## Submit problems 3 and 5 on Tuesday, 27 March.

1. Let  $A \subset \mathbb{R}^2$  be the rectangle  $[-1/2, 1/2] \times [0, 2\pi]$  and  $f : A \to \mathbb{R}^3$  be given by

$$f(s,t) = (t\cos(s/2) + 1)u(s) + t\sin(s/2)v$$

where  $u(s) = (\cos(s), \sin(s), 0)$  and v = (0, 0, 1). Show that M = f(A) is a manifold with boundary of dimension 2. What is  $\partial M$ ?

- 2. Consider the cylinder  $C = \{(x, y, z) \in \mathbb{R}^3 \mid x^2 + y^2 = 1, -1/2 \le z \le 1/2\}$ . Show that C is a manifold with boundary of dimension 2. What is  $\partial M$ ?
- 3. Let  $U \subset \mathbb{R}^n$  be open and  $f: U \to \mathbb{R}^k$  be a submersion. Let  $a \in f(U)$  and

$$M = \{x \in U \mid f(x) = a\}$$
.

- (a) Let  $p \in M$  and  $(V, \phi)$  a chart for M at p, such that  $\phi(x) = p$  for  $x \in V$ . Show that  $f_* \circ \phi_* : T_x \mathbb{R}^{n-k} \to T_a \mathbb{R}^k$  is the zero map of vector spaces.
- (b) Show that  $T_pM = \ker(f_*: T_p\mathbb{R}^n \to T_a\mathbb{R}^k)$ .
- 4. Let  $f : \mathbb{R}^2 \to \mathbb{R}$  be a  $\mathcal{C}^1$  function and  $\Gamma_f \subset \mathbb{R}^3$  be the graph of f as in problem 10 of assignment 9. Then  $\Gamma_f$  is a manifold.
  - (a) Find the tangent space to  $\Gamma_f$  at p = (0, 0, f(0, 0)).
  - (b) Now let  $f(x,y) = \frac{\cos(x^2 + y^2)}{1 + x^2 + y^2}$  graph this function and repeat part (a) for this function.
- 5. Consider the following primitive model for a solar system. A star is located at the origin O = (0, 0, 0), and is stationary. A planet P is revolving around the star at distance 10r (at constant speed) along the x-y plane. A satellite S of P is revolving around P at a distance r from P (with constant speed) and is always in the plane containing the z-axis and P. During one complete revolution of P, S revolves 10 times around P. Initially P is at (10r, 0, 0) and S at (11r, 0, 0).
  - (a) Show that the trajectory of S is a manifold of dimension 1 and give an atlas for it.
  - (b) Find the tangent spaces at the points where the three bodies are collinