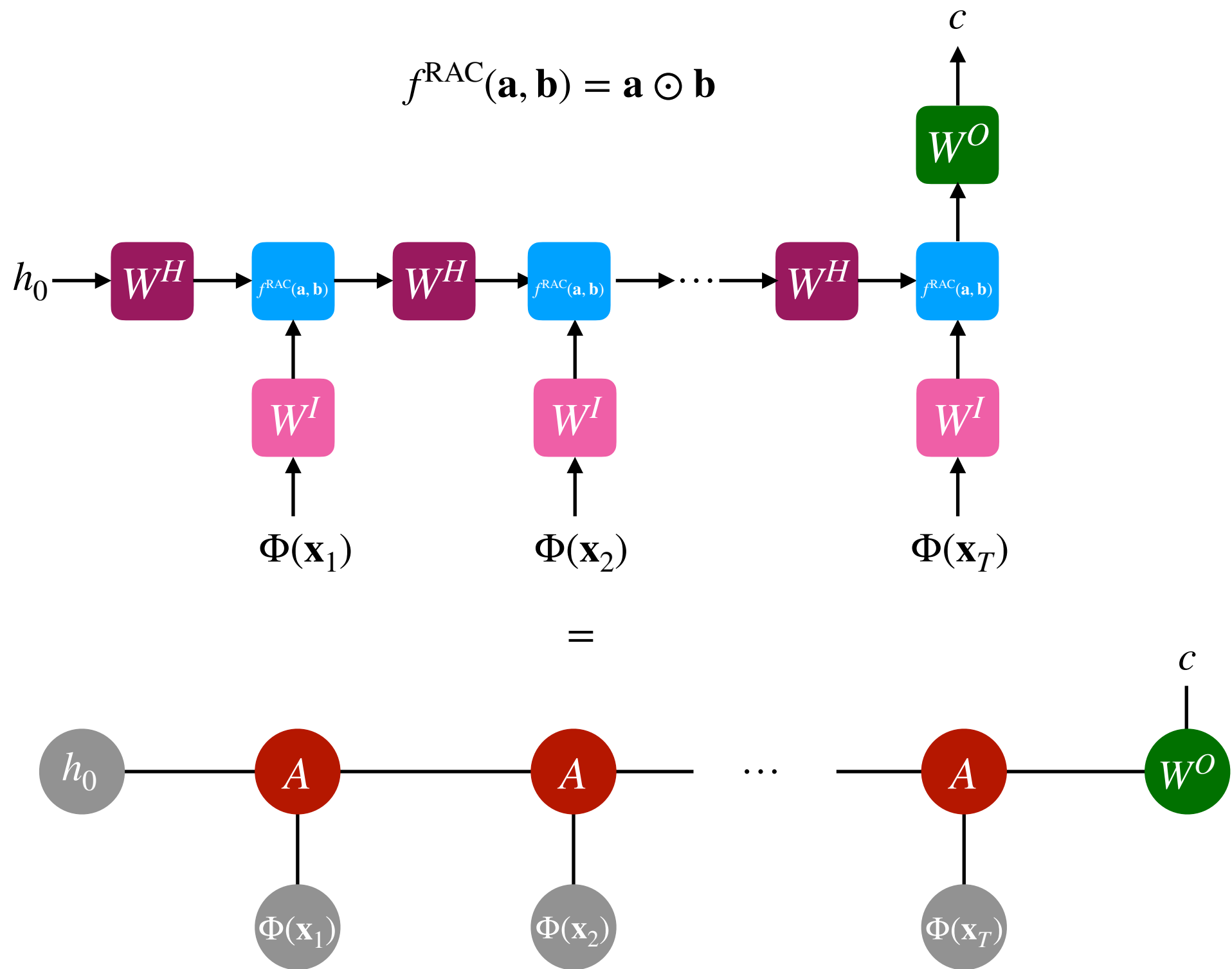
$$\mathbf{h}^t = f\left(W^H \mathbf{h}^{t-1}, W^I \Phi(\mathbf{x}_t)\right) \approx P(c | x_T, \dots, x_1)$$

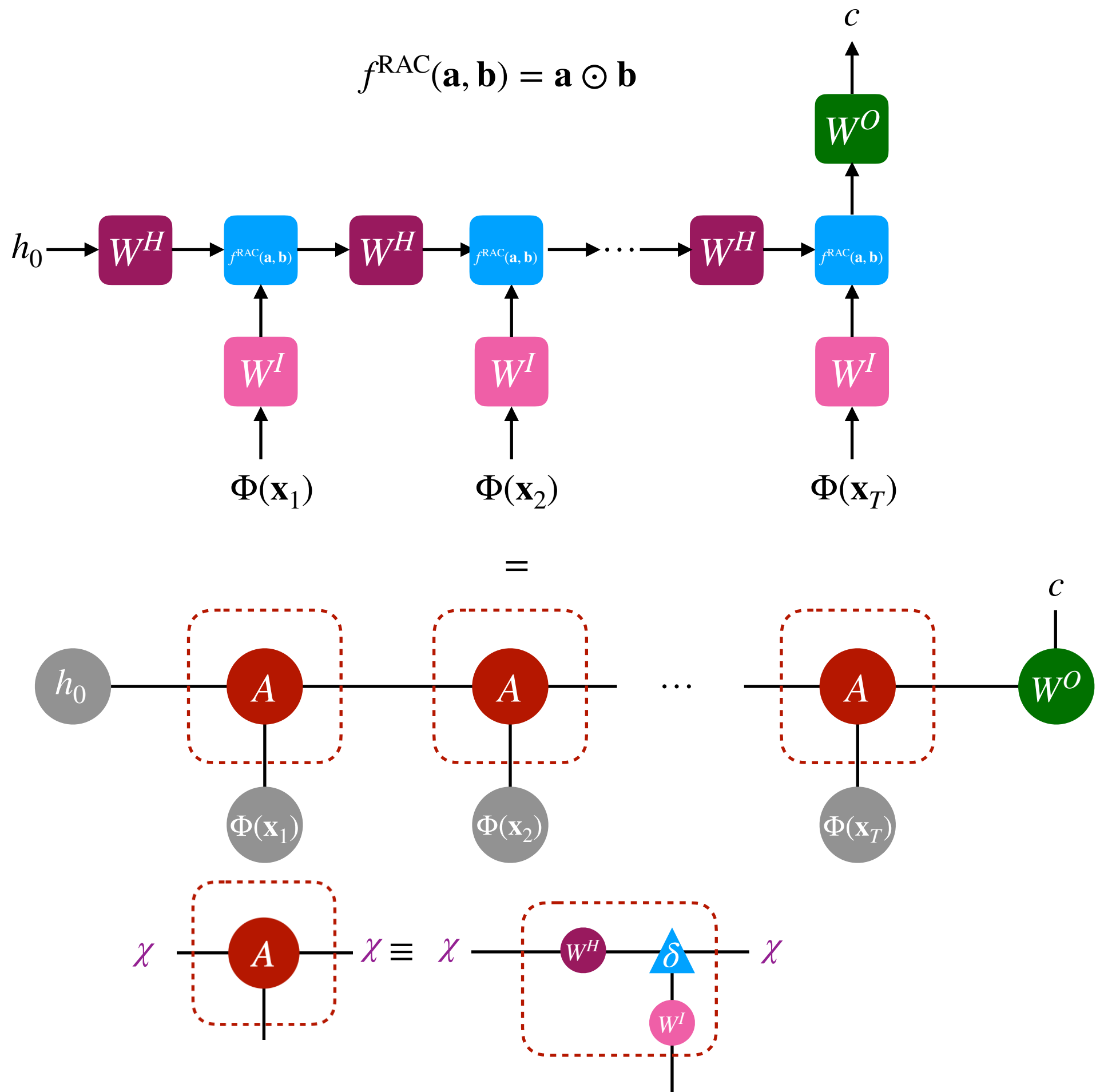
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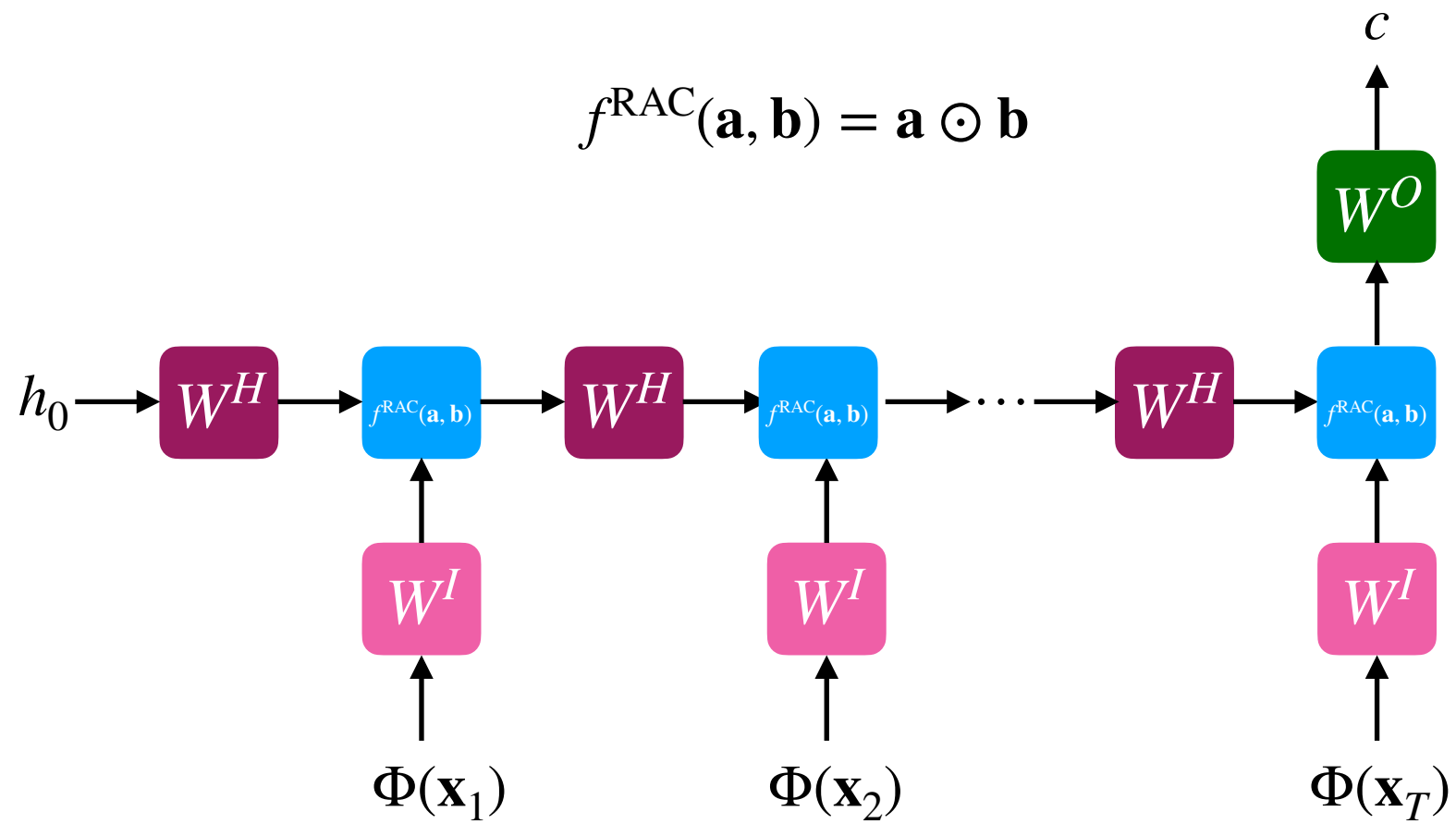
However, for a specific type of **activation function** called Recurrent Arithmetic Circuits (RACs), there's a mapping to a translational invariant **Matrix Product State (MPS)**

$$f(\mathbf{a}, \mathbf{b}) \equiv f^{\text{RAC}}(\mathbf{a}, \mathbf{b}) = \mathbf{a} \odot \mathbf{b}$$



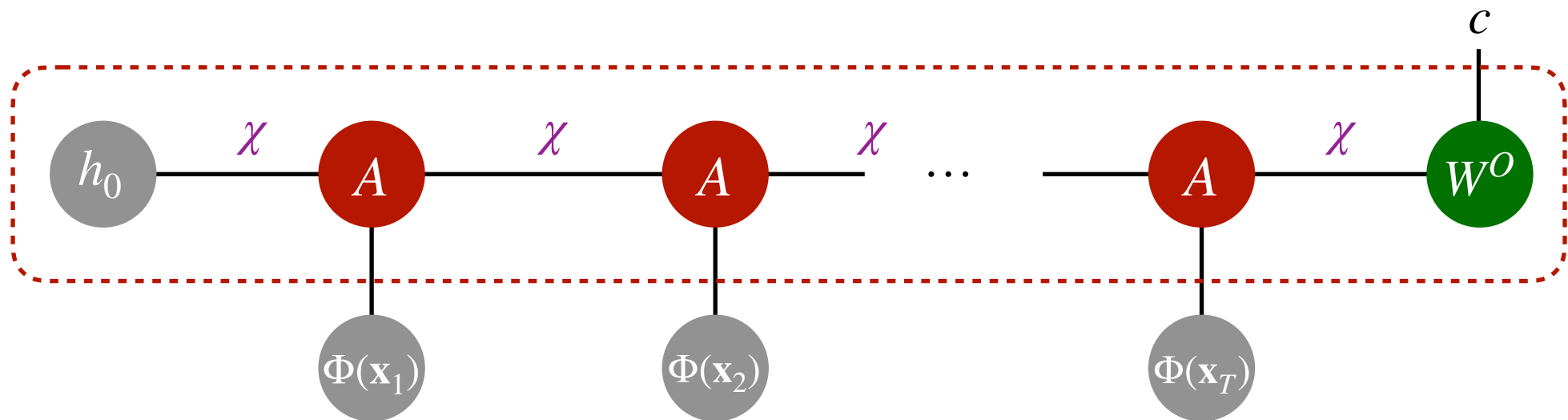




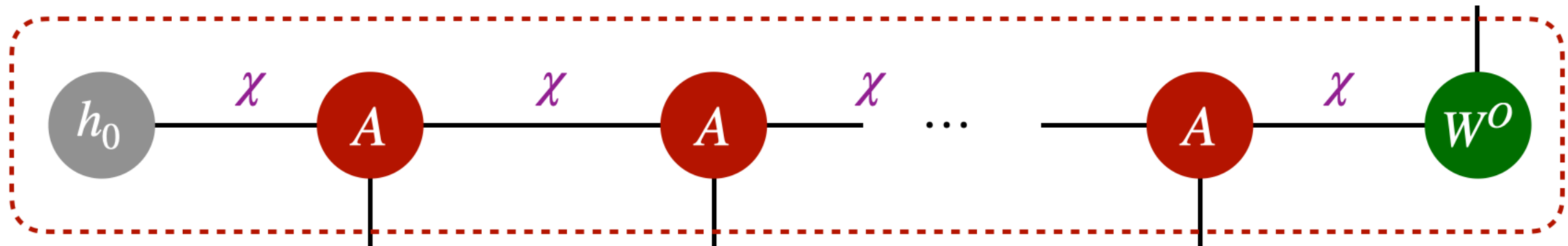


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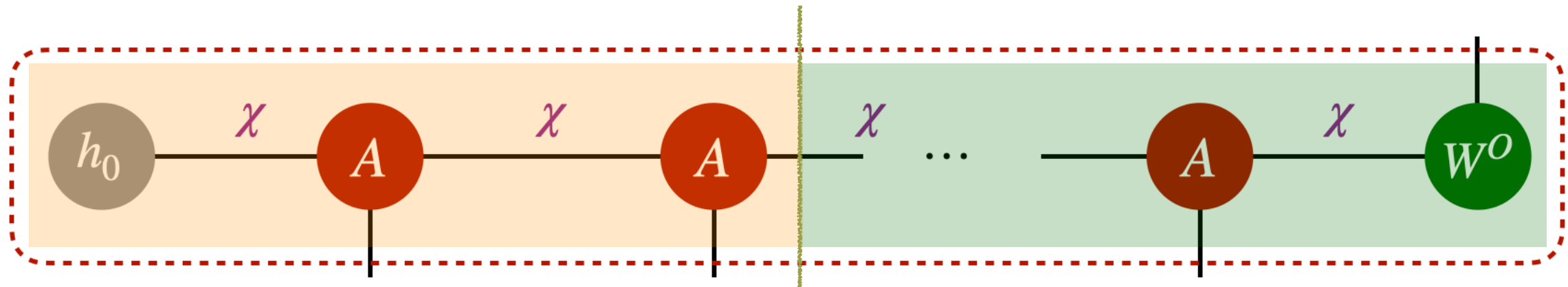
MPS



# Entanglement Entropy as a Proxy of Information Propagation in RACs



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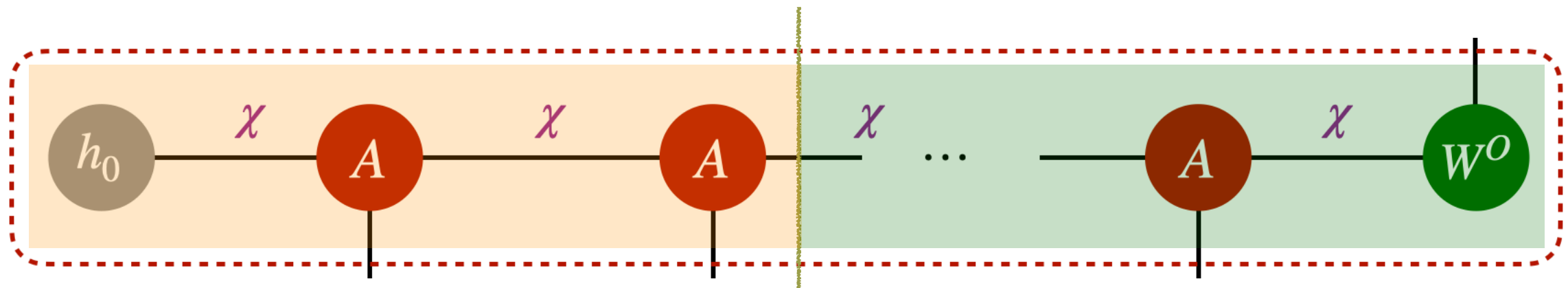
$$|\psi_{MPS}\rangle = \sum_{\alpha=1}^r \lambda_{\alpha} \left| \phi_{\alpha}^L \right\rangle \otimes \left| \phi_{\alpha}^R \right\rangle$$

Entanglement Entropy

$$S = - \sum_{\alpha=1}^r \left| \lambda_{\alpha} \right|^2 \ln \left| \lambda_{\alpha} \right|^2$$



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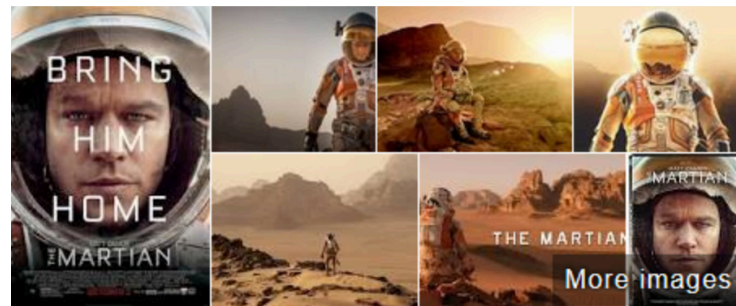
Entanglement Entropy

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If  $r \ll \chi$ , then  $|\psi_{MPS}\rangle$  does not possess long-range correlation.

Thus  $S$  can be a good proxy to test whether the learned RACs has long-range information propagation.

# Sentiment Analysis for IMDB dataset



## The Martian

2015 · Science fiction film/Drama film · 2h 31m



[Play trailer on YouTube](#)



Like



Dislike

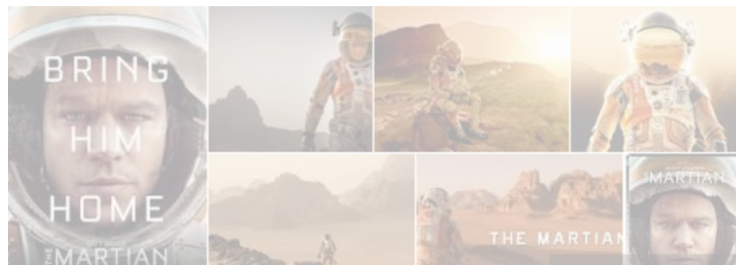
★ 10/10

### pleasantly surprised

[whammo-79346](#) 17 January 2016

Seeing that the movie was over 2 hrs long, and knowing that the person was going to be stuck on the planet by their self for the majority, I didn't have high hopes for it. Usually these types of movies are boring. Not a lot of writers can pull this off. This movie was really good tho. A group of us watched it and really enjoyed. There were some things they failed to explain, that we collectively came up with our own answer for. Other than that, it was great. I never felt bored or left waiting for more. Overall, I feel it was very

# Sentiment Analysis for IMDB dataset: fixed word embedding



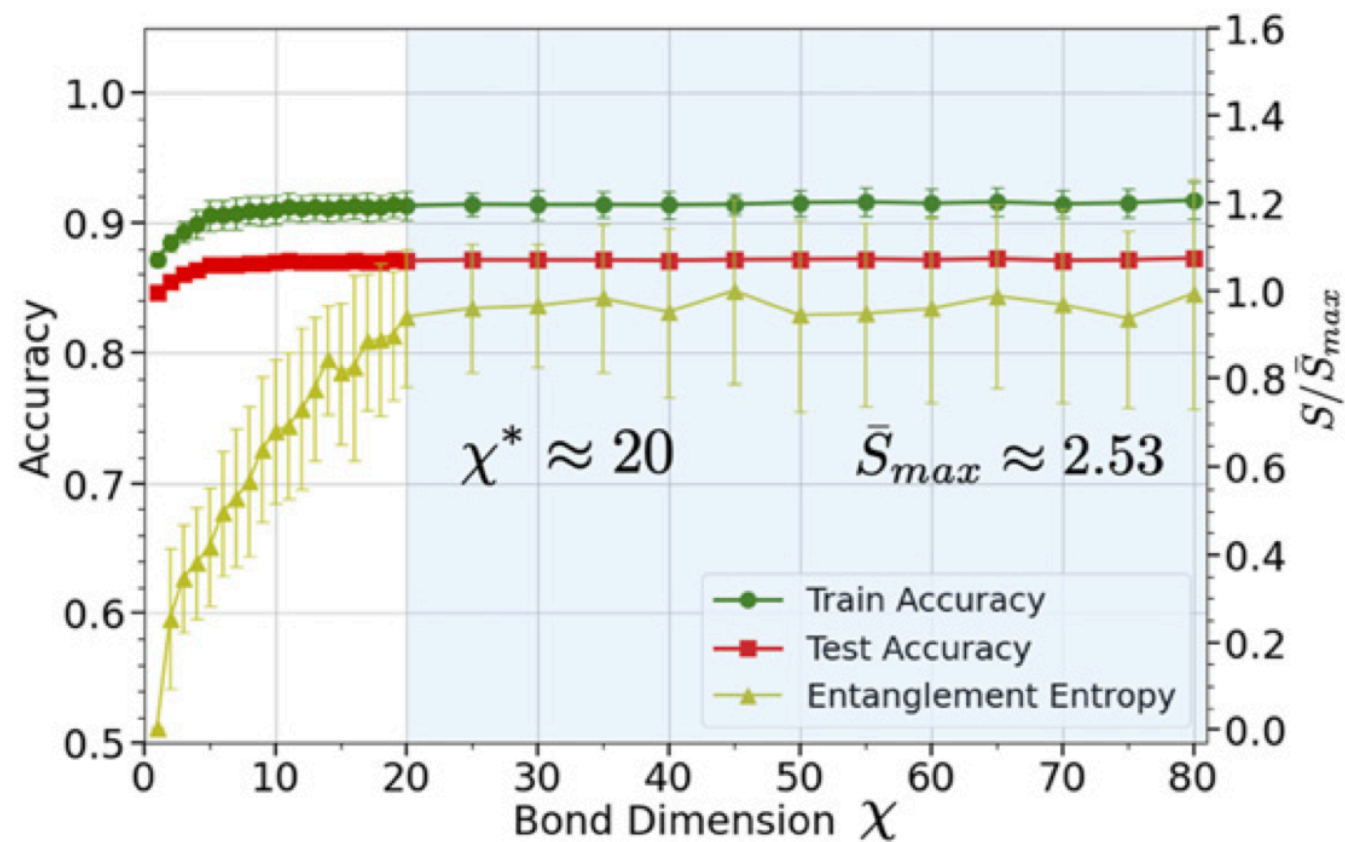
★ 10/10

**pleasantly surprised**

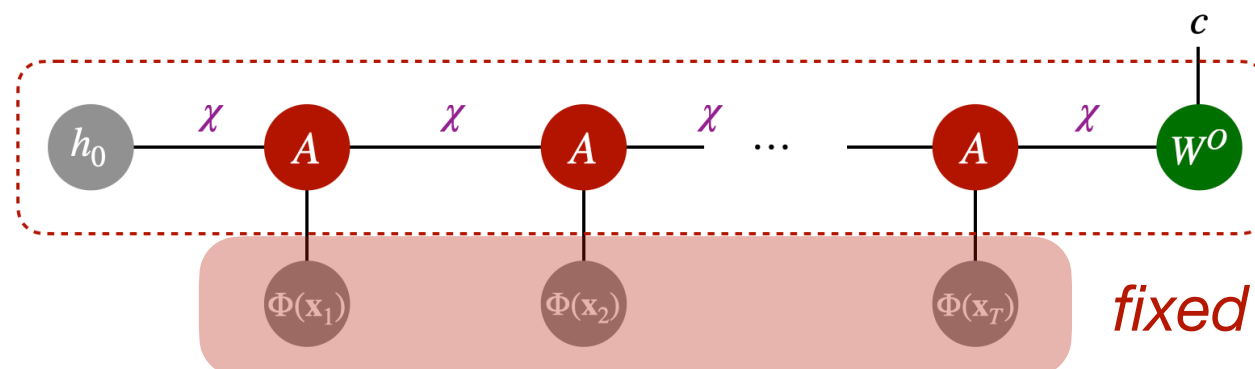
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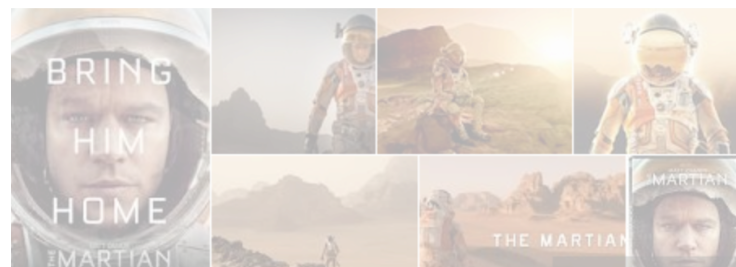
Fix the pre-trained  $\Phi(w) \in \mathbb{R}^4$



MPS



# Sentiment Analysis for IMDB dataset: fixed word embedding



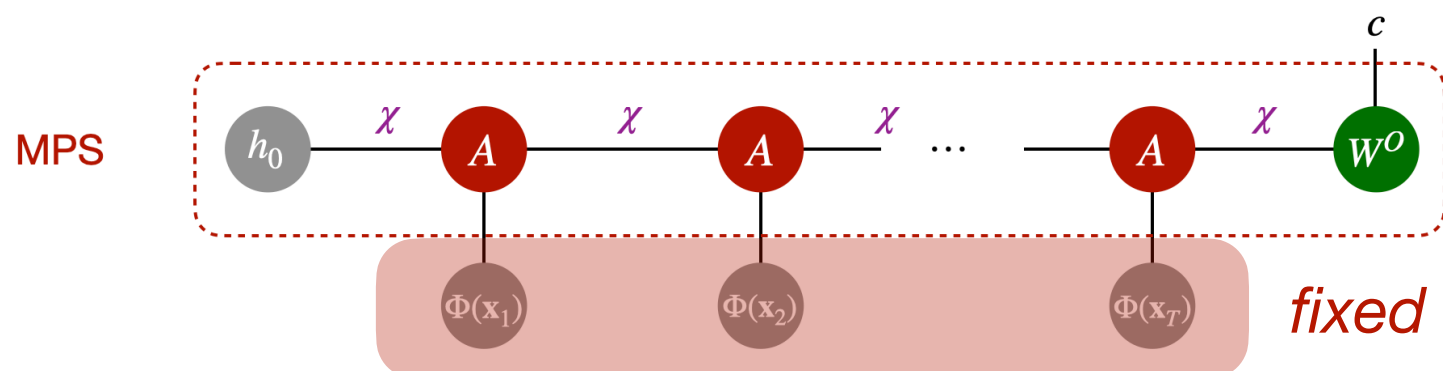
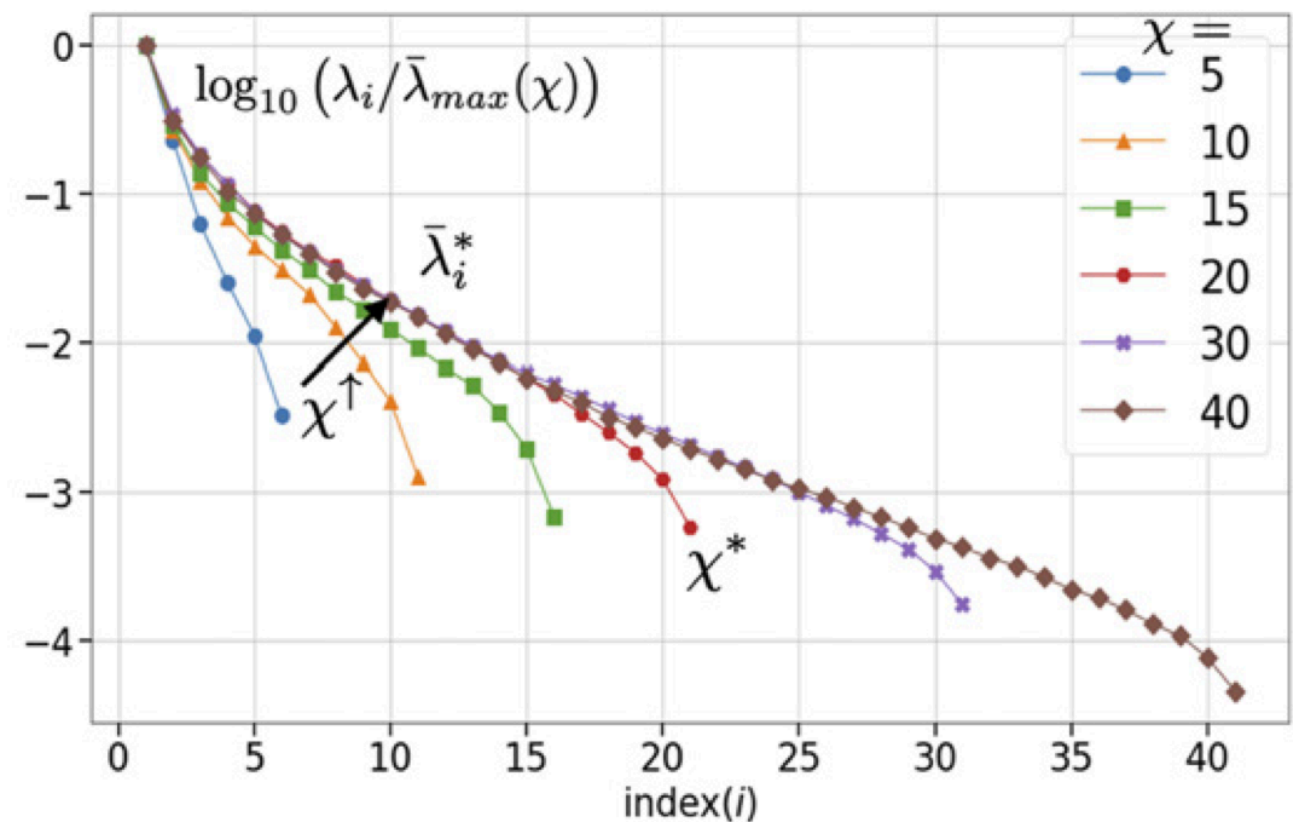
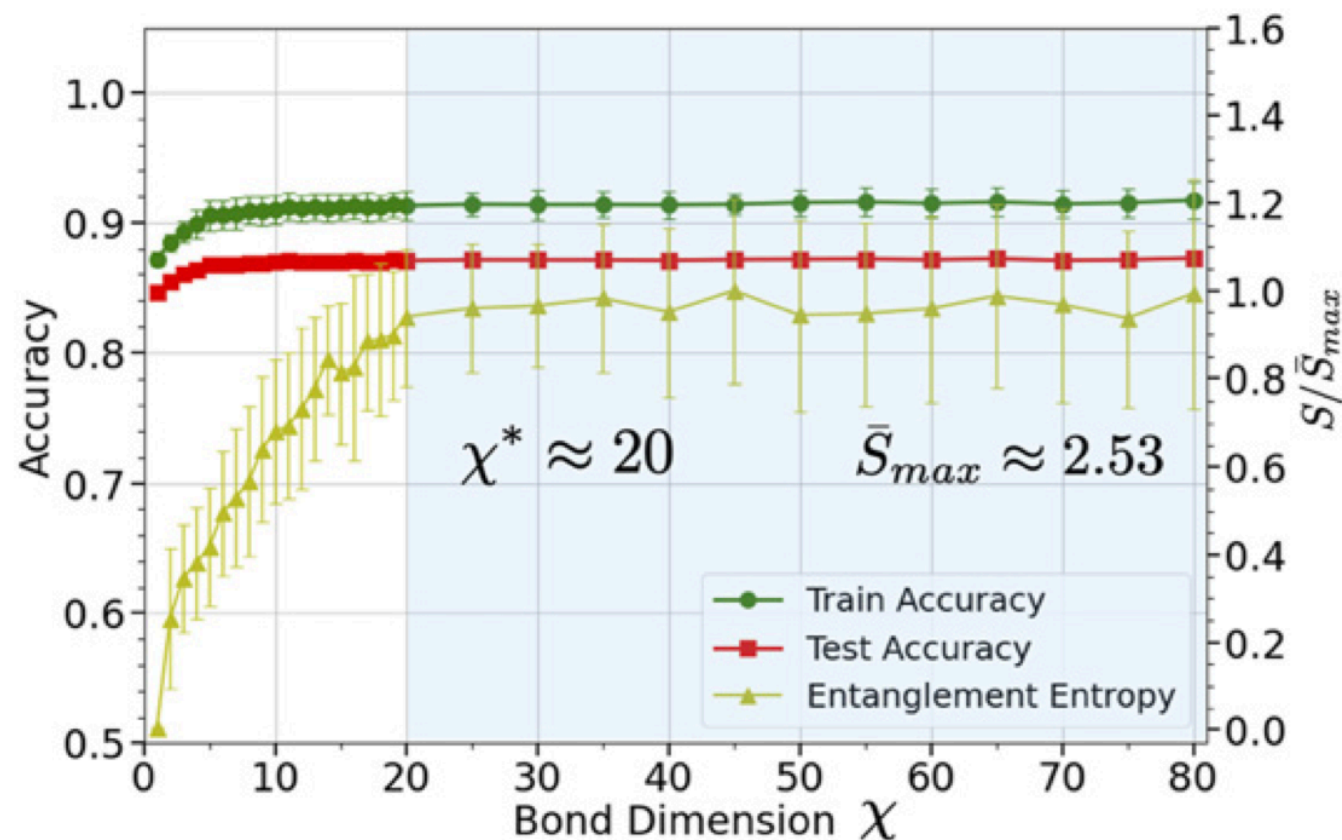
★ 10/10

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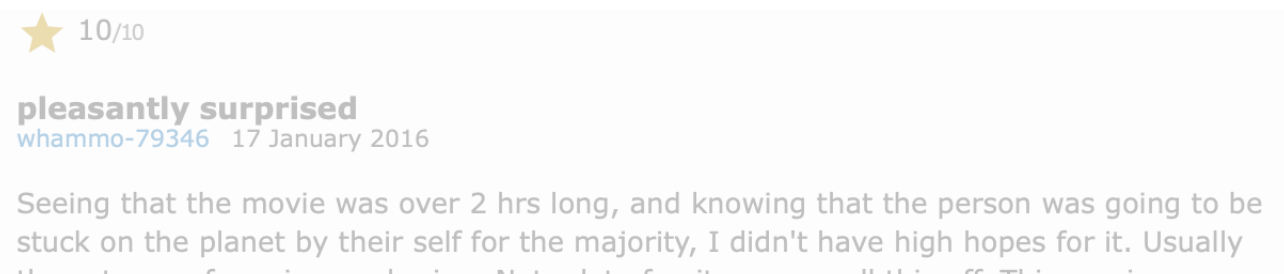
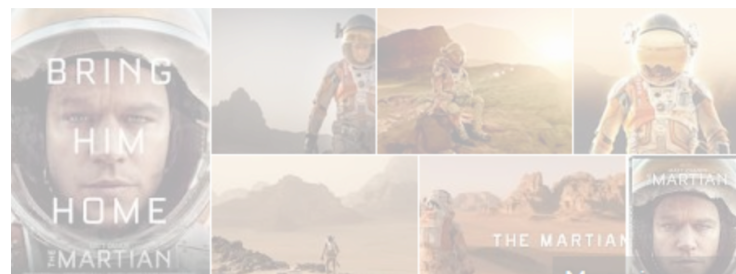
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*Collapse of entanglement spectrum determines model bias*

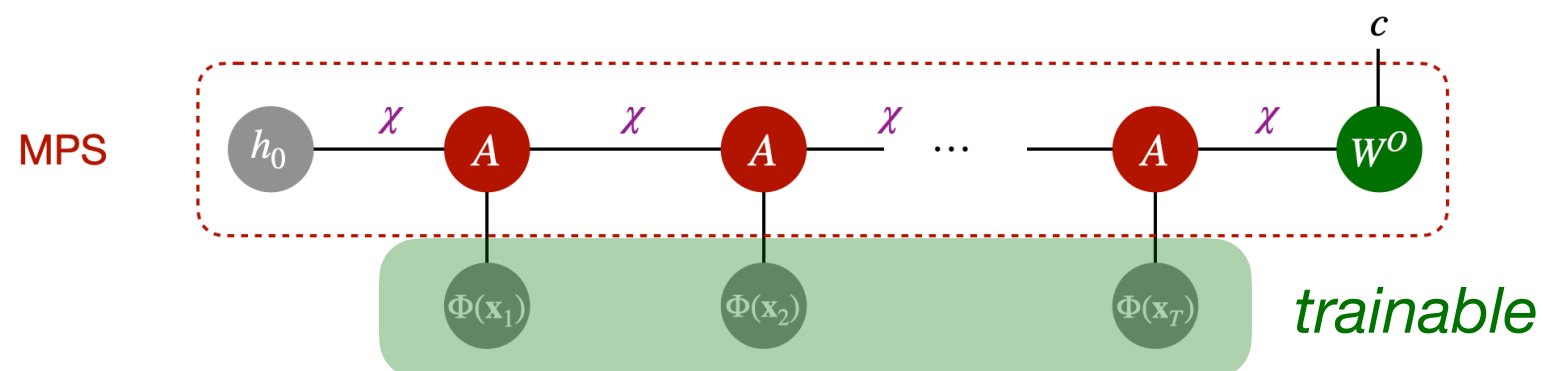
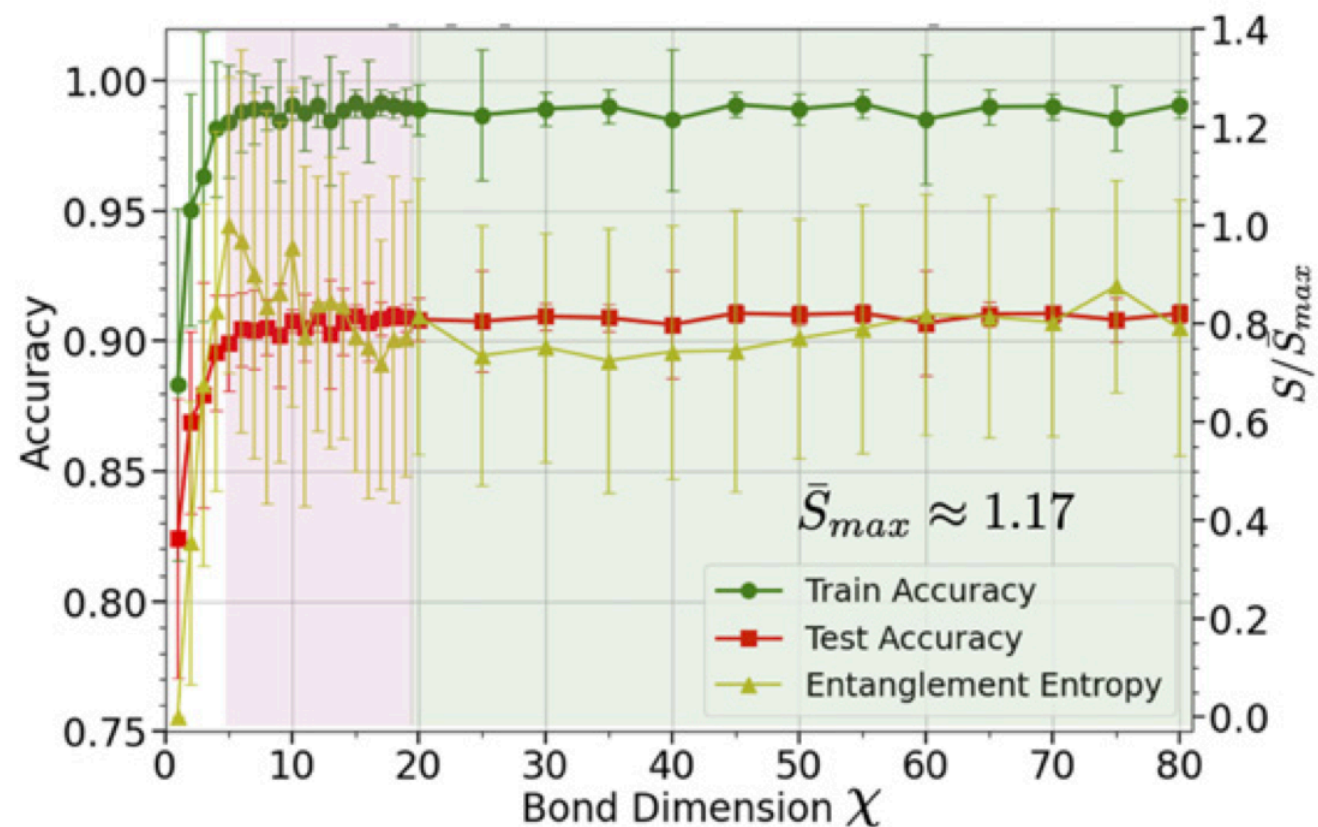




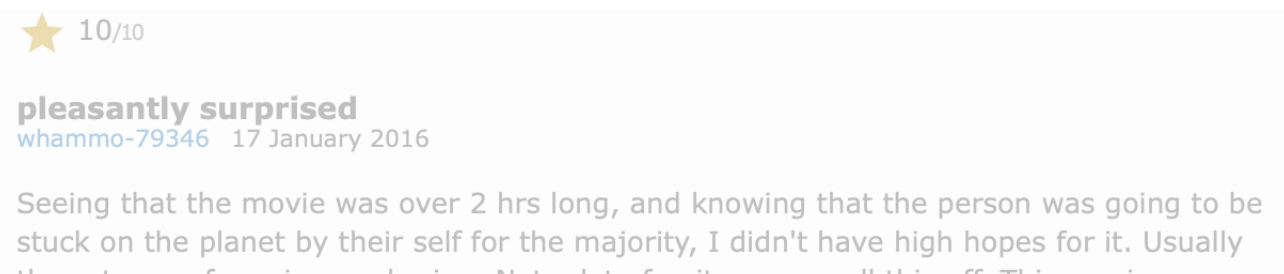
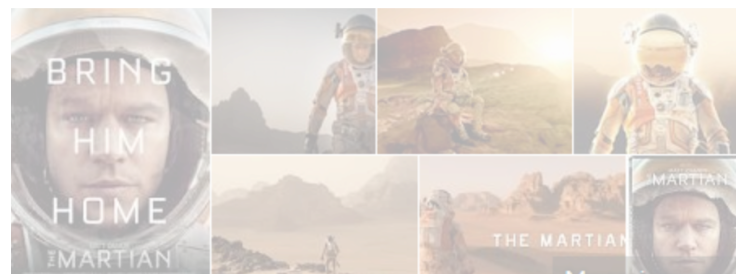
# Sentiment Analysis for IMDB dataset: trainable word embedding



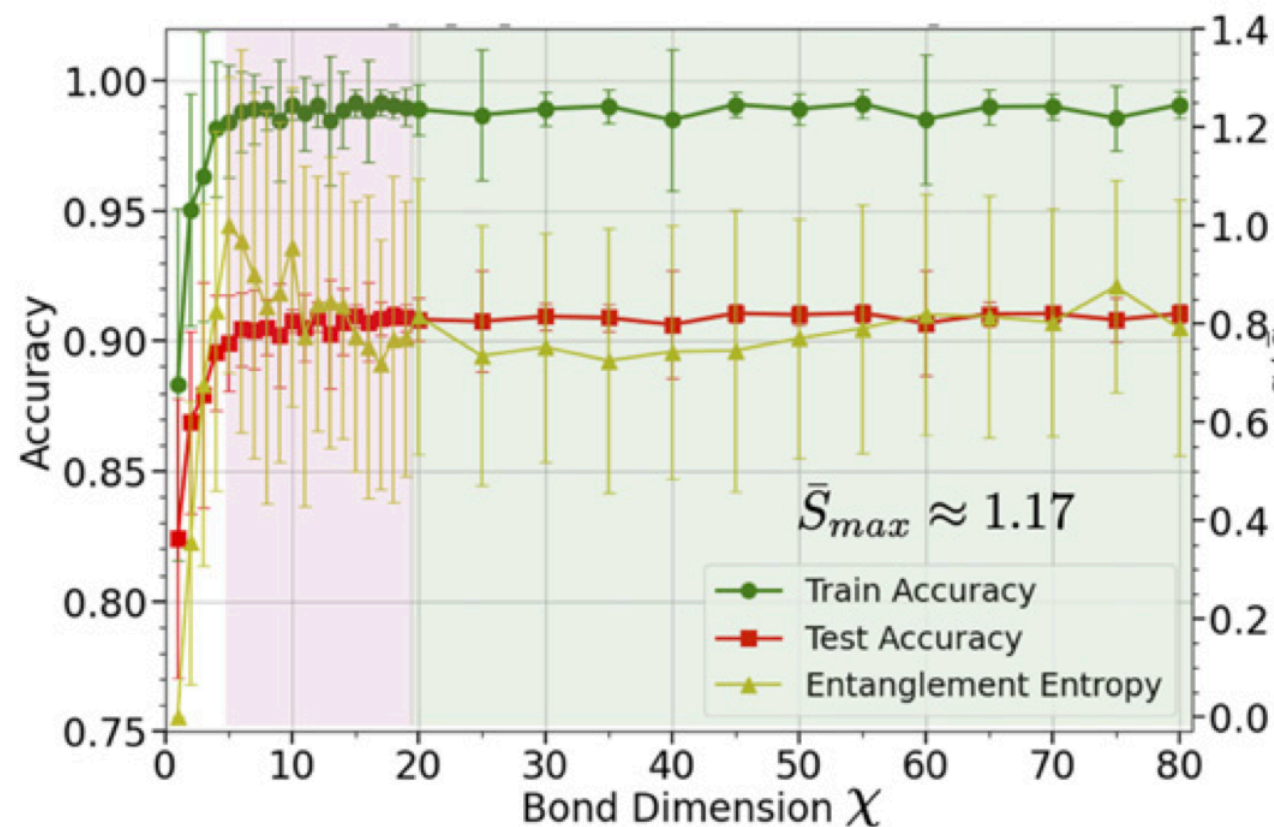
Train  $\Phi(w) \in \mathbb{R}^4$  with RACs



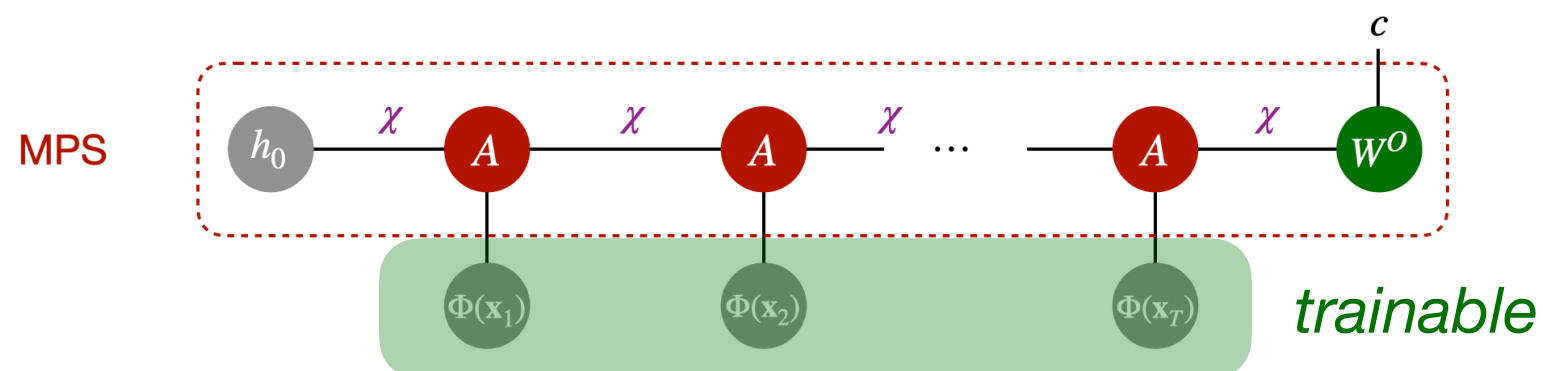
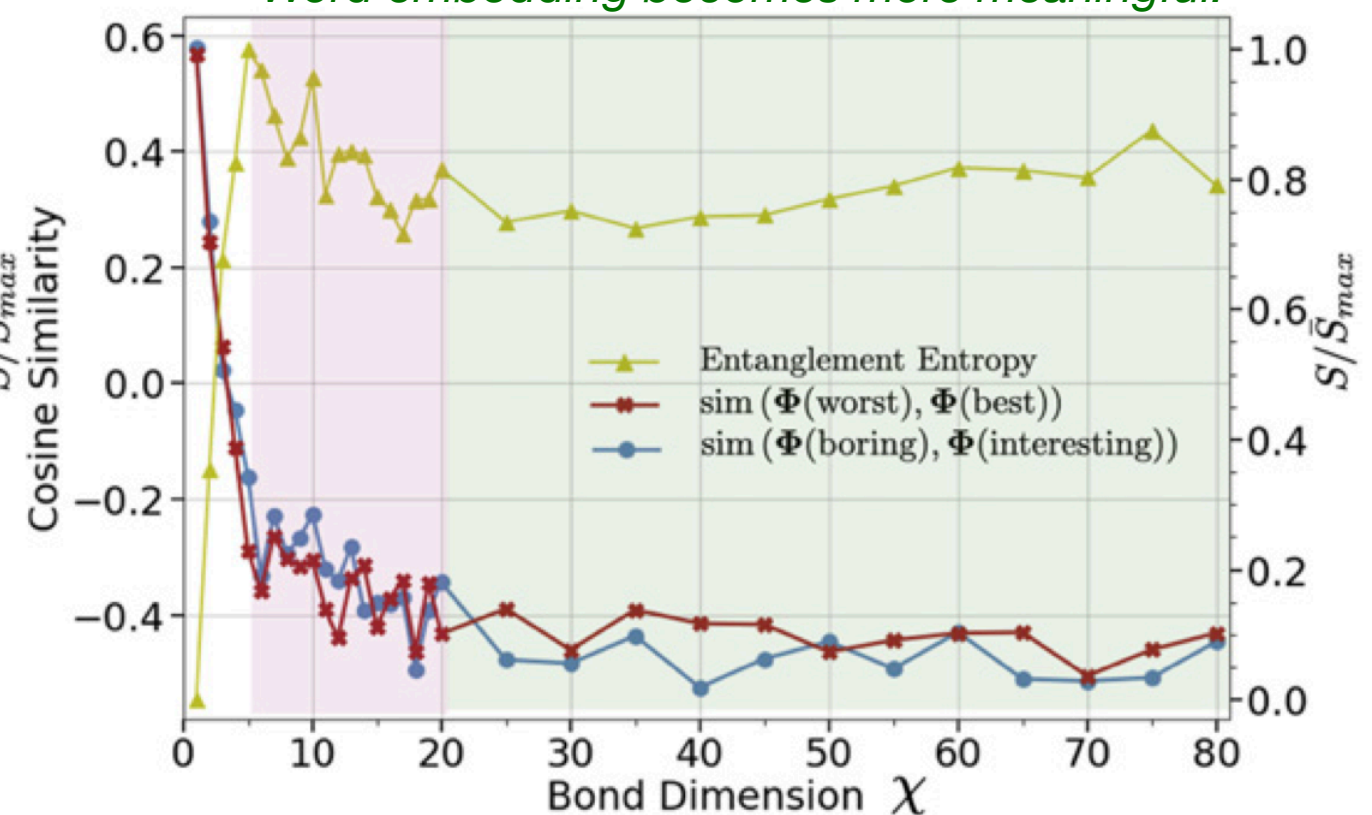
# Sentiment Analysis for IMDB dataset: trainable word embedding



Train  $\Phi(w) \in \mathbb{R}^4$  with RACs



Word embedding becomes more meaningful!



## Summary

Mapping RACs to MPS allows one to exploit entanglement entropy as a measure of long-range correlation in natural language modeling.

Machine learning model bias in sentiment analysis is closely related to the saturation of information propagation, arising from the collapse of MPS's entanglement spectrum.

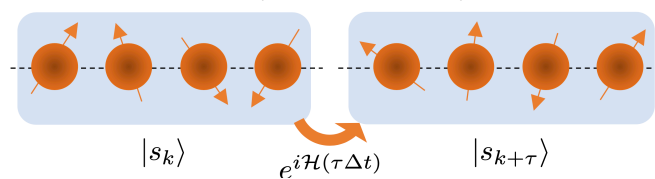
Word embedding plays a very crucial role in expressing data. Although long-range information propagation is limited by the area law of MPS, the expressiveness of model is boosted by more meaningful word embeddings.



# Outline

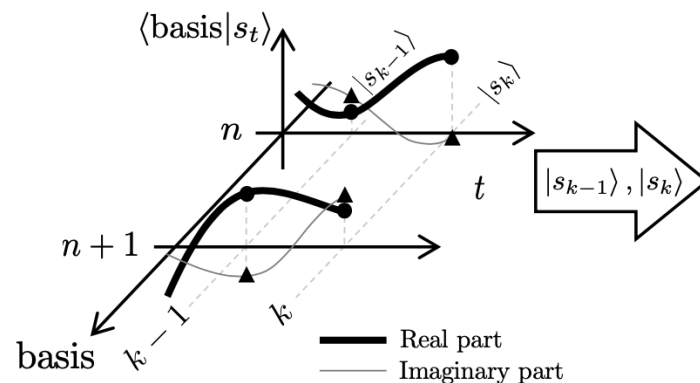
## Part 2: Next Generation Reservoir Computing (NG-RC) for Many-body Quantum Dynamics Prediction

$$\mathcal{H} = -J \sum_{i=1}^4 Z_i Z_{i+1} + h \sum_{i=1}^4 X_i$$



$$|s_t\rangle = e^{iHt}|s_0\rangle$$

## Quantum dynamics

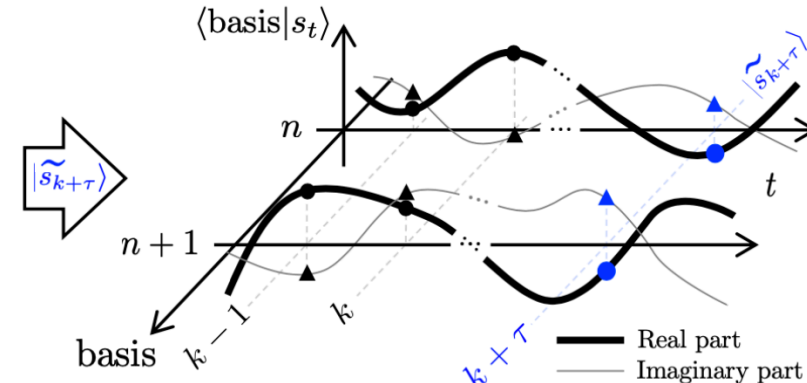


(Q)NG-RC

### Skipping-ahead prediction

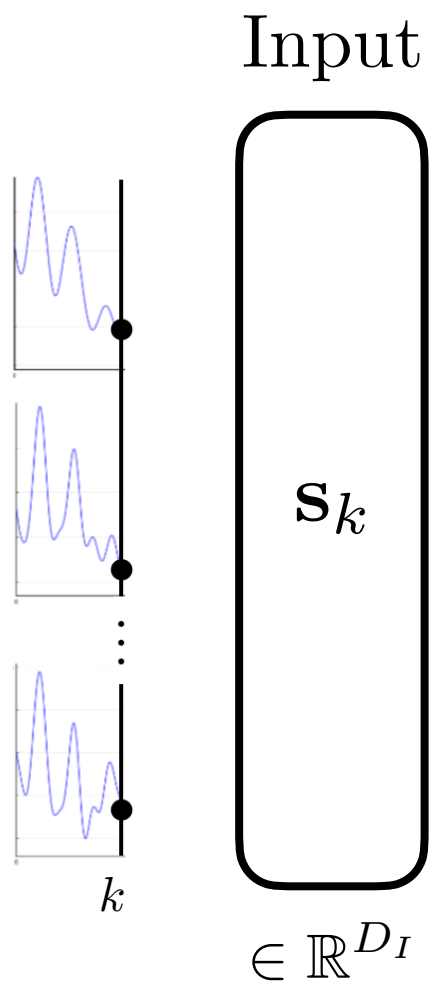
$$|\tilde{s}_{\tilde{k}+\tau}\rangle = f_{\tau}(|\tilde{s}_{\tilde{k}}\rangle, |\tilde{s}_{\tilde{k}-1}\rangle)$$

## Skipping-ahead prediction

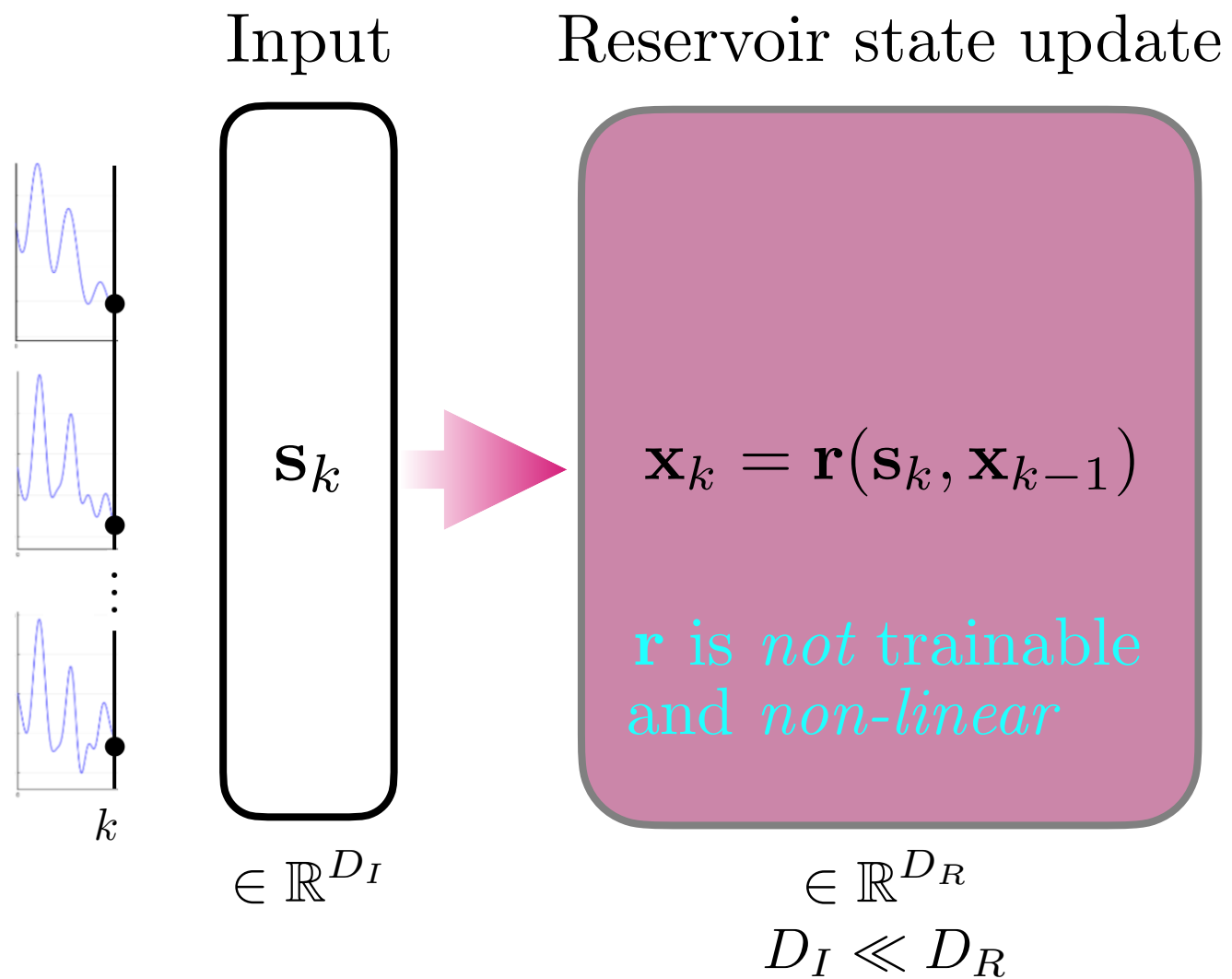




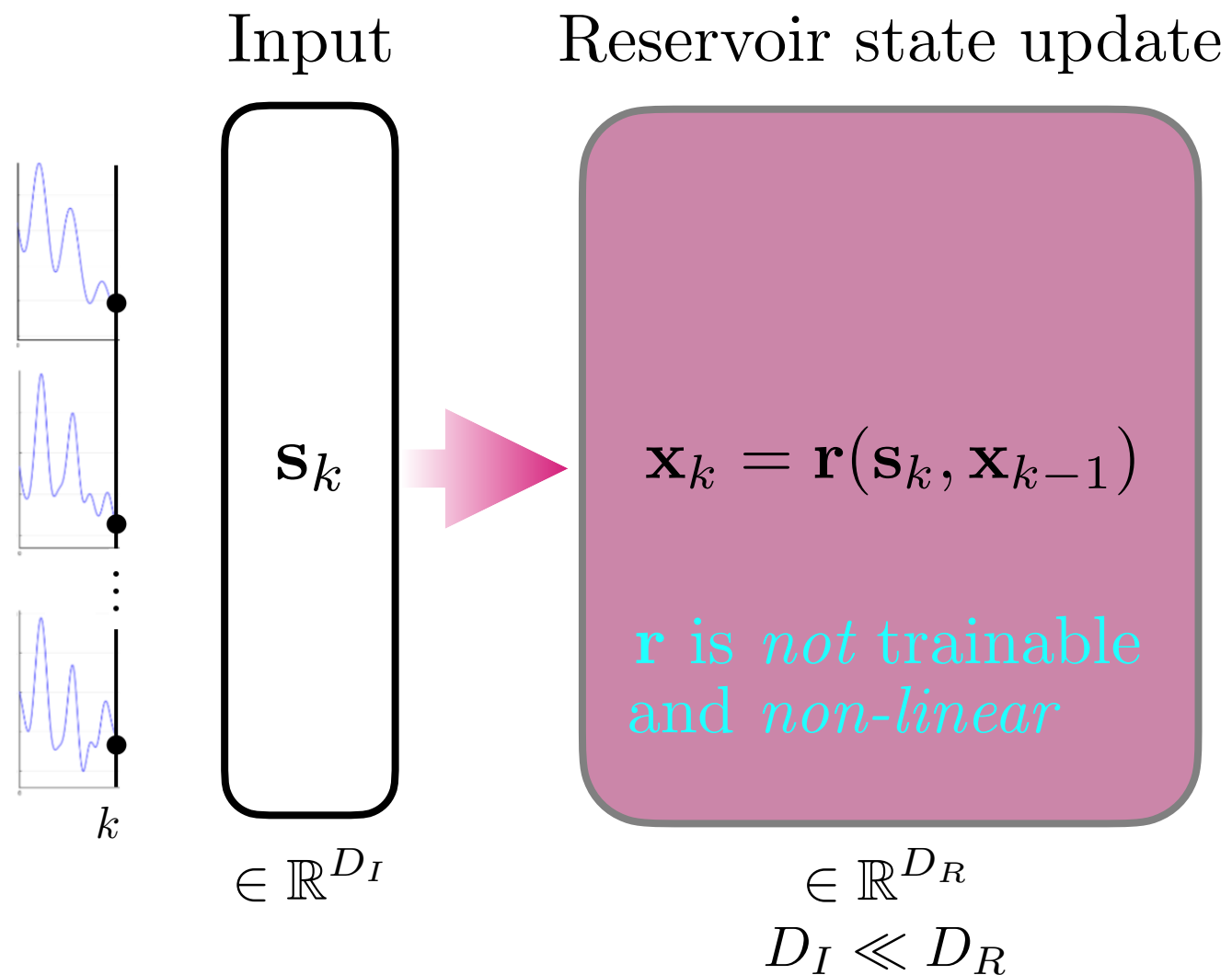
# Reservoir Computing (RC) in a nutshell



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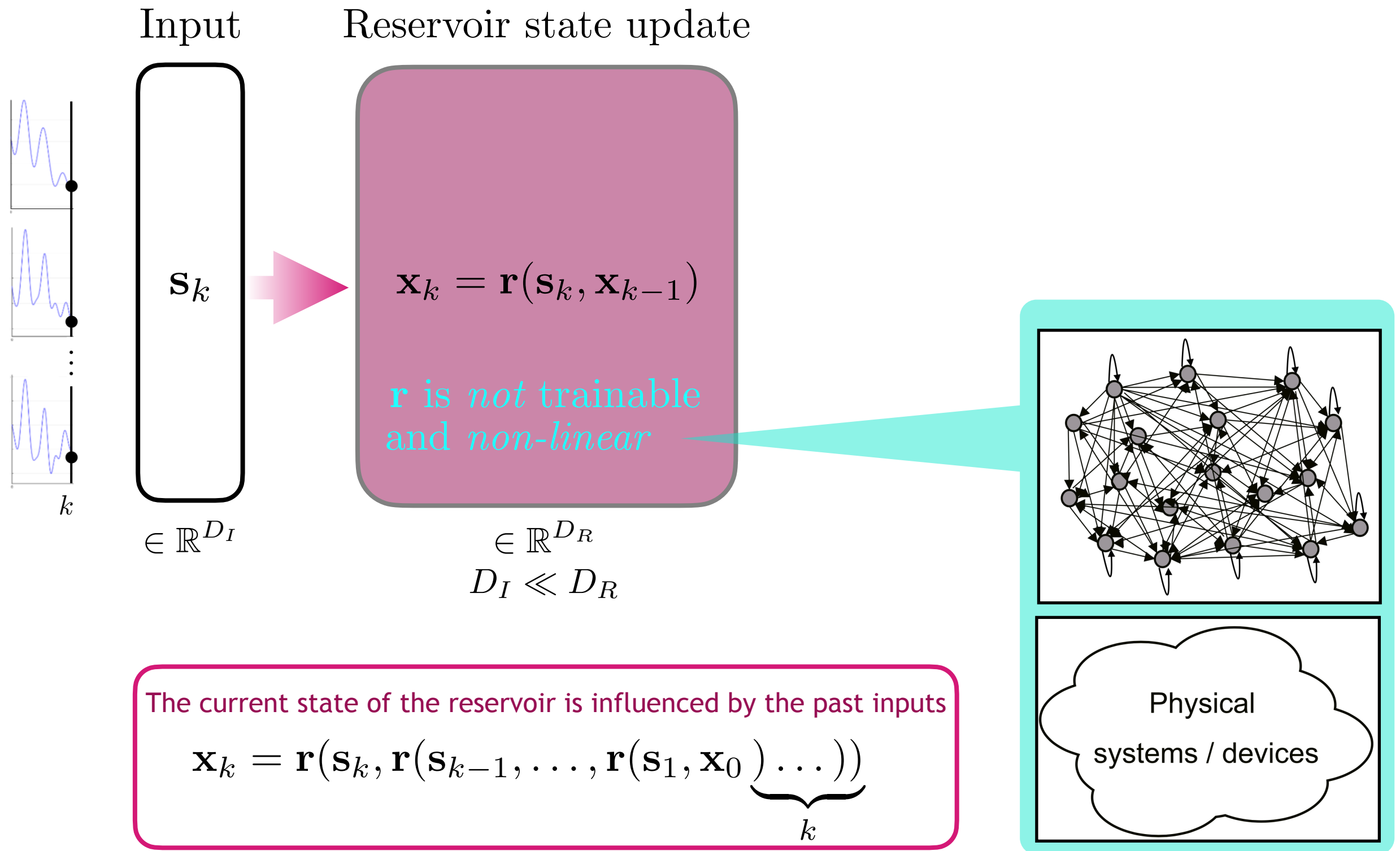
# Reservoir Computing (RC) in a nutshell



The current state of the reservoir is influenced by the past inputs

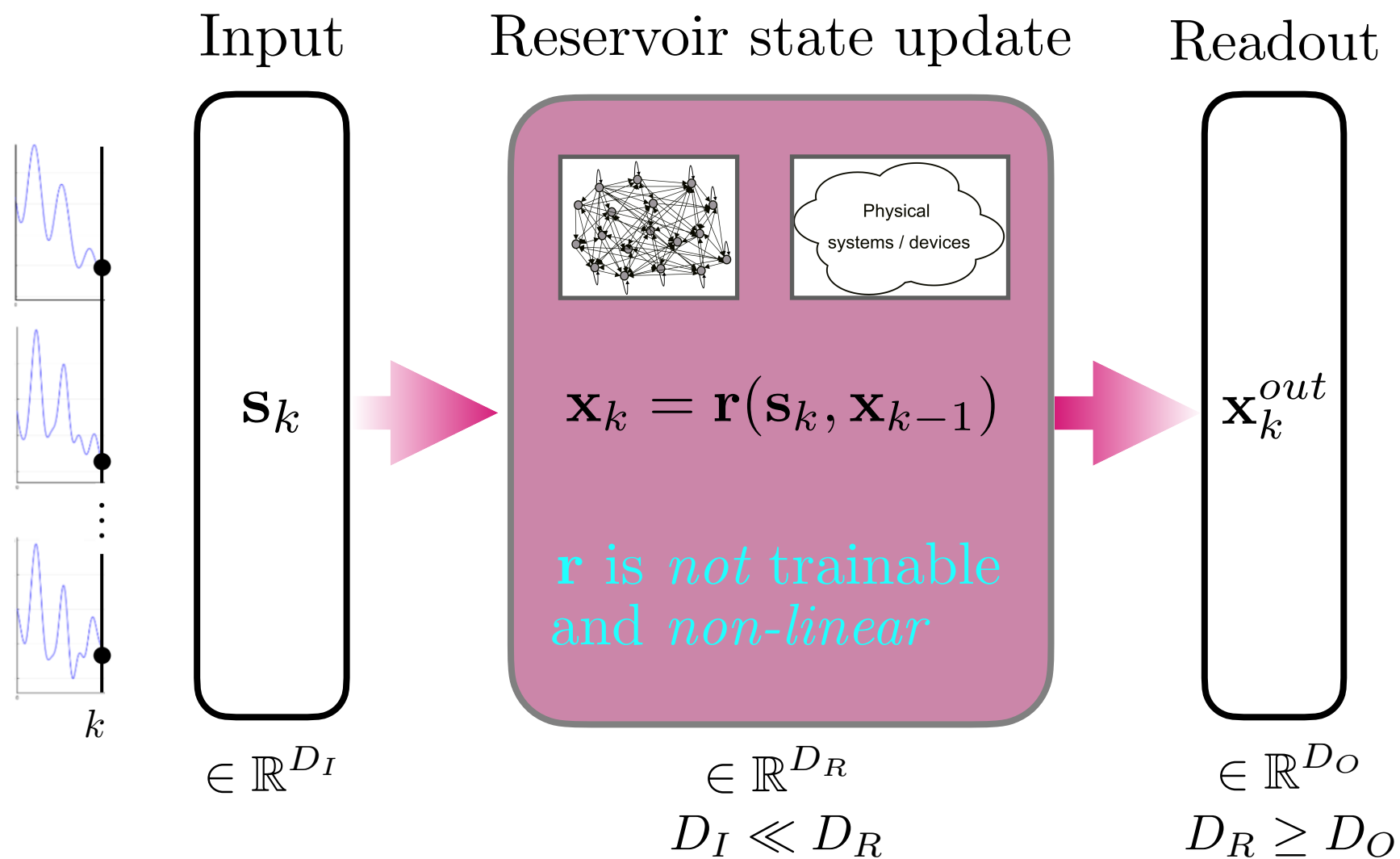
$$\mathbf{x}_k = \mathbf{r}\left(\mathbf{s}_k, \underbrace{\mathbf{r}(\mathbf{s}_{k-1}, \dots, \mathbf{r}(\mathbf{s}_1, \mathbf{x}_0) \dots)}_k\right)$$

# Reservoir Computing (RC) in a nutshell

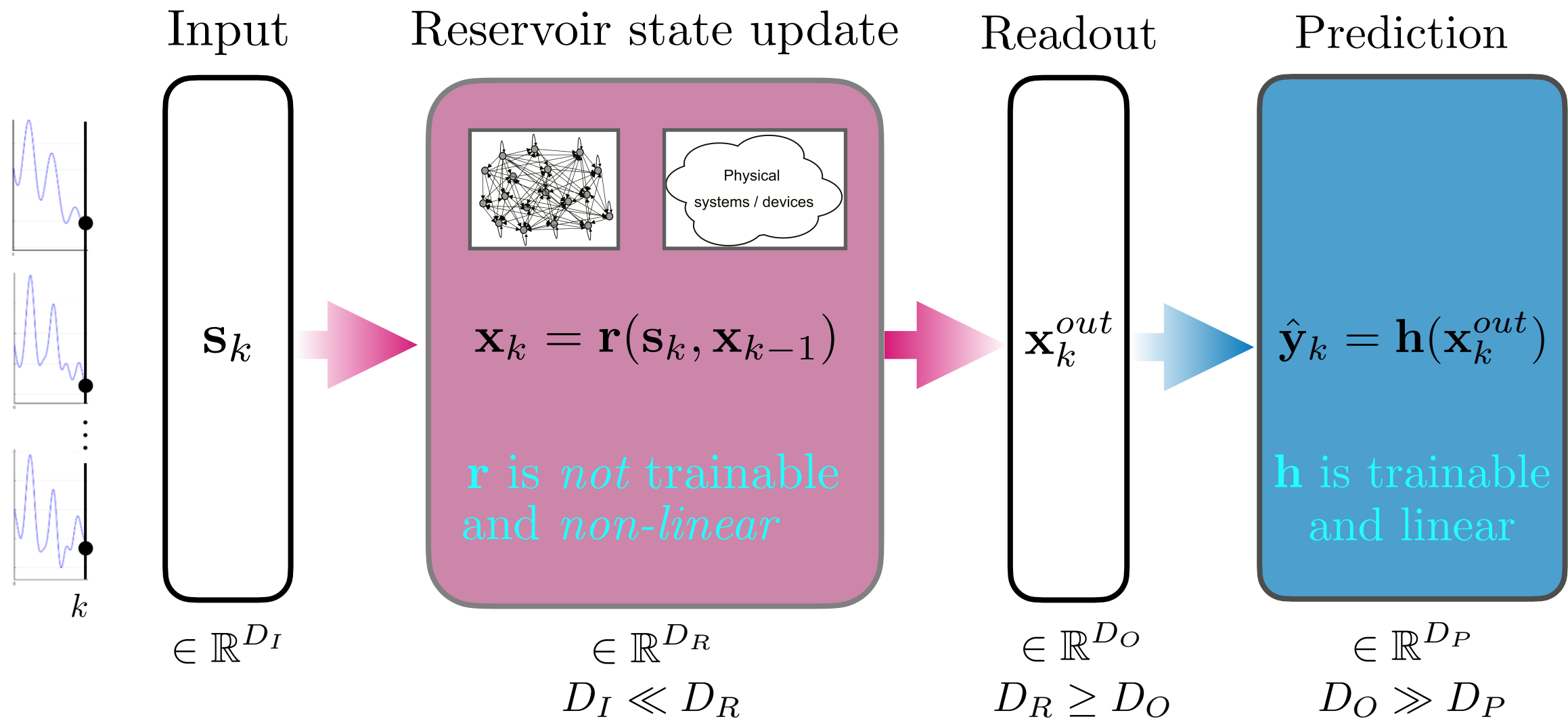




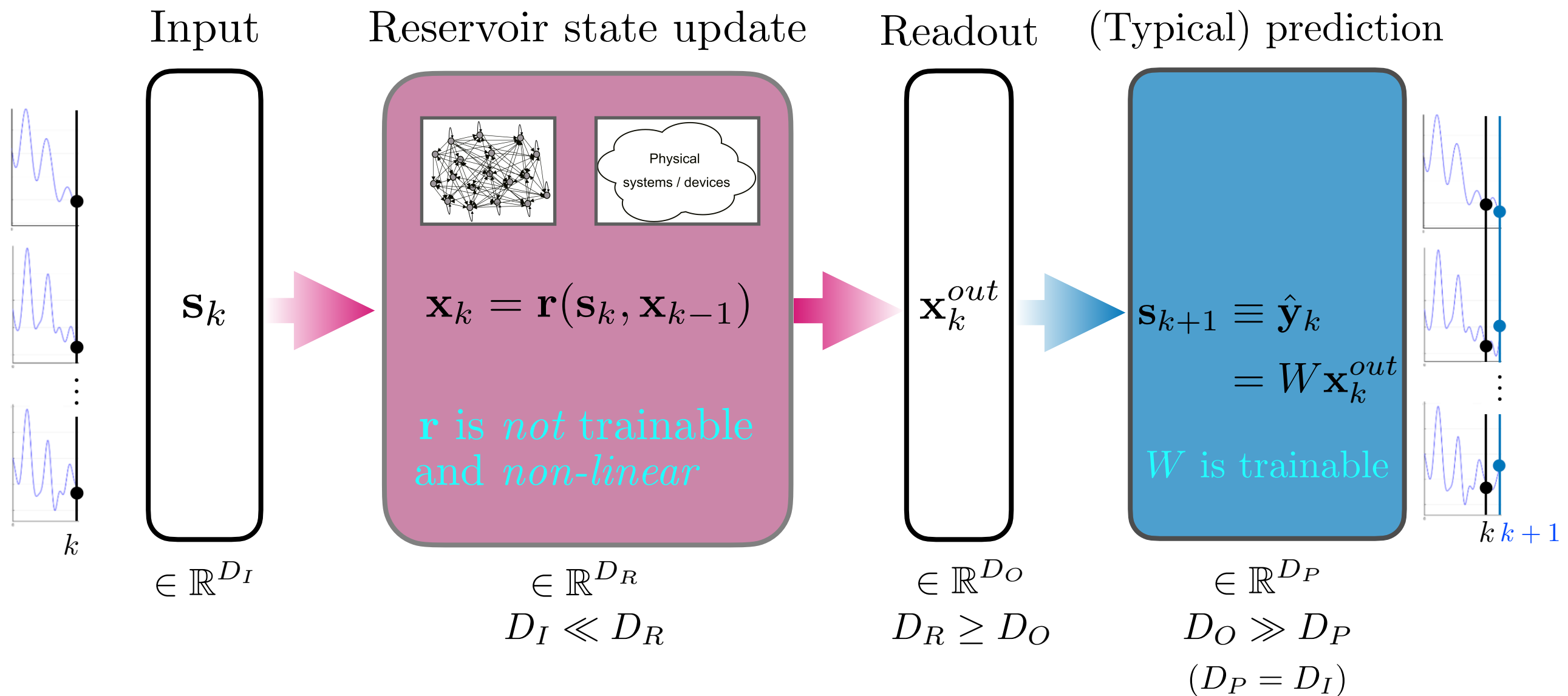
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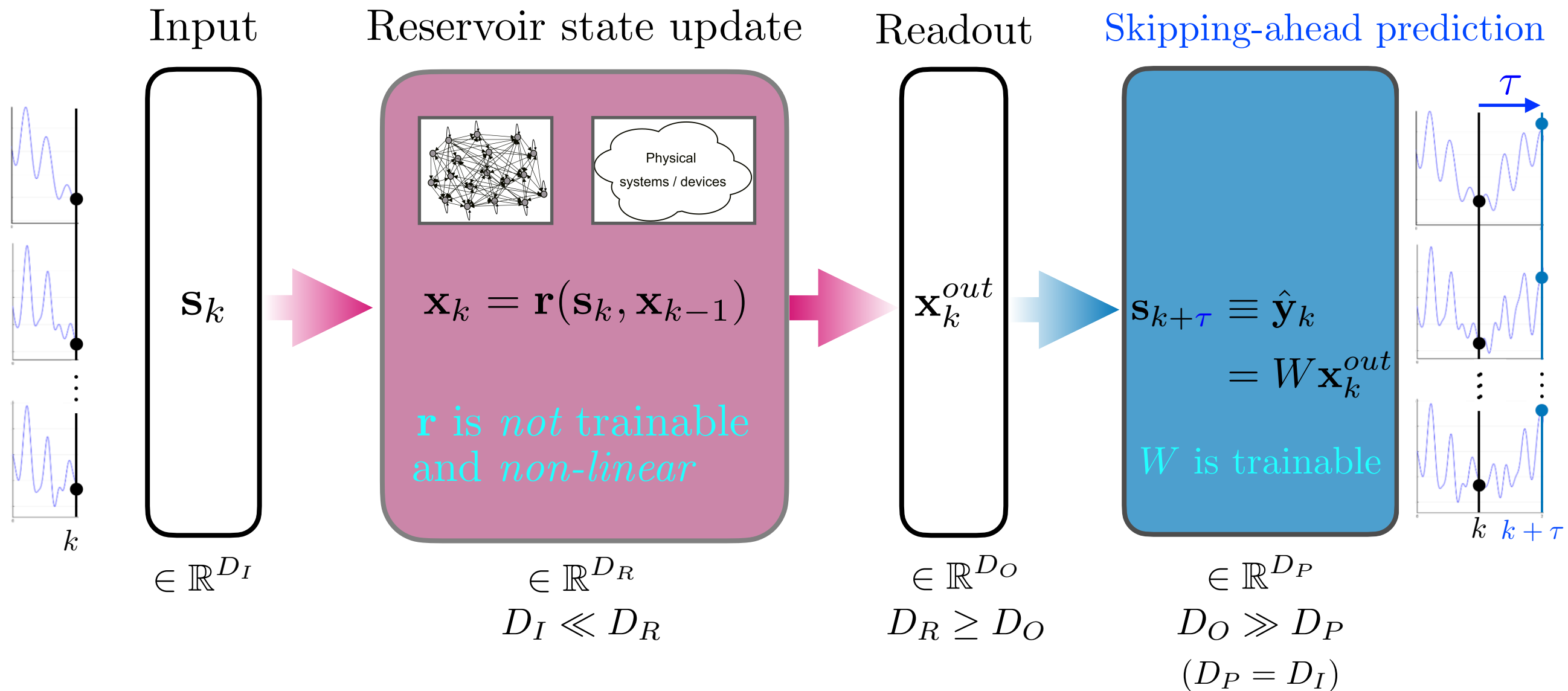
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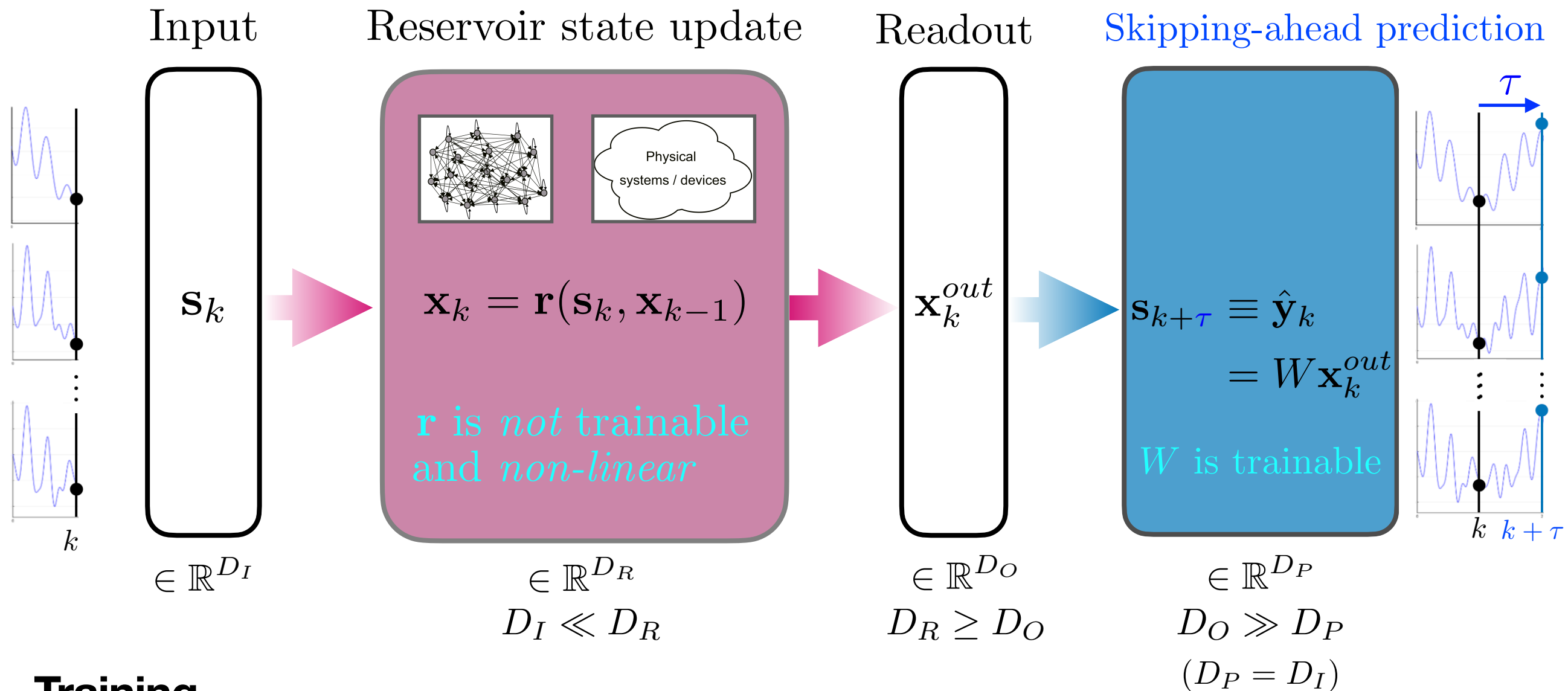


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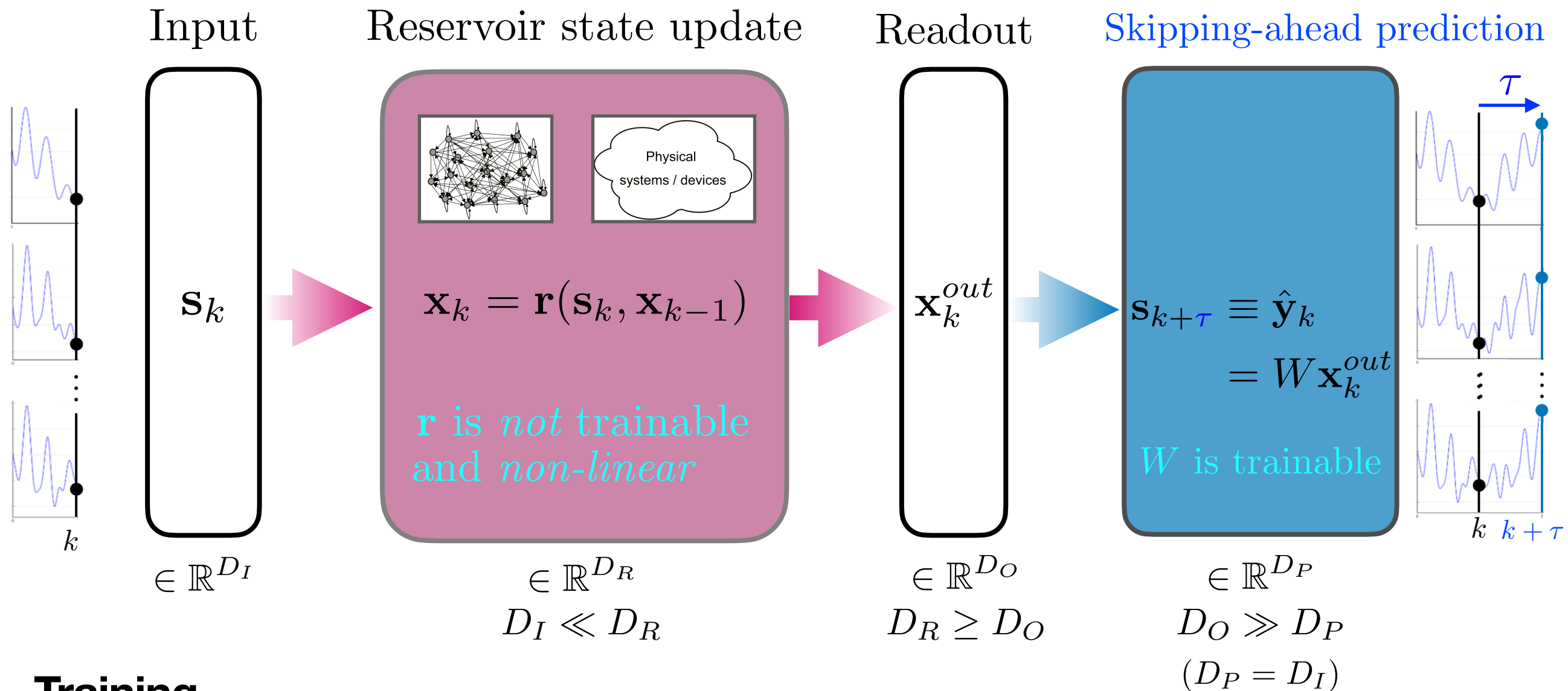


## Training

$\mathbf{W}$  is “trained” by minimizing

$$\frac{1}{T} \sum_{k=0}^{T-1} \|\hat{\mathbf{y}}_k - \mathbf{W} \mathbf{x}_k^{out}\|_2^2 + \lambda \|\mathbf{W}\|^2$$

# Reservoir Computing (RC) in a nutshell



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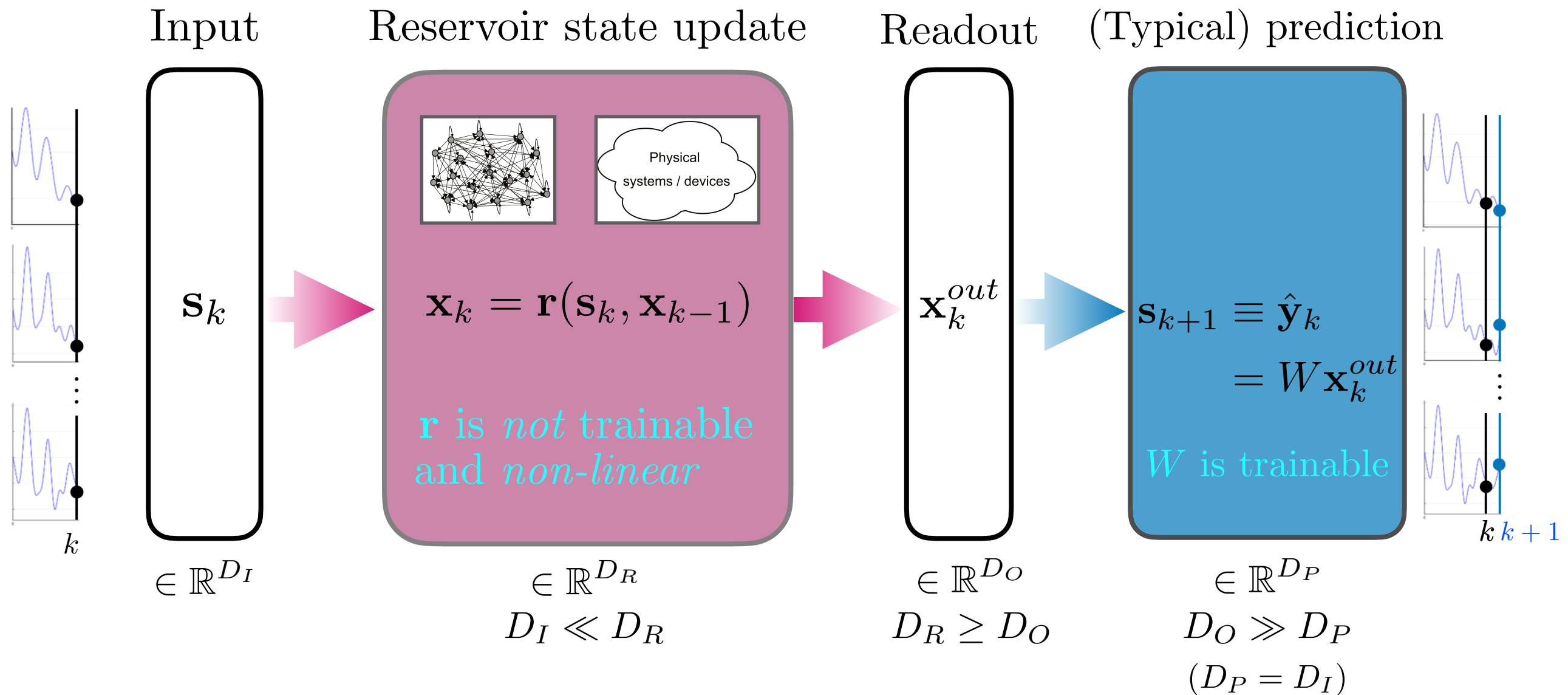
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$$\mathbf{W} = \mathbf{Y} \mathbf{X}^\dagger (\mathbf{X} \mathbf{X}^\dagger + \lambda \mathbf{I})^{-1}$$

$\mathbf{Y} = (\hat{\mathbf{y}}_0, \dots, \hat{\mathbf{y}}_{T-1}) \in \mathbb{R}^{D_P \times T}$  target matrix  
 $\mathbf{X} = (\mathbf{x}_0^{out}, \dots, \mathbf{x}_{T-1}^{out}) \in \mathbb{R}^{D_O \times T}$  feature matrix

# Reservoir Computing (RC) in a nutshell



## Typical Prediction

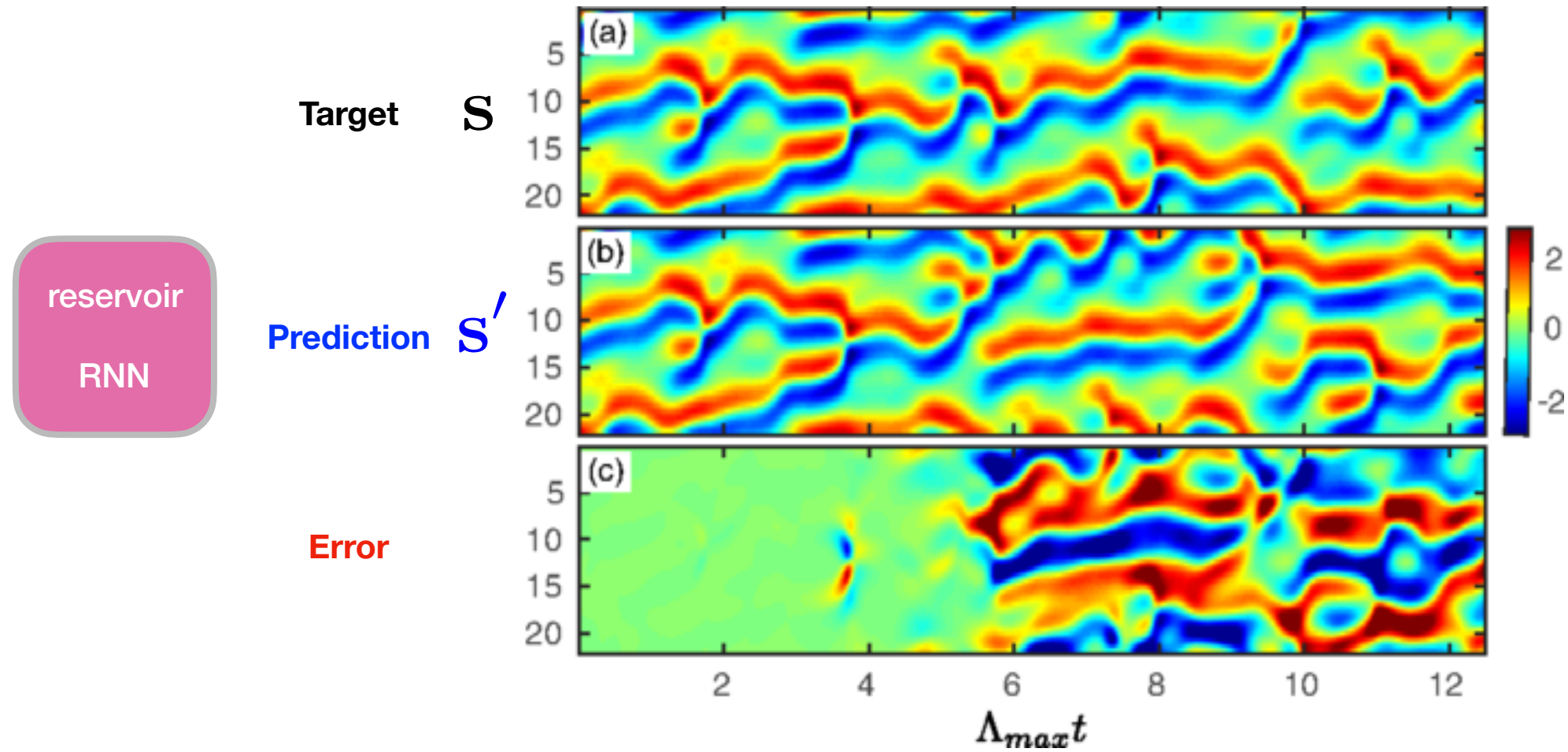
$$(\mathbf{x}_k^{out} = \mathbf{x}_k)$$

$$\mathbf{s}'_{k+1} = W \mathbf{x}_k = W \mathbf{r}(\mathbf{s}'_k, \mathbf{x}_{k-1})$$

$$\mathbf{s}'_{k+2} = W \mathbf{r}(\mathbf{s}'_{k+1}, \mathbf{x}_k) = W \mathbf{r}(W \mathbf{r}(\mathbf{s}'_k, \mathbf{x}_{k-1}), \mathbf{x}_k)$$

$\vdots$

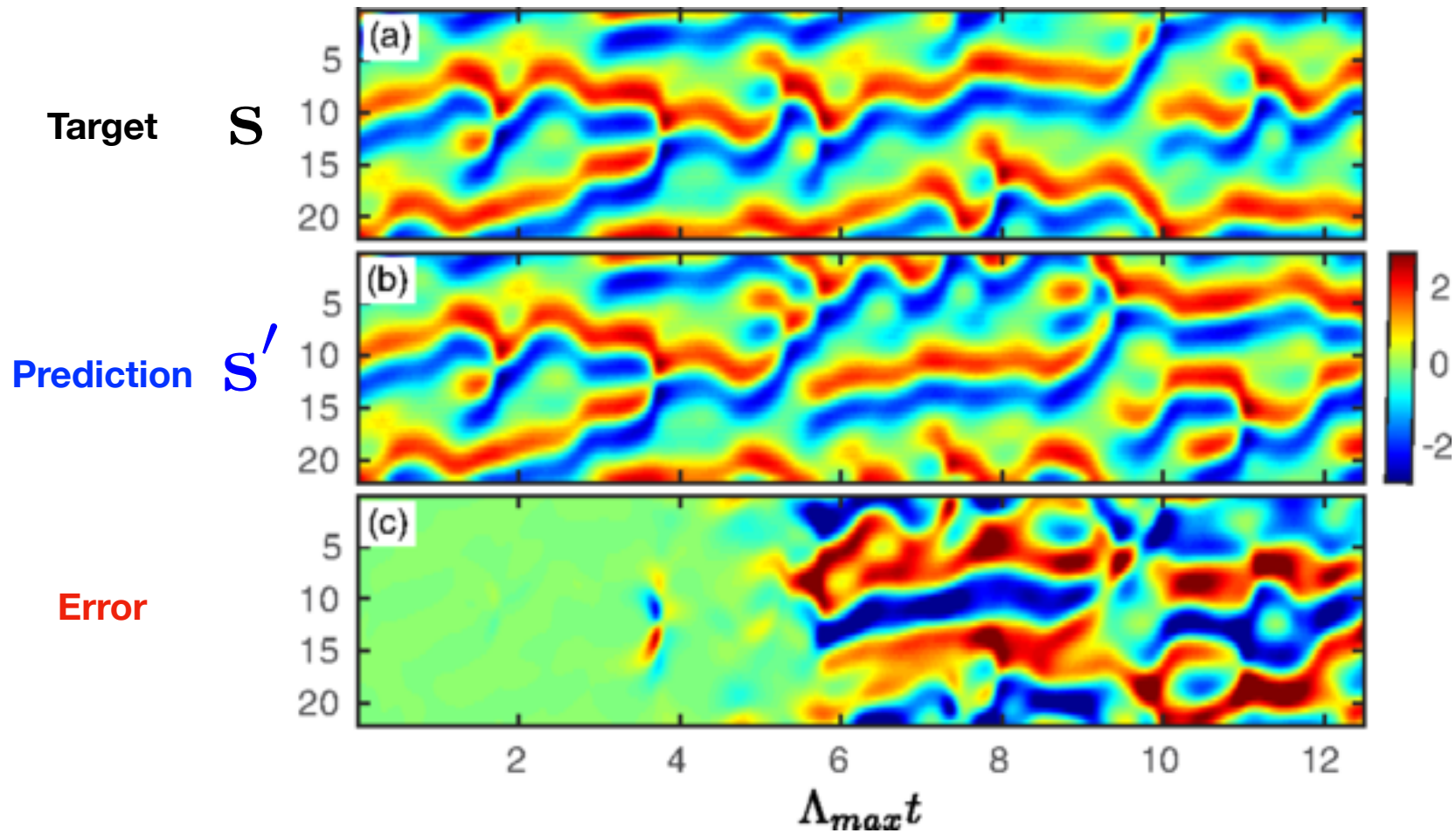
## kuramoto-sivashinsky spatiotemporal chaos



J. Pathak et. al. Model-Free Prediction of Large Spatiotemporally Chaotic Systems from Data: A Reservoir Computing Approach, *Phys. Rev. Lett.* **120**, 024102, 2018

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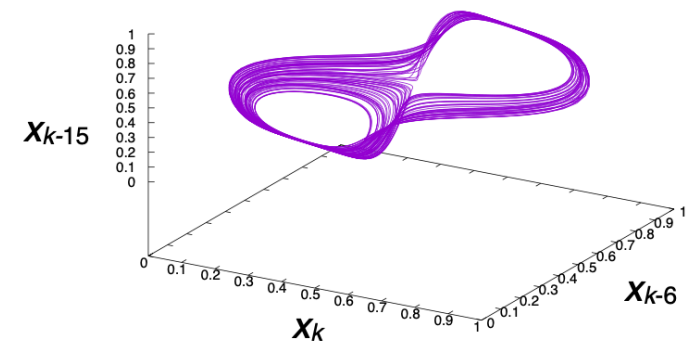
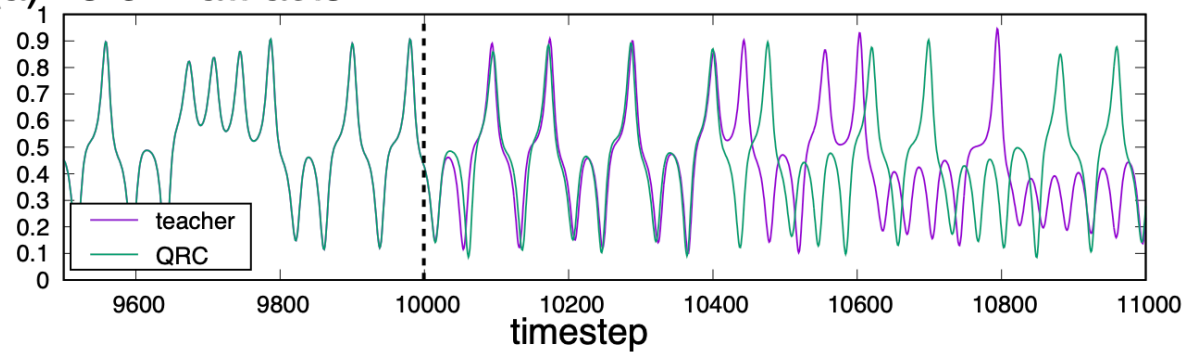
reservoir  
RNN



J. Pathak et. al. Model-Free Prediction of Large Spatiotemporally Chaotic Systems from Data: A Reservoir Computing Approach, *Phys. Rev. Lett.* **120**, 024102, 2018

reservoir  
quantum  
Ising

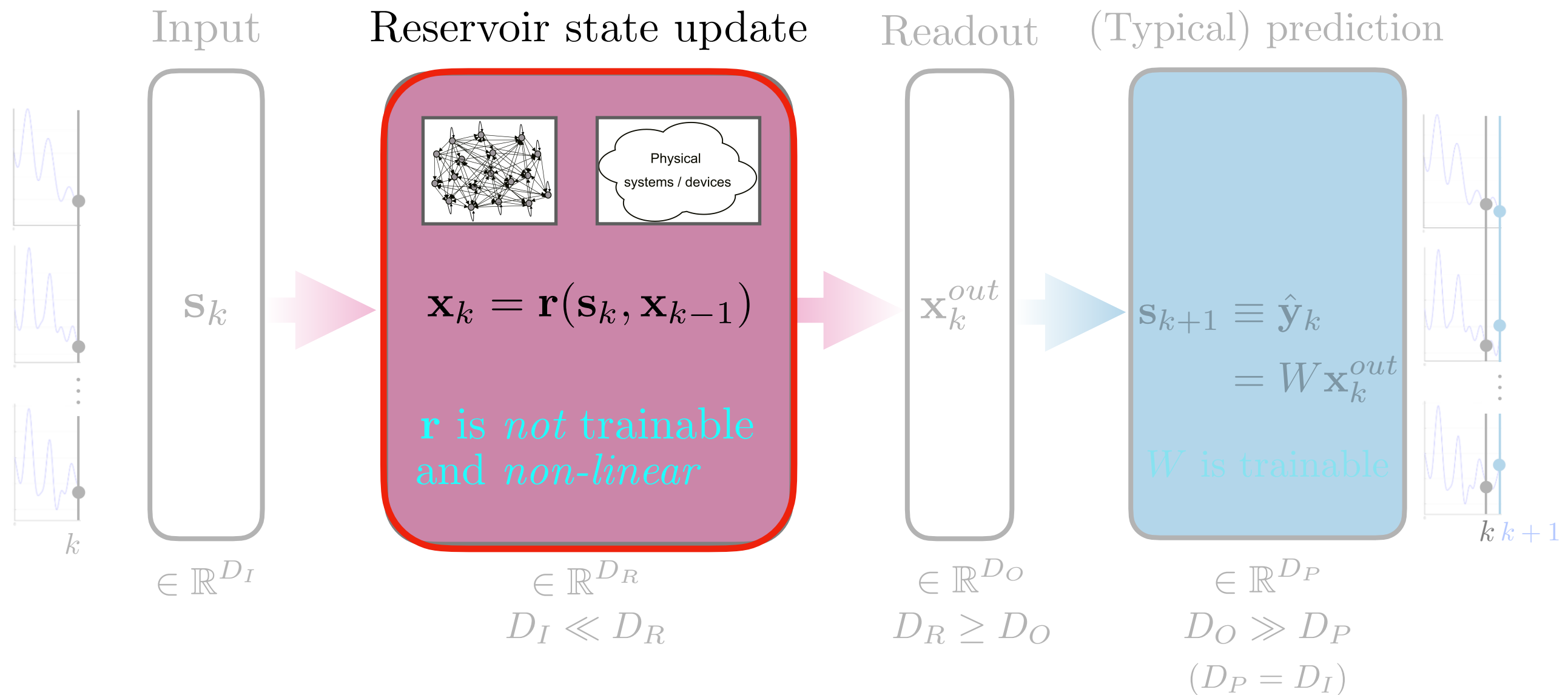
(a) Lorenz attractor



K. Fujii, K. Navajoma Quantum Reservoir Computing: A Reservoir Approach Toward Quantum Machine Learning Near-Term Devices, *Reservoir Computing* 423-450, 2021

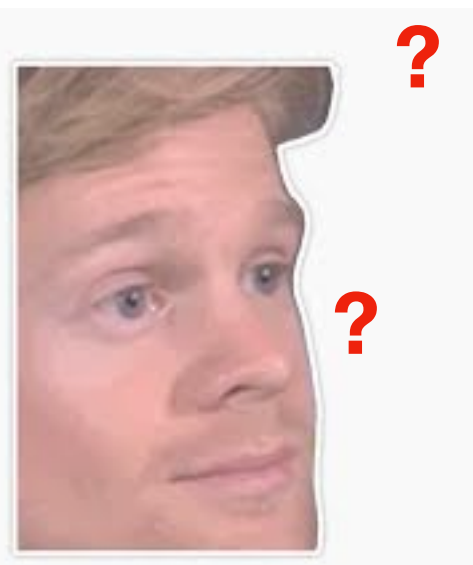
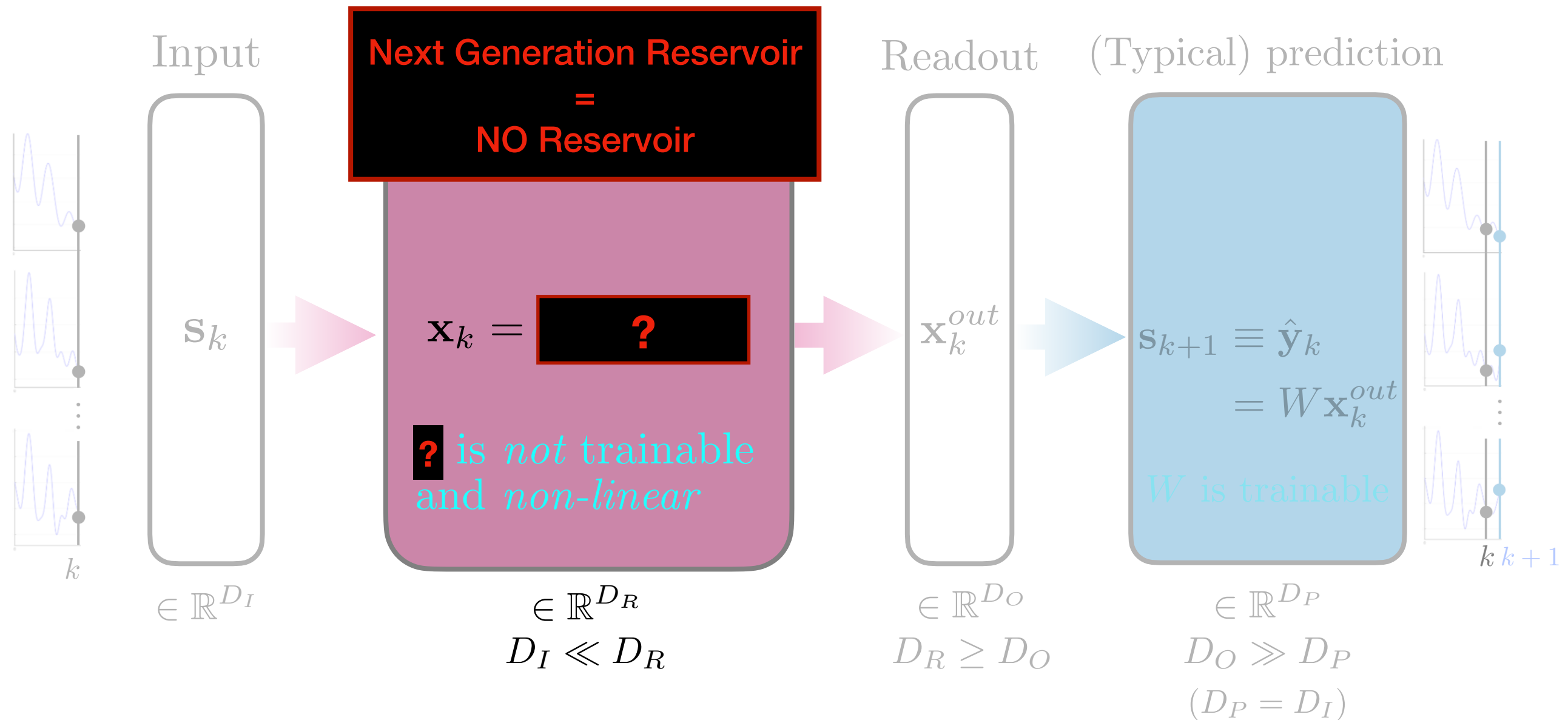


# Reservoir Computing (RC) in a nutshell

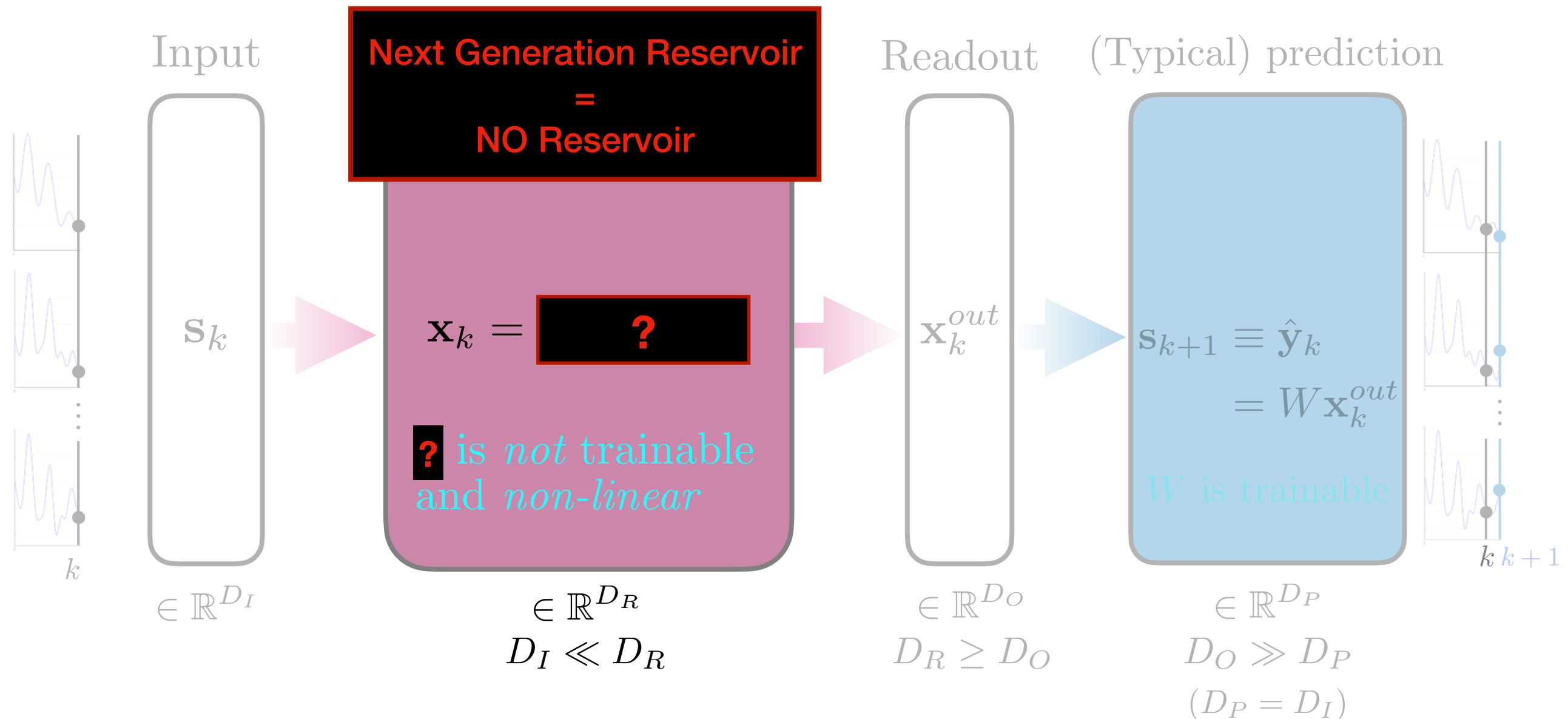


**! No clear strategy on how to initialize different types of reservoir !**

# Next Generation Reservoir Computing (NG-RC) in a nutshell



# Next Generation Reservoir Computing (NG-RC) in a nutshell



## Non-linear feature map with “memory” of the past data

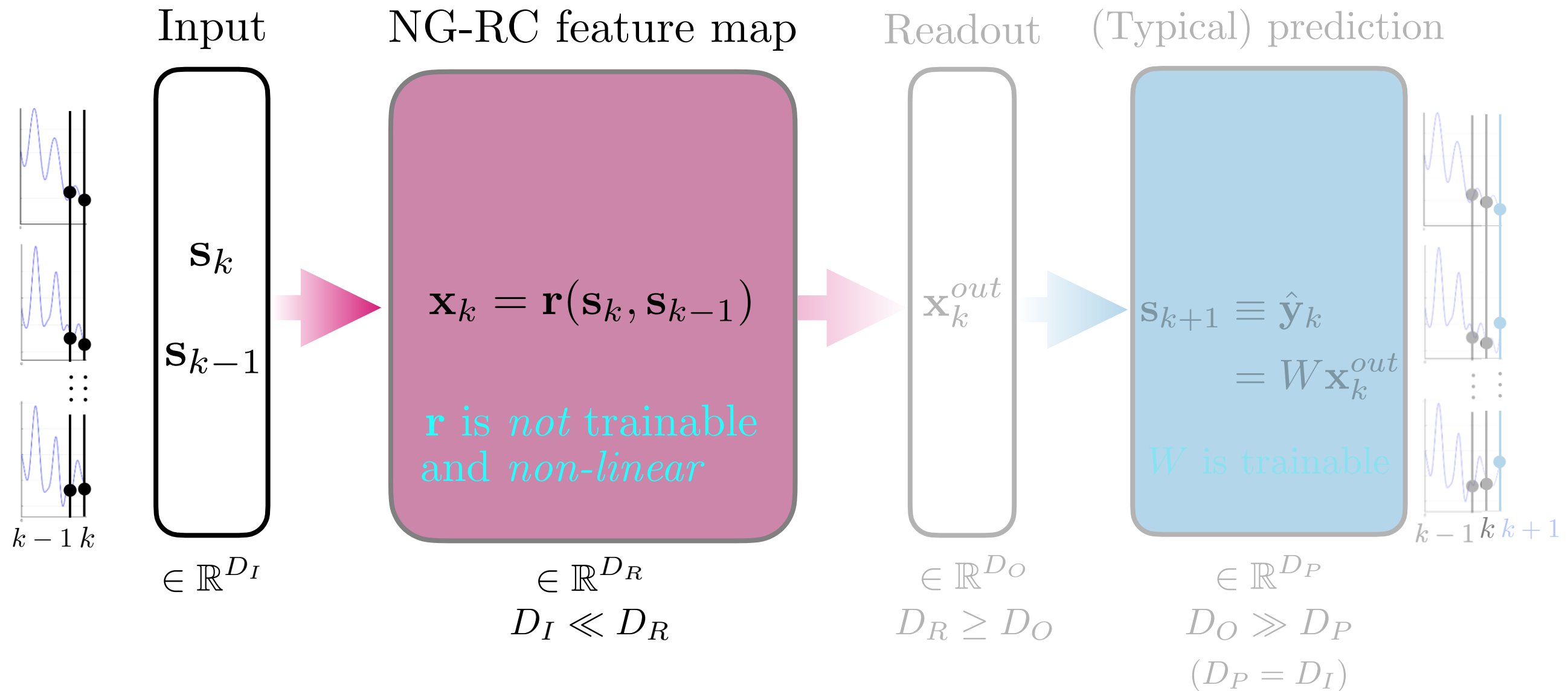
$$\mathbf{o}_k = \mathbf{s}_k \oplus \mathbf{s}_{k-\Delta} \oplus \mathbf{s}_{k-2\Delta} \oplus \dots \oplus \mathbf{s}_{k-(m-1)\Delta}$$

$$\mathbf{x}_k = \mathbf{o}_k \oplus (\mathbf{o}_k)^{\otimes p} \quad (\text{non-linear for } p > 1)$$

In some limit, equivalent to nonlinear vector autoregression (NVAR) with universal approximation property for dynamical systems

D. J. Gauthier et. al. Next generation reservoir computing *Nature Communications* 12:5564 (2021)

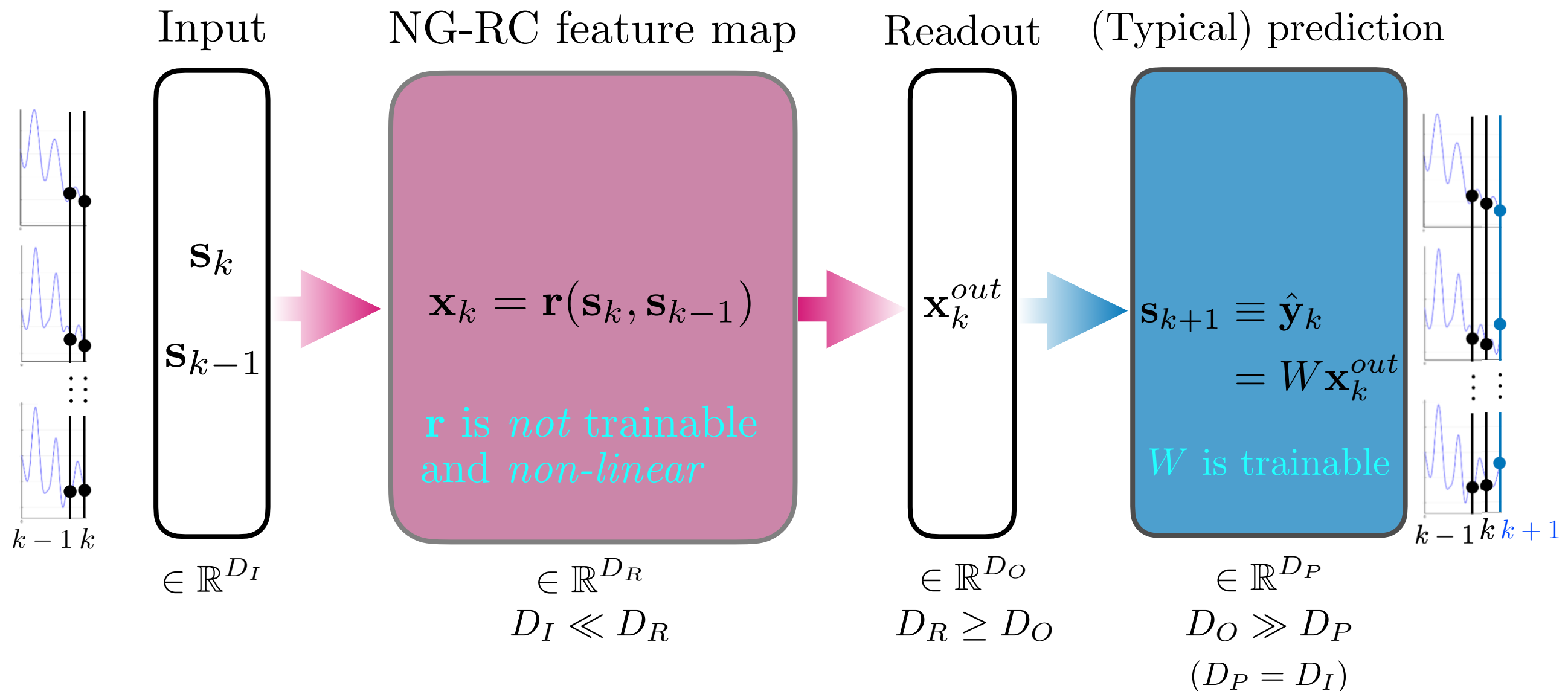
# Next Generation Reservoir Computing (NG-RC) in a nutshell



For example  $\Delta = 1, m = 2, p = 2$

$$\begin{aligned} \mathbf{x}_k &= \mathbf{s}_k \oplus \mathbf{s}_{k-1} \oplus [(\mathbf{s}_k \oplus \mathbf{s}_{k-1}) \otimes (\mathbf{s}_k \oplus \mathbf{s}_{k-1})] \\ &\equiv \mathbf{r}(\mathbf{s}_k, \mathbf{s}_{k-1}) \end{aligned}$$

# Next Generation Reservoir Computing (NG-RC) in a nutshell



**Training**

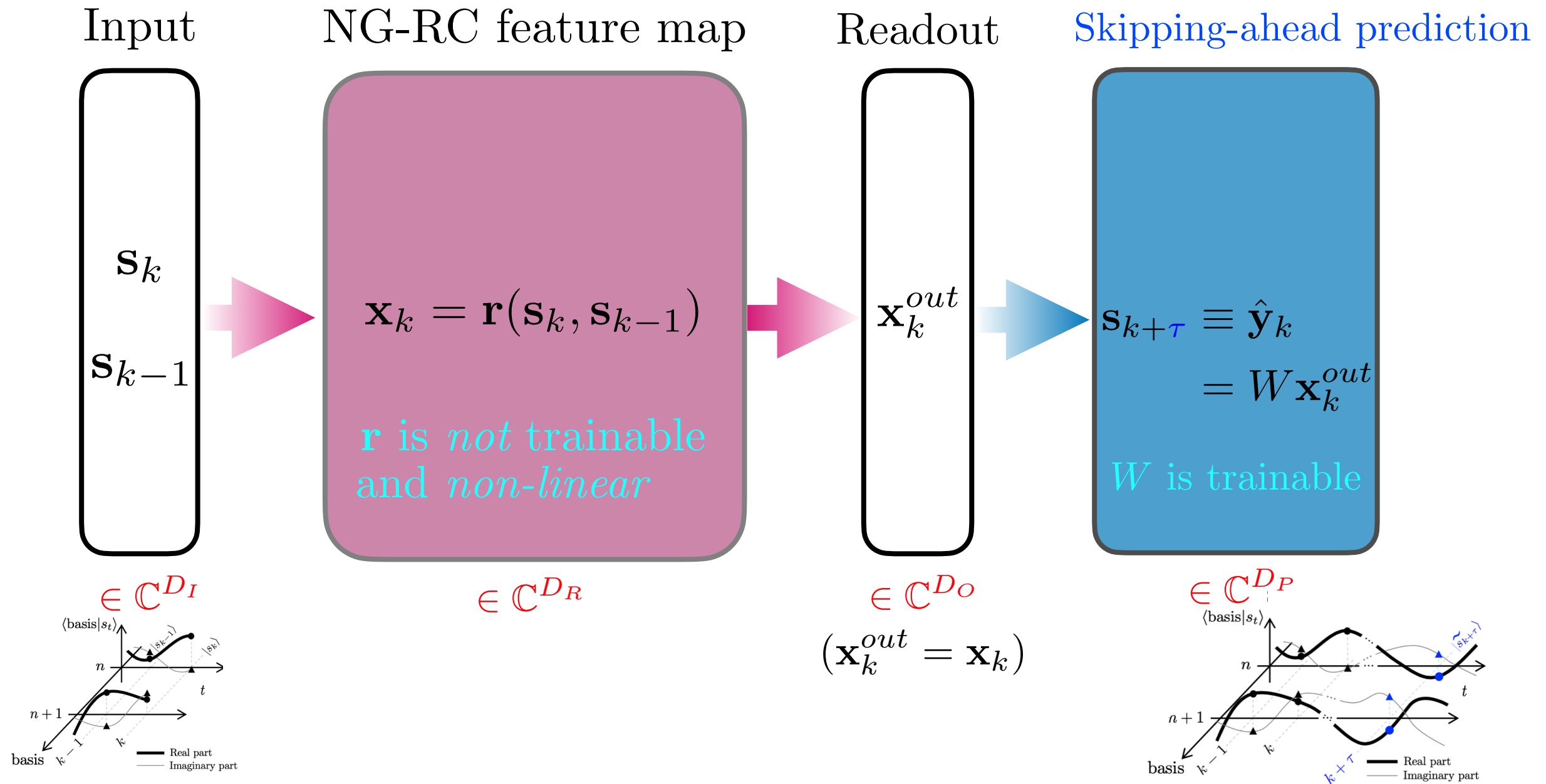
$$W = Y X^\dagger (X X^\dagger + \lambda I)^{-1}$$

**Typical prediction**

$$\mathbf{s}'_{k+1} = W \mathbf{x}_k = W \mathbf{r}(\mathbf{s}'_k, \mathbf{s}'_{k-1}) \quad (\mathbf{x}_k^{out} = \mathbf{x}_k)$$



# NG-RC for forecasting quantum dynamics



**Training**

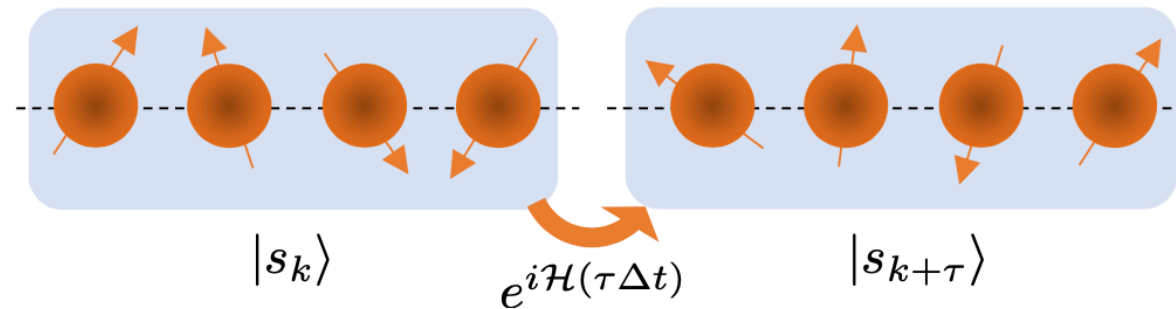
$$W = Y X^\dagger (X X^\dagger + \lambda I)^{-1}$$

**Skipping-ahead prediction**

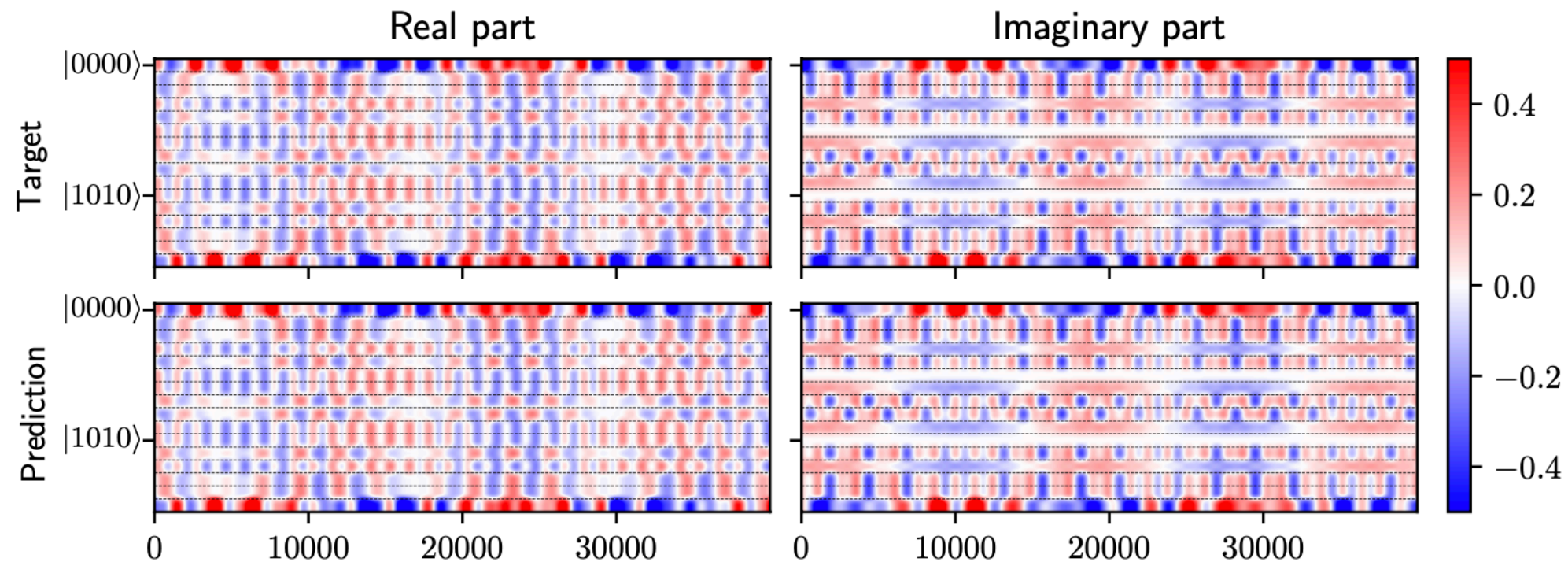
$$\mathbf{s}'_{k+\tau} = W \mathbf{x}_k = W \mathbf{r}(\mathbf{s}'_k, \mathbf{s}'_{k-1})$$

# NG-RC for forecasting integrable quantum dynamics

$$\mathcal{H} = -J \sum_{i=1}^4 Z_i Z_{i+1} + h \sum_{i=1}^4 X_i$$

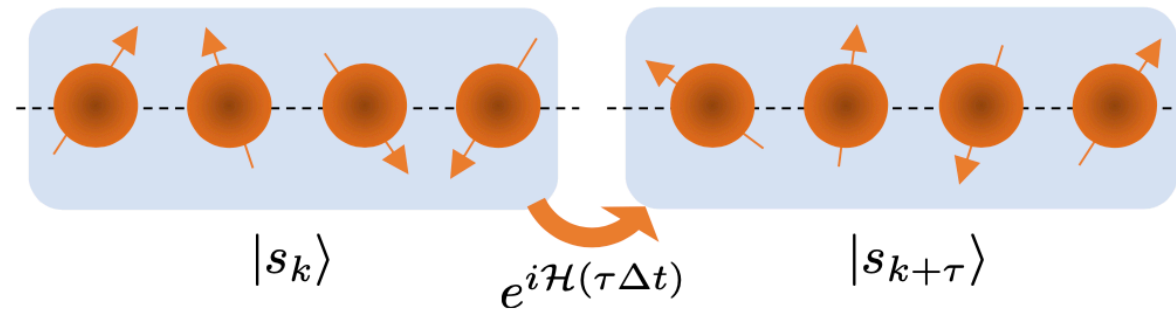


skipping-ahead with  $\tau = 10^6$

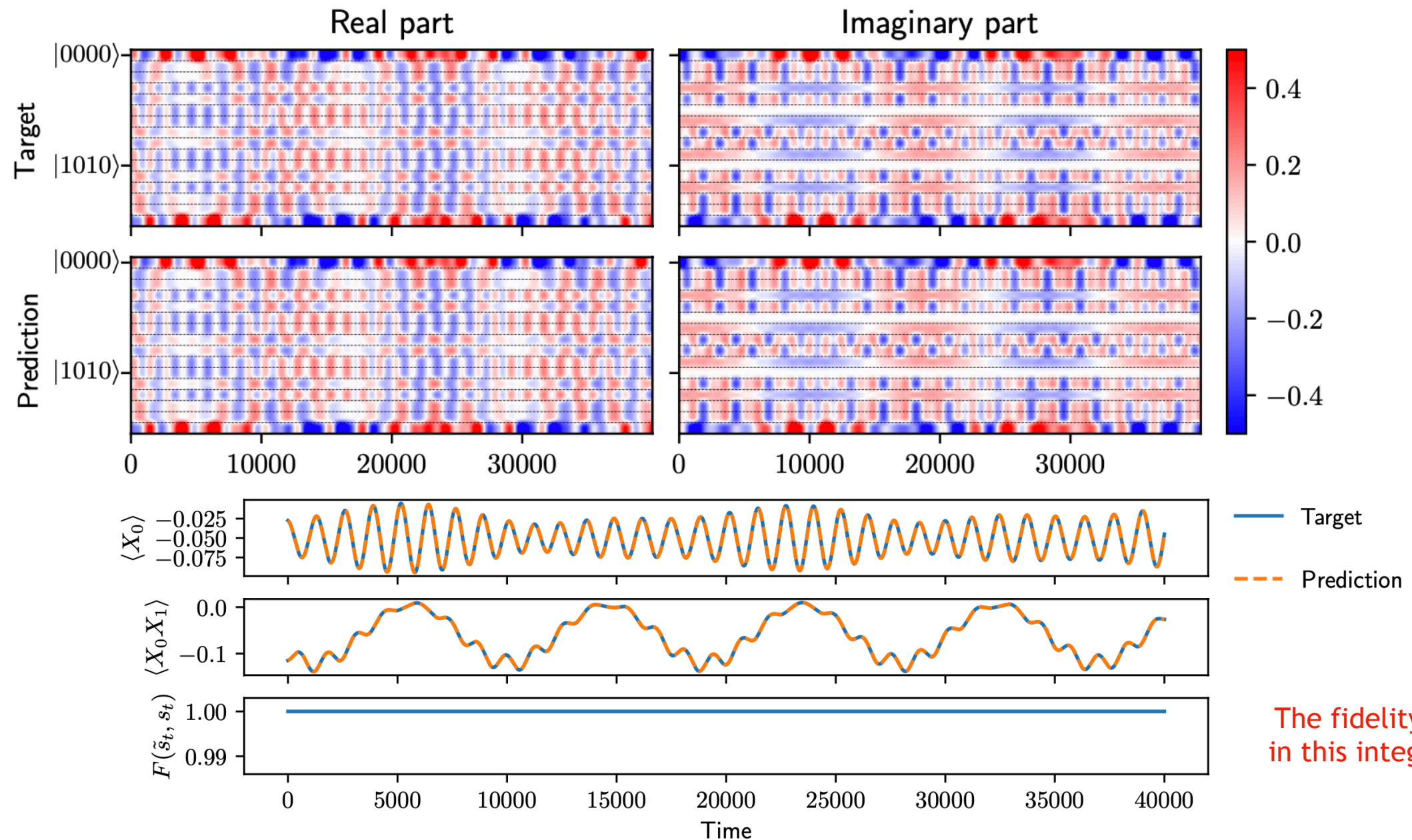


# NG-RC for forecasting integrable quantum dynamics

$$\mathcal{H} = -J \sum_{i=1}^4 Z_i Z_{i+1} + h \sum_{i=1}^4 X_i$$



skipping-ahead with  $\tau = 10^6$



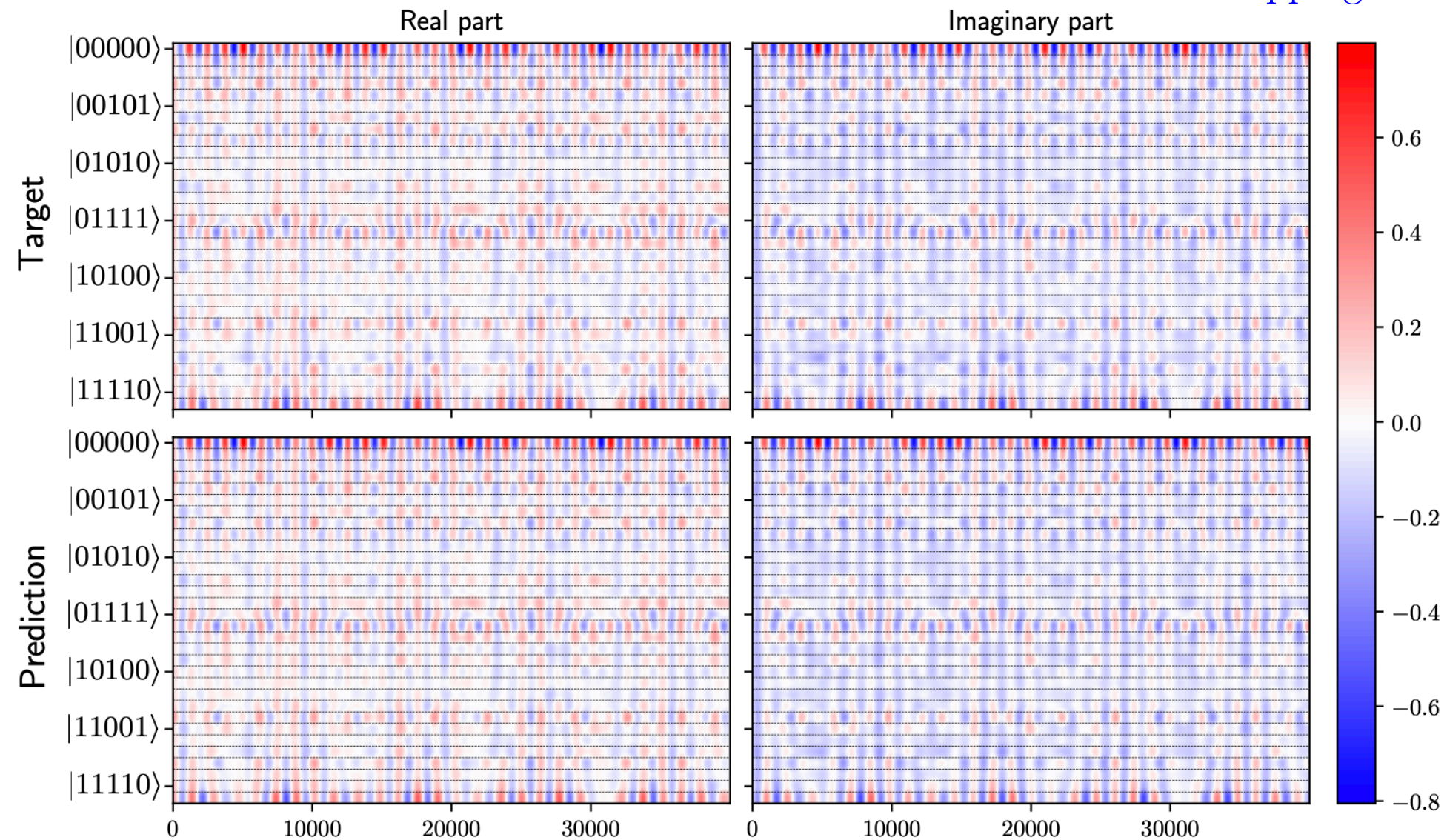


# NG-RC for forecasting *chaotic* quantum dynamics

$$\mathcal{H}_{\text{tilted}} = J \sum_{i=1}^{d-1} Z_i Z_{i+1} + h \sum_{i=1}^d (X_i \sin \theta + Z_i \cos \theta)$$

$$d = 5, \theta = 15\pi/32$$

skipping-ahead with  $\tau = 10^6$



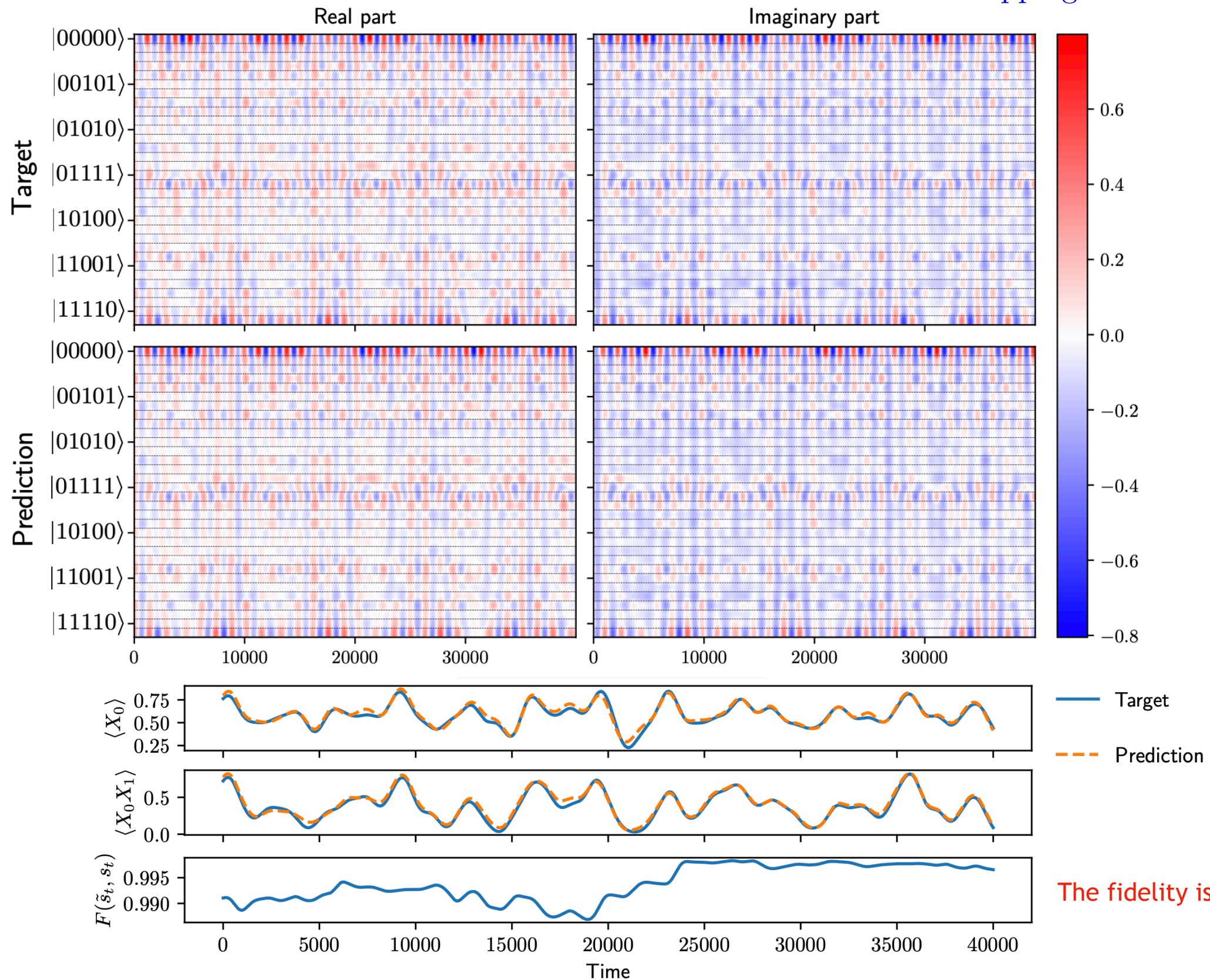


# NG-RC for forecasting *chaotic* quantum dynamics

$$\mathcal{H}_{\text{tilted}} = J \sum_{i=1}^{d-1} Z_i Z_{i+1} + h \sum_{i=1}^d (X_i \sin \theta + Z_i \cos \theta)$$

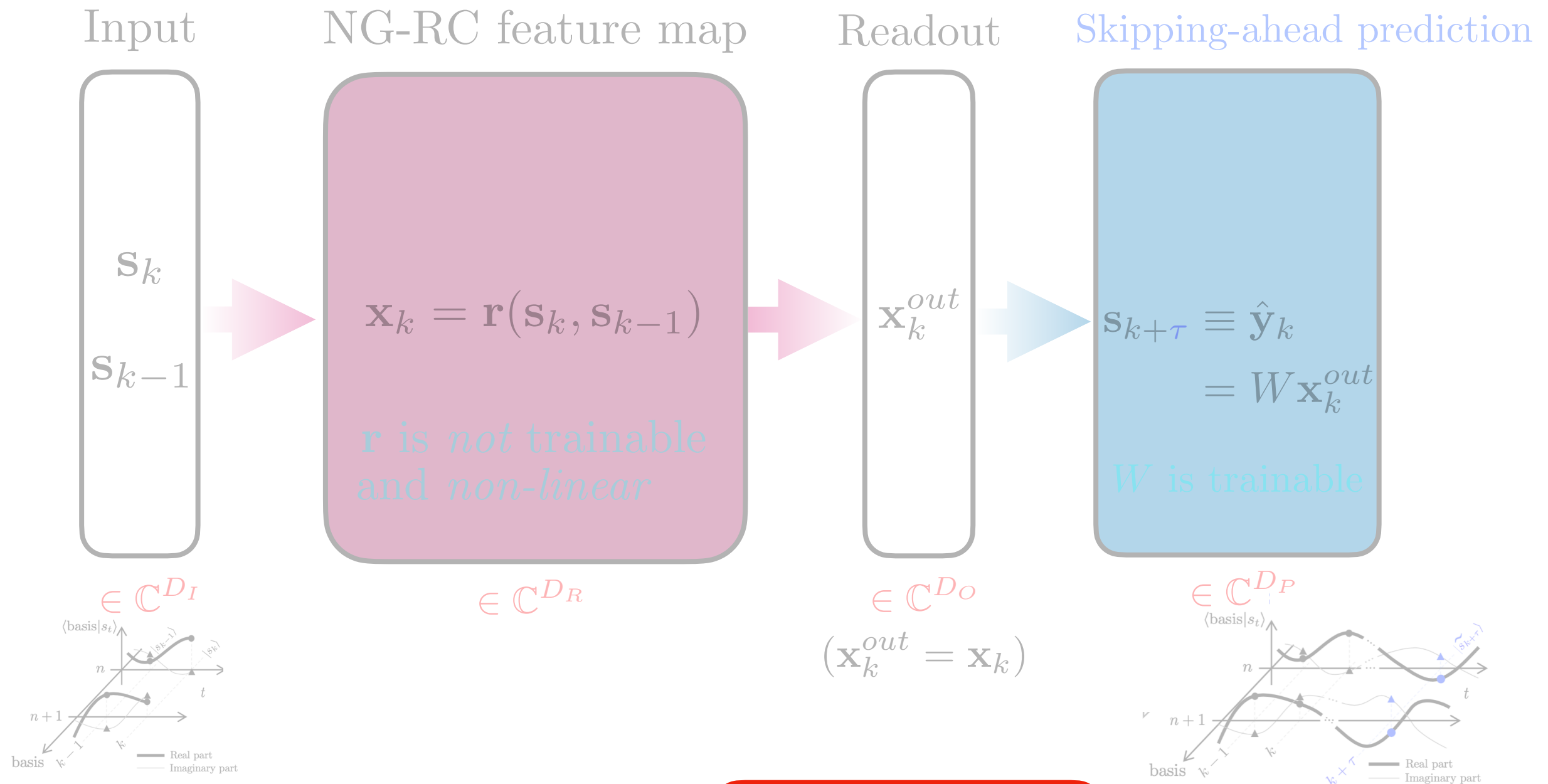
$$d = 5, \theta = 15\pi/32$$

skipping-ahead with  $\tau = 10^6$





# Scalability issue of classical NG-RC for many-body systems



**Training**

$$W = Y X^\dagger (X X^\dagger + \lambda I)^{-1}$$

$$O(2^{2d} T)$$

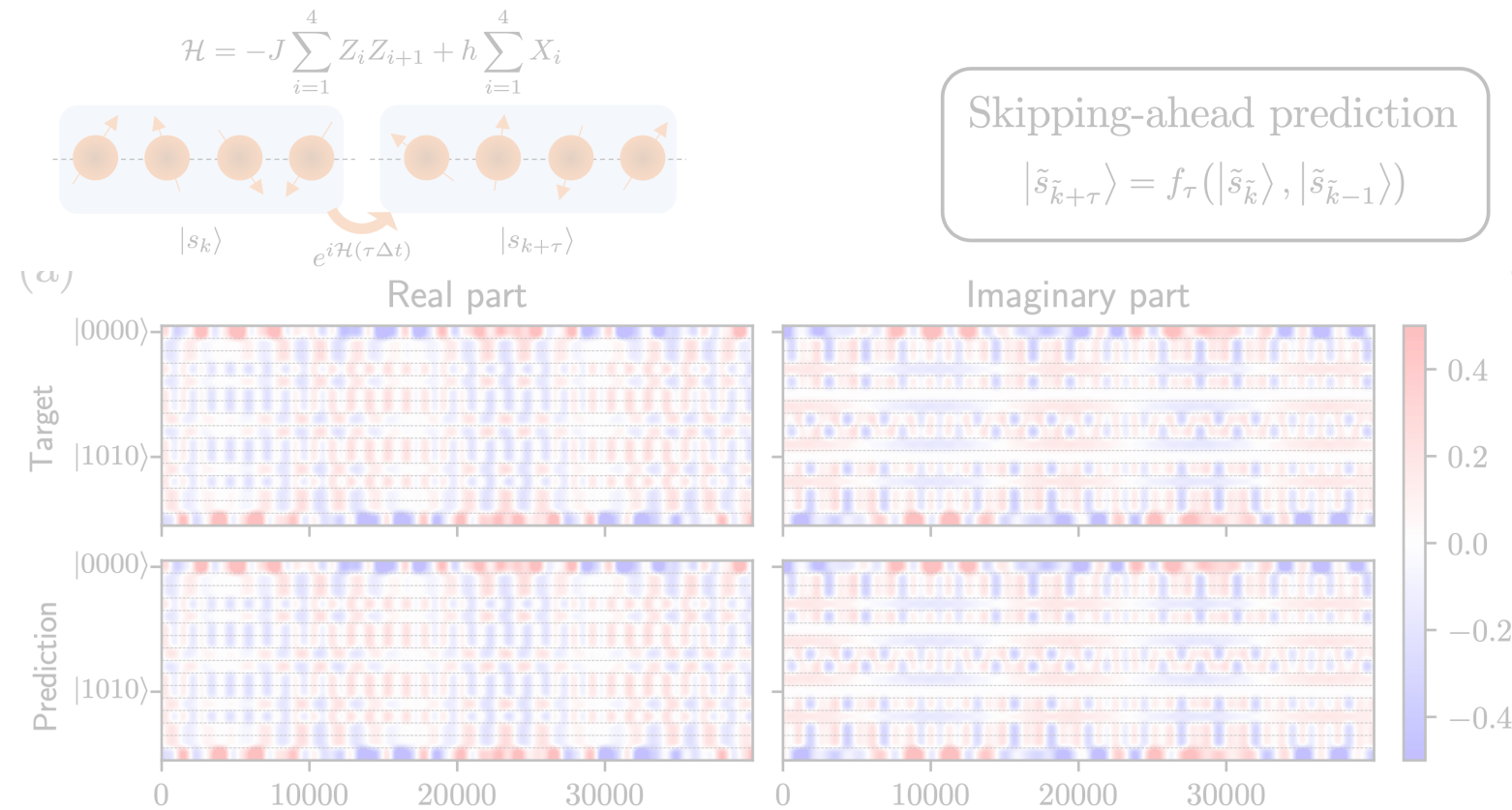
Pseudoinverse Computation  
 $d = \#$  of qubits

**Skipping-ahead prediction**

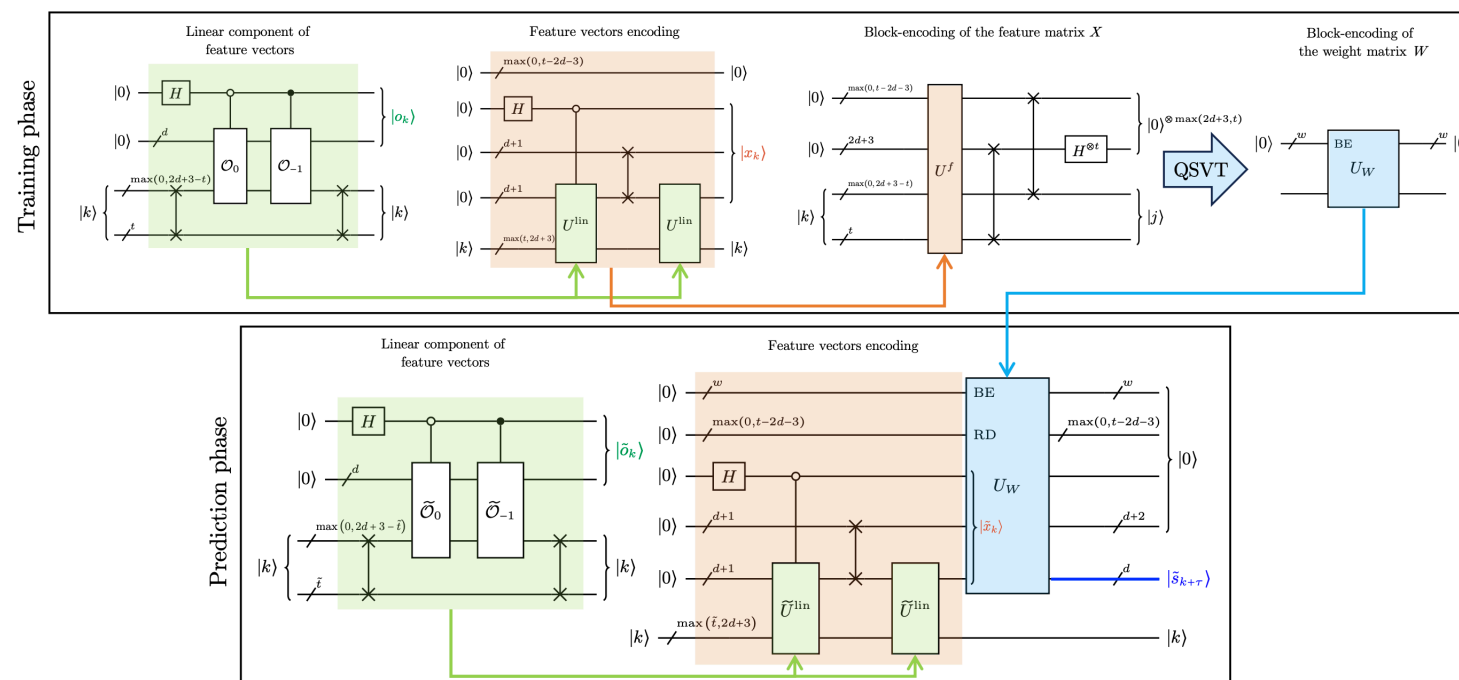
$$\mathbf{s}'_{k+\tau} = W \mathbf{x}_k = W \mathbf{r}(\mathbf{s}'_k, \mathbf{s}'_{k-1})$$

# Outline

## Part 1: NG-RC for Many-body Quantum Dynamics Prediction

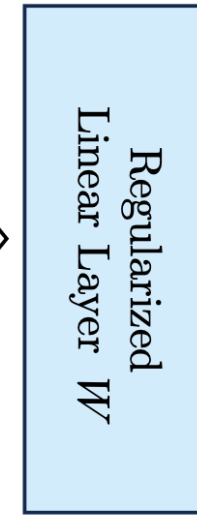
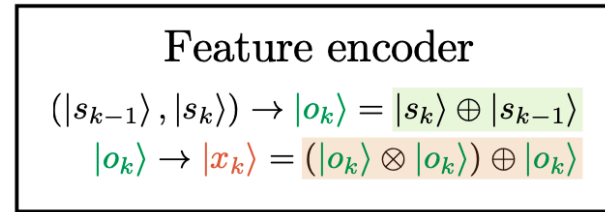
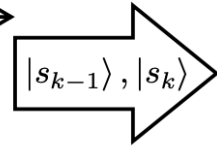
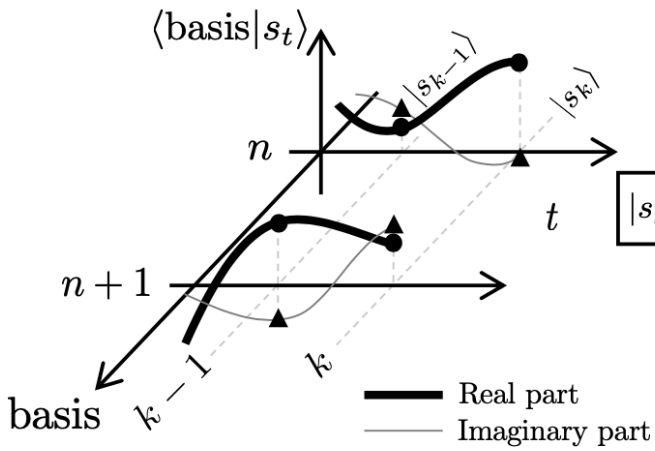


## Part 2: Quantum Algorithm for NG-RC (QNG-RC)

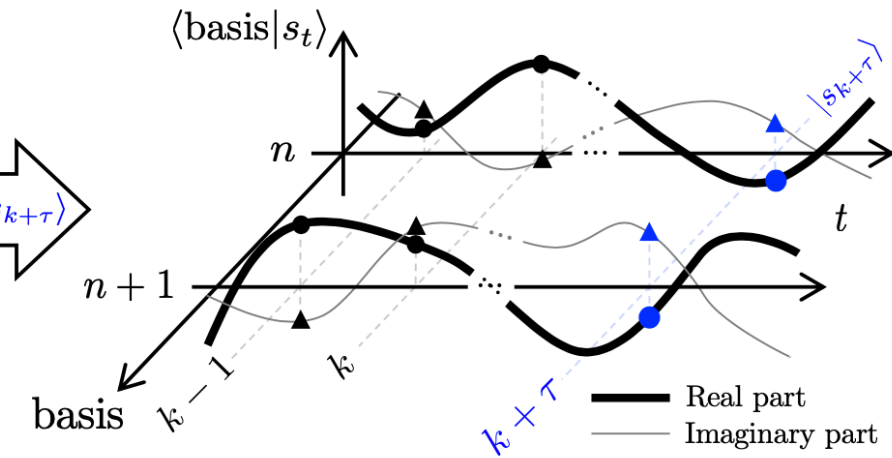


# Quantum Algorithm for NG-RC (QNG-RC)

Quantum dynamics

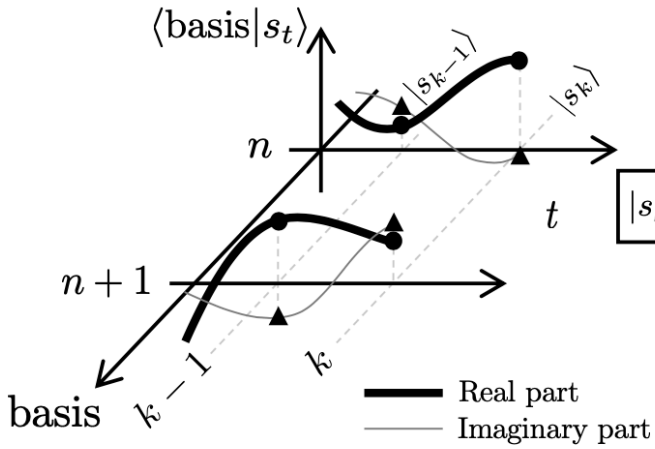


Skipping-ahead dynamics



# Quantum Algorithm for NG-RC (QNG-RC)

Quantum dynamics



Feature encoder

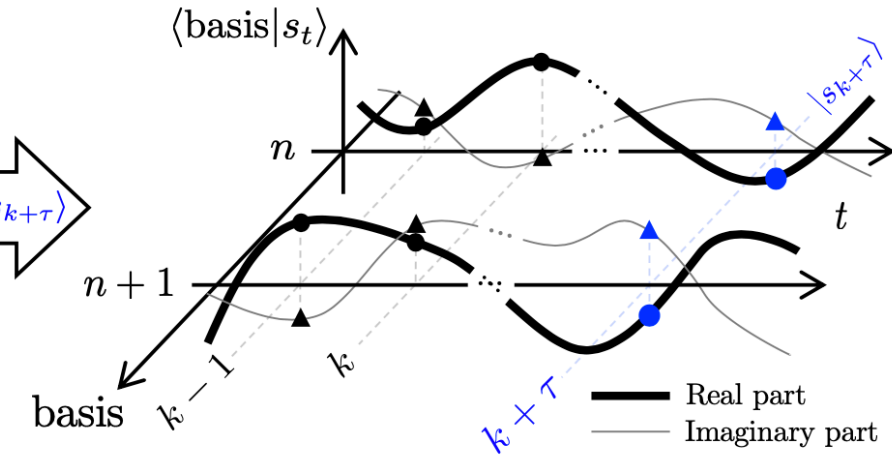
$$\begin{aligned} (|s_{k-1}\rangle, |s_k\rangle) &\rightarrow |o_k\rangle = |s_k\rangle \oplus |s_{k-1}\rangle \\ |o_k\rangle &\rightarrow |x_k\rangle = (|o_k\rangle \otimes |o_k\rangle) \oplus |o_k\rangle \end{aligned}$$

$$|x_k\rangle$$

Regularized  
Linear Layer  $W$

$$|s_{k+\tau}\rangle$$

Skipping-ahead dynamics



Training

$$W = Y X^\dagger (X X^\dagger + \lambda I)^{-1}$$

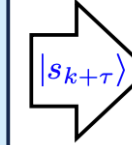
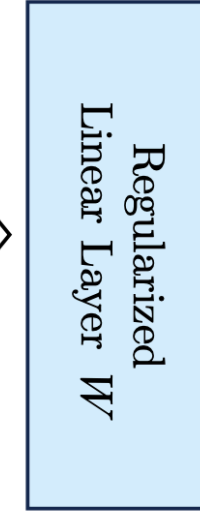
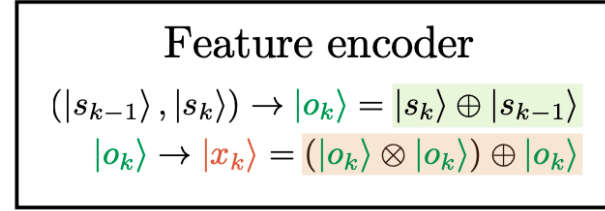
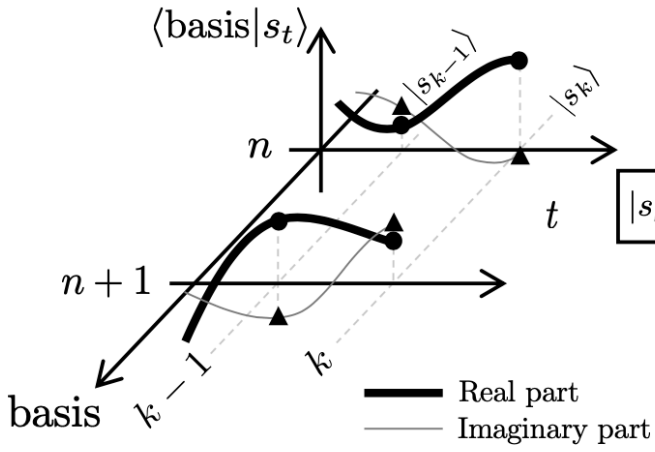
Skipping-ahead  
prediction

$$|s'_{k+\tau}\rangle = W |x_k\rangle = W \mathbf{r} (|s'_k\rangle, |s'_{k-1}\rangle)$$

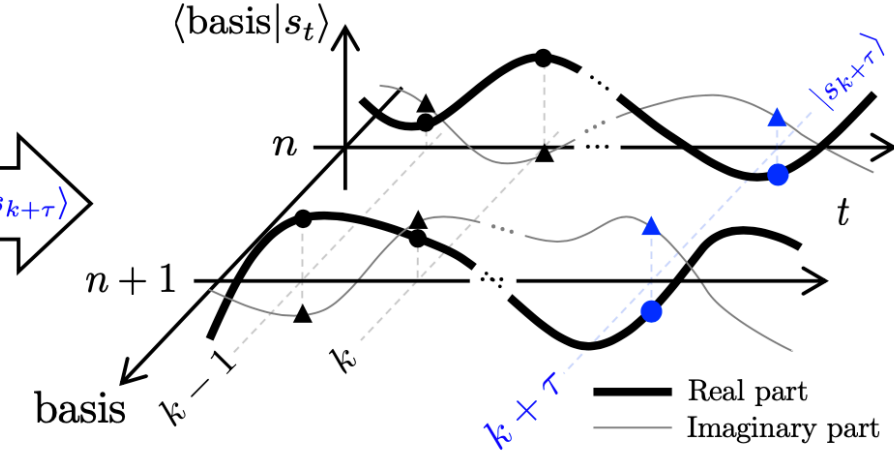


# Quantum Algorithm for NG-RC (QNG-RC)

Quantum dynamics



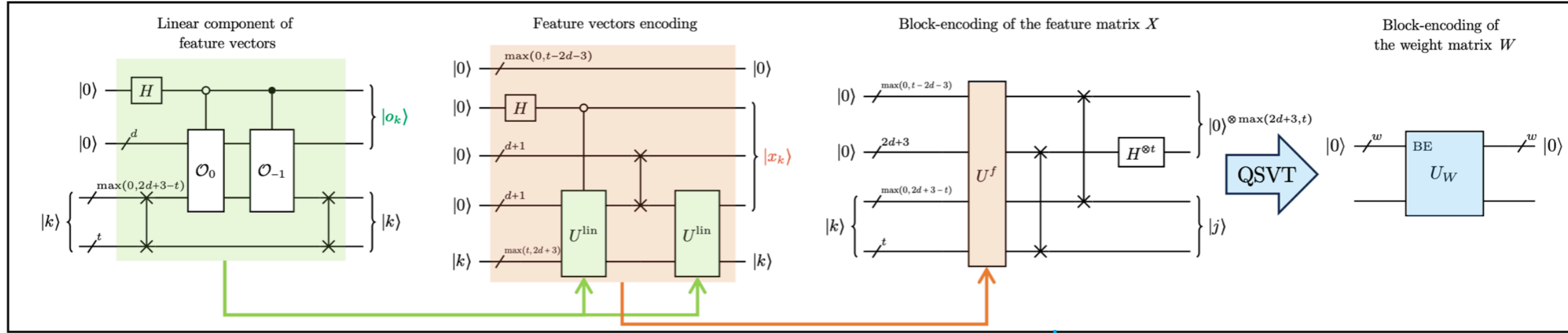
Skipping-ahead dynamics



Training

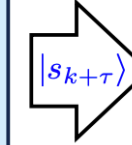
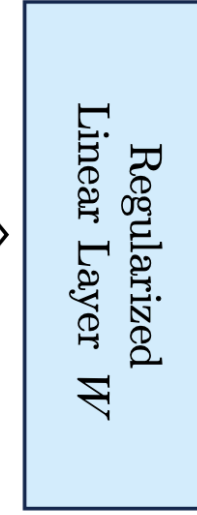
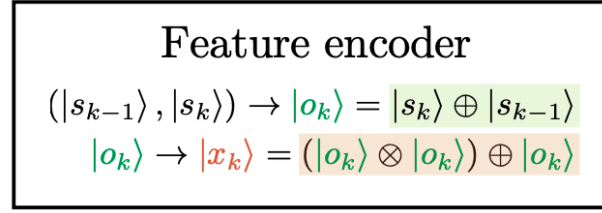
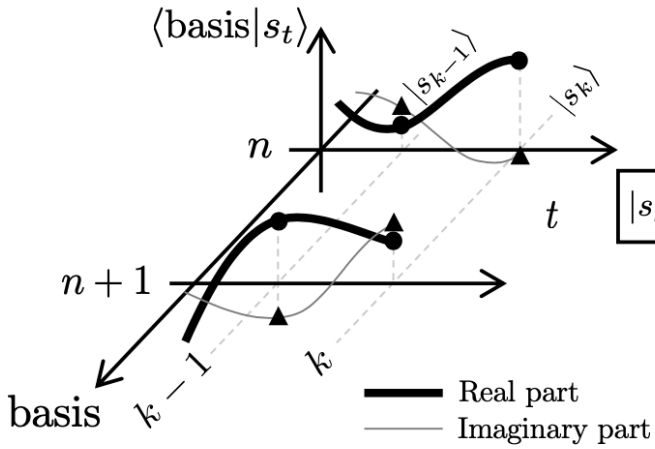
$$W = Y X^\dagger (X X^\dagger + \lambda I)^{-1}$$

Training phase

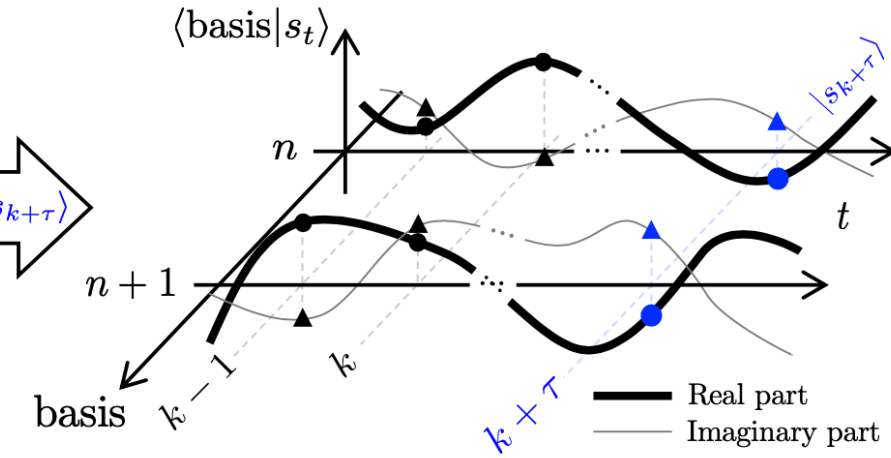


# Quantum Algorithm for NG-RC (QNG-RC)

Quantum dynamics



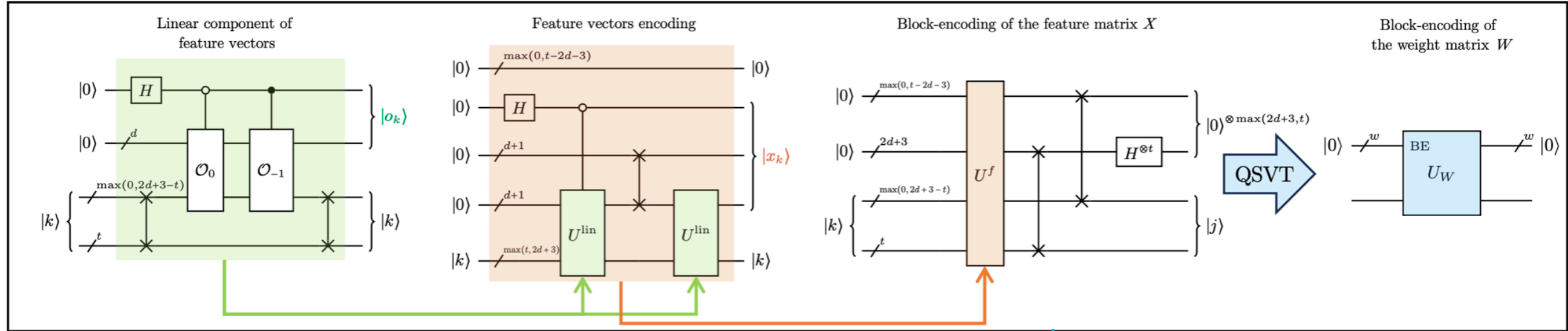
Skipping-ahead dynamics



Training

$$W = Y X^\dagger (X X^\dagger + \lambda I)^{-1}$$

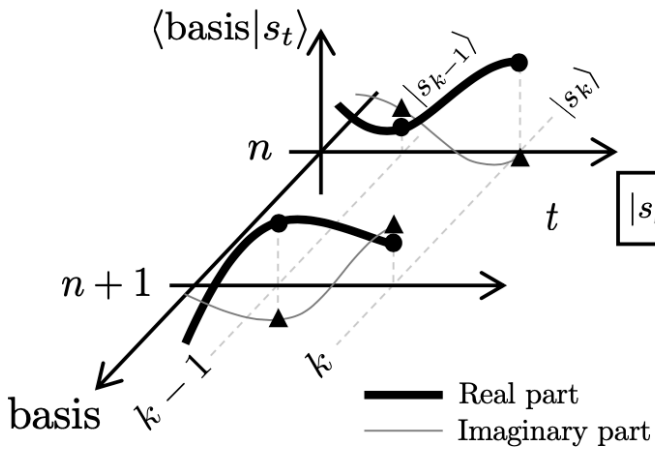
Training phase



**Theorem** Given the block-encoded feature matrix  $X$  and target matrix  $Y$ , constructed in time  $T_O$ , and  $\kappa$  being a condition number of the Tikhonov-regularized feature matrix  $\begin{pmatrix} X & \sqrt{\lambda}I \\ 0 & 0 \end{pmatrix}$ , then the block-encoding of  $W$ , with error  $\delta_W \in (0,1)$ , can be constructed in time  $T_W = O\left(d\kappa T \log\left(\frac{\kappa T}{\delta_W}\right) T_O\right)$  with  $O(d)$  number of qubits.

# Quantum Algorithm for NG-RC (QNG-RC)

Quantum dynamics



Feature encoder

$$(|s_{k-1}\rangle, |s_k\rangle) \rightarrow |o_k\rangle = |s_k\rangle \oplus |s_{k-1}\rangle$$

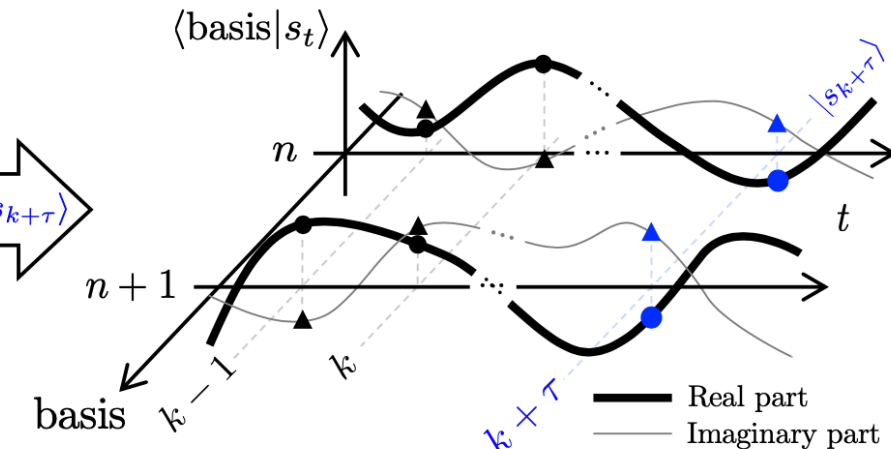
$$|o_k\rangle \rightarrow |x_k\rangle = (|o_k\rangle \otimes |o_k\rangle) \oplus |o_k\rangle$$

$$|x_k\rangle$$

Regularized  
Linear Layer  $W$

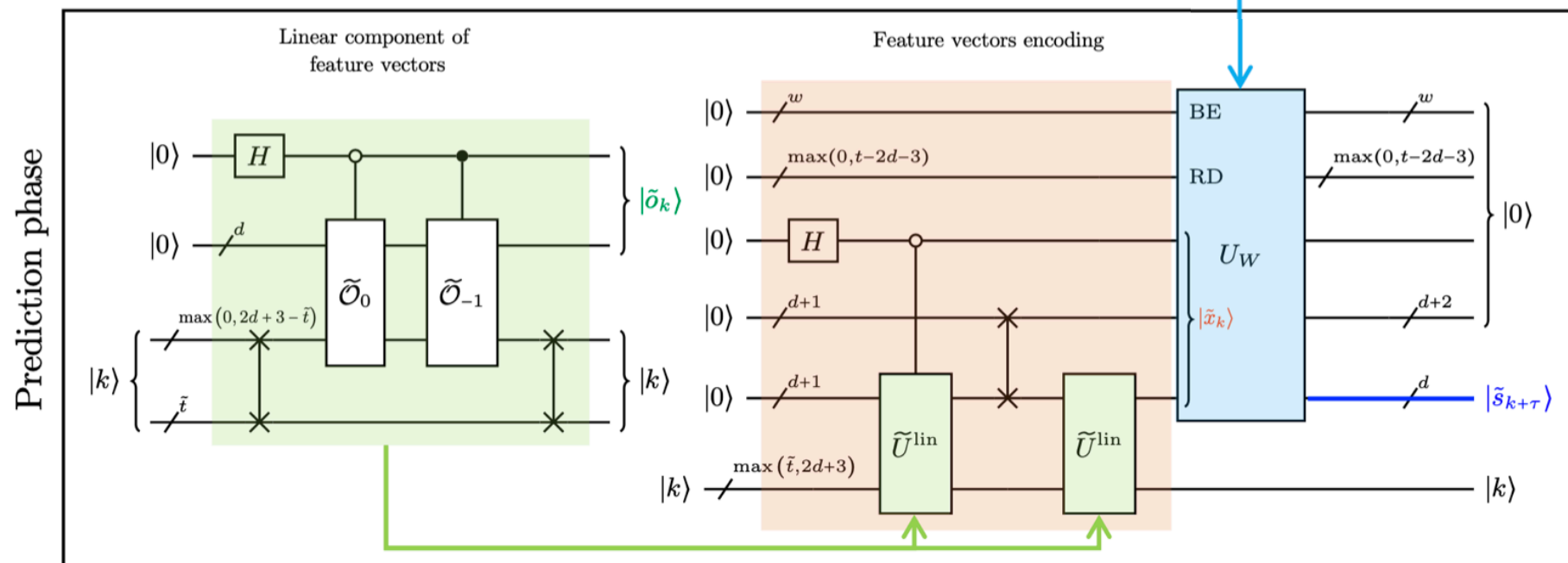
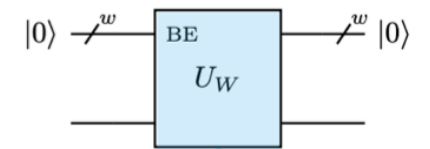
$$|s_{k+\tau}\rangle$$

Skipping-ahead dynamics



Skipping-ahead  
prediction

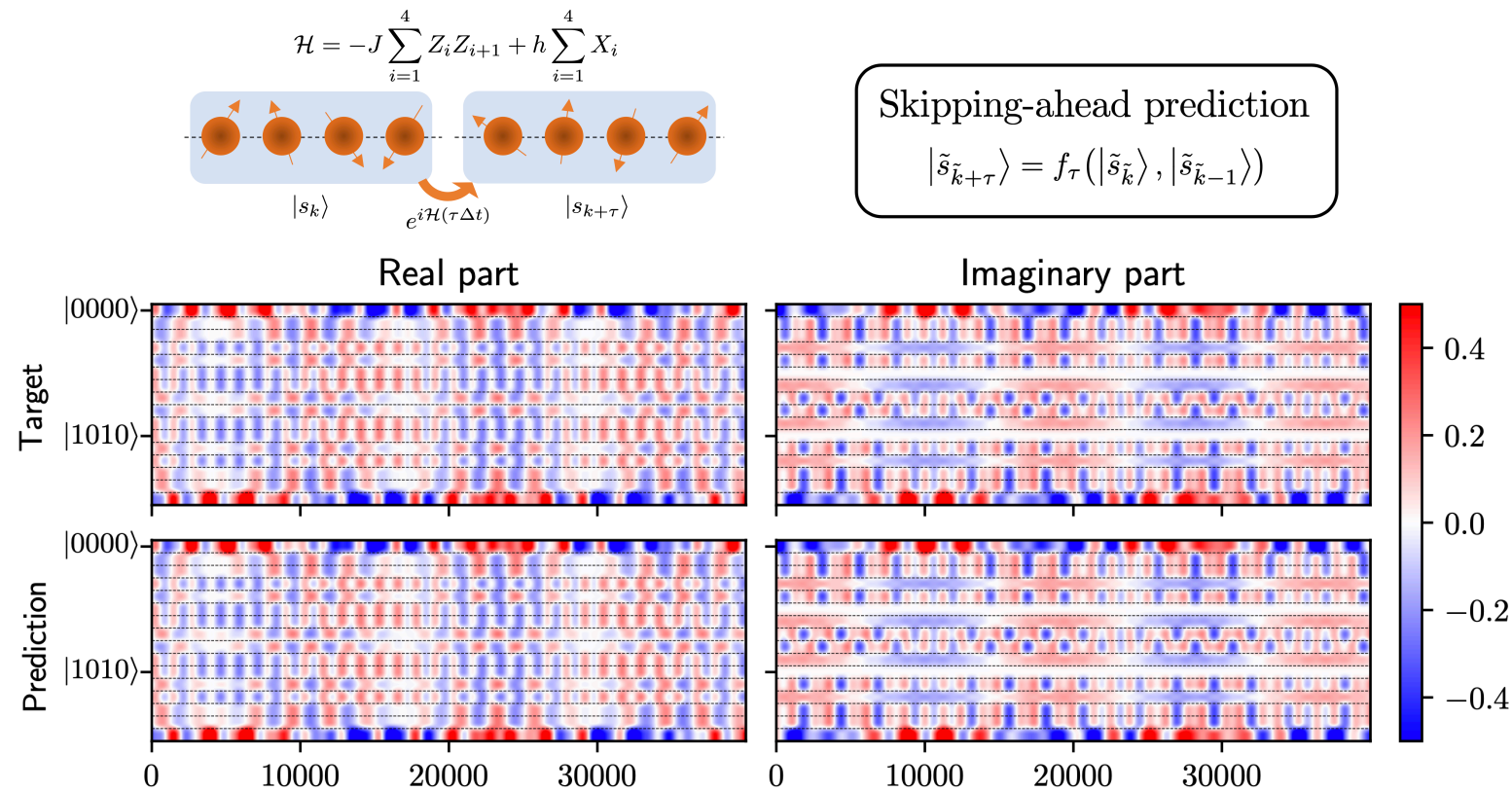
$$|s'_{k+\tau}\rangle = W|x_k\rangle = W\mathbf{r}(|s'_k\rangle, |s'_{k-1}\rangle)$$



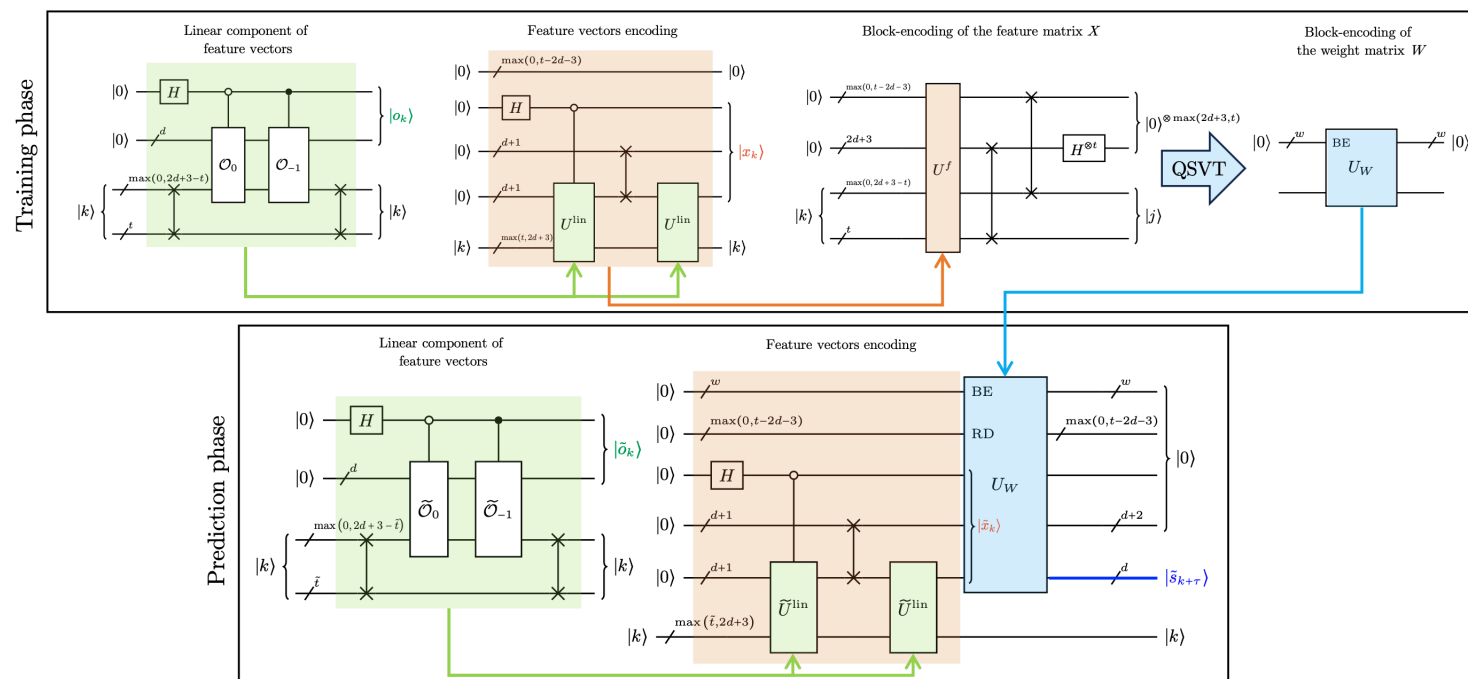
requires  
 $O(d)$  # of qubits

# Summary

1. NG-RC can be applied to forecast *full* many-body dynamics far into the future, but with the time cost that scales as  $O(2^{2d})$

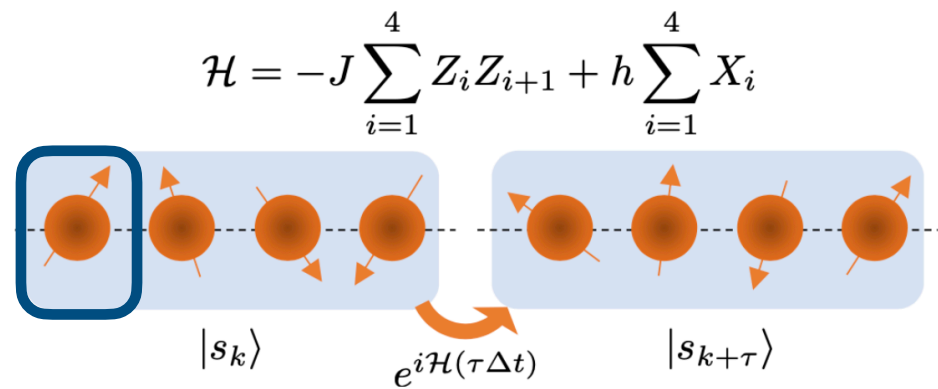


2. There is a quantum algorithm that performs skipping-ahead prediction coherently with the time cost and resource that scales as  $O(d)$



# Question Inspired by Experiments:

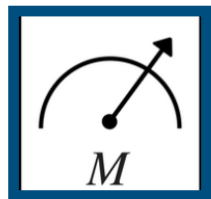
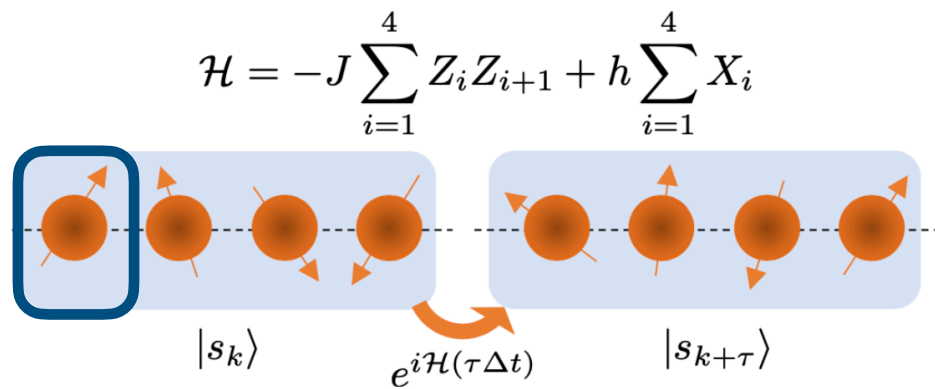
Can we measure *one* observable dynamics and reconstruct ALL the observables dynamics?





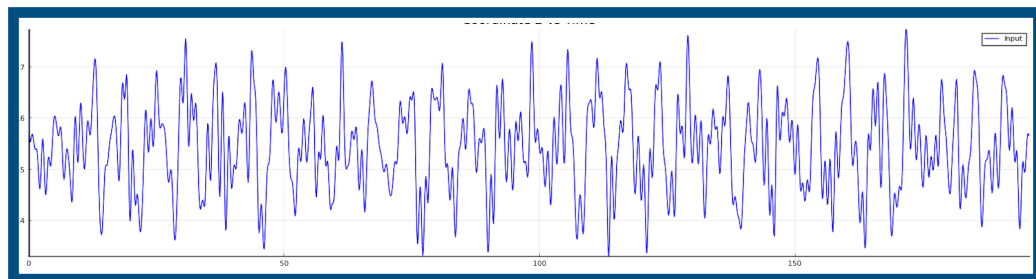
# Question Inspired by Experiments:

Can we measure *one* observable dynamics and reconstruct ALL the observables dynamics?



**Partial observation of the past**

$\langle X_1 \rangle$

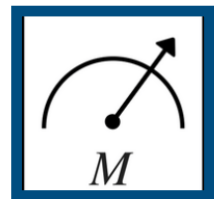
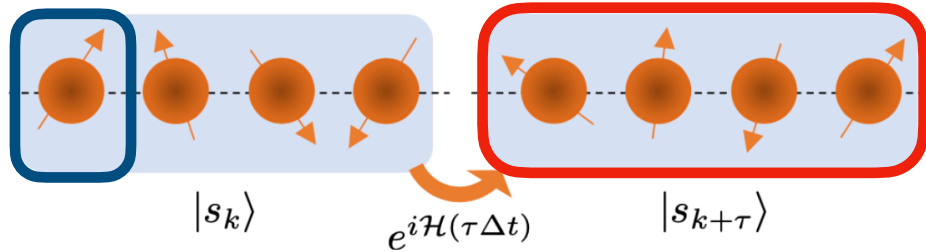


$t$

# Question Inspired by Experiments:

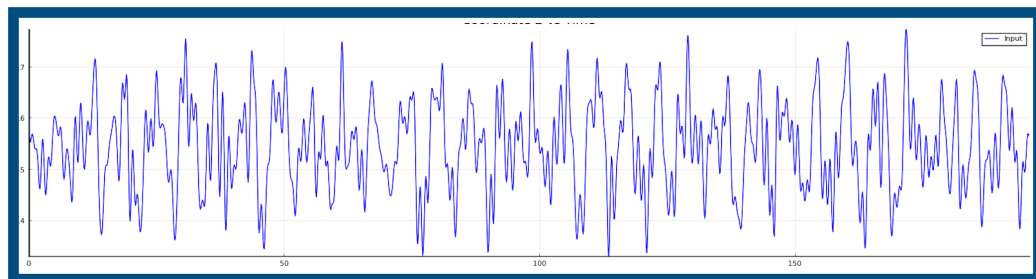
Can we measure *one* observable dynamics and reconstruct ALL the observables dynamics?

$$\mathcal{H} = -J \sum_{i=1}^4 Z_i Z_{i+1} + h \sum_{i=1}^4 X_i$$



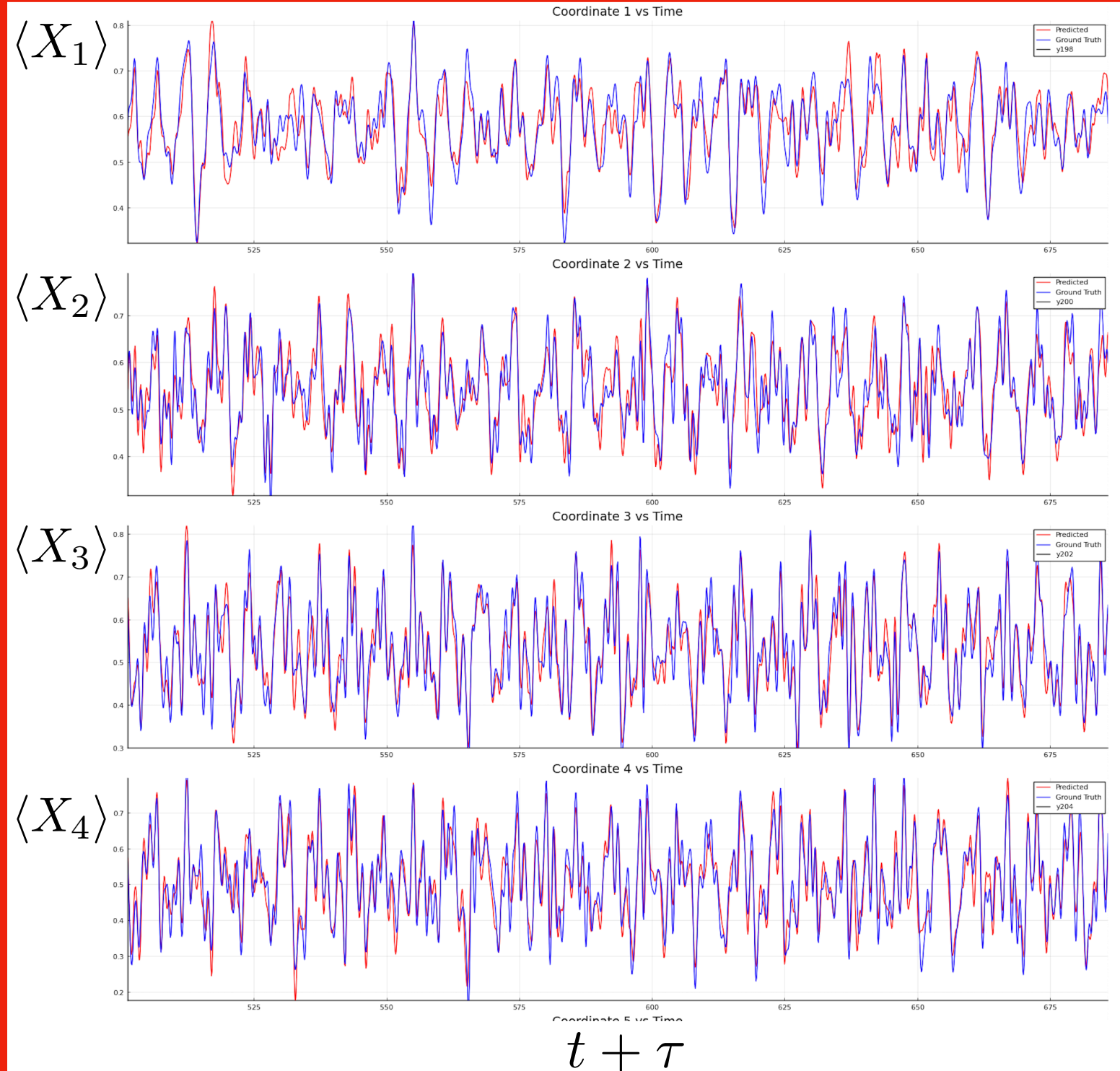
**Partial observation of the past**

$\langle X_1 \rangle$



$t$

**Reconstruction of ALL observables into the far future ( $\tau = 10^6$ )**



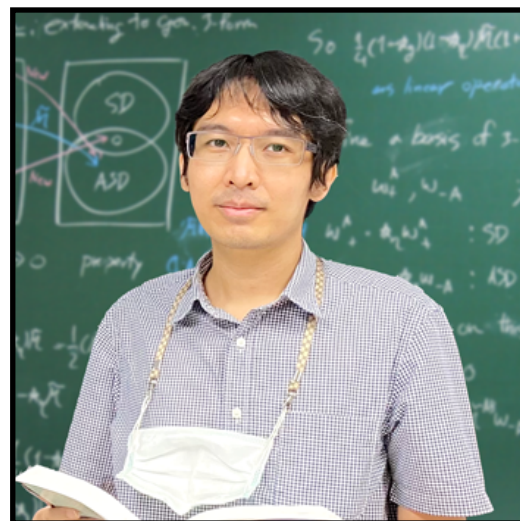
# Acknowledgement

Apimuk Sornsaeng



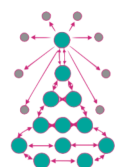
Chulalongkorn University  
Thailand

Ninnat Dangniam



Institute for Fundamental Study  
Thailand

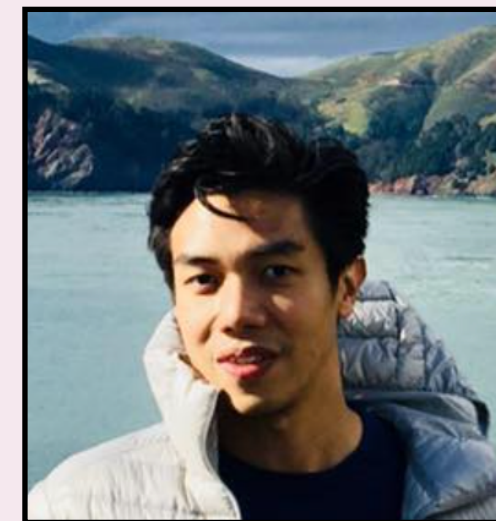
## Funding Acknowledgement



CHICS

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thiparatc@gmail.com



Lab website: [www.chics.ai](http://www.chics.ai)

# Benefits of Matrix Product States: Exponential Data Compression

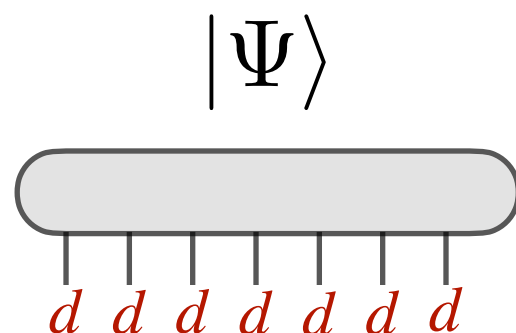
$$|\Psi\rangle = \sum_{d_1, d_2, \dots, d_N} c_{d_1, d_2, \dots, d_N} |d_1 \ d_2 \ \dots \ d_N\rangle$$

If the Hilbert space of each particle has dimension  $d$ , need to specify all  $d^N$  tensor coefficients.

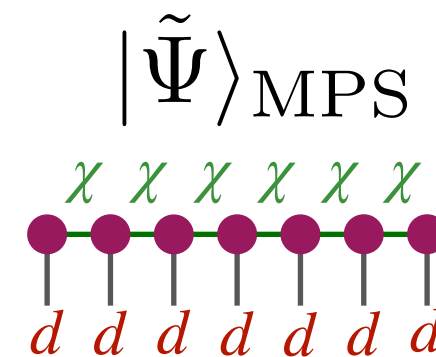
However, for a gapped 1D systems, a useful ansatz is the **MPS**

$$|\tilde{\Psi}\rangle_{\text{MPS}} \approx \sum_{\{\alpha\}} A_{d_1}^{\alpha_1} \dots A_{d_i}^{\alpha_{i-1} \alpha_i} \dots A_{d_N}^{\alpha_{N-1}} |d_1\rangle |d_2\rangle \dots |d_N\rangle$$

$\alpha_i$  denotes the interaction with particle  $i$  with an effective dimension  $\chi$ , called the **bond dimension**.



$\approx$



number of parameters

$d^N$

$N\chi^2 d$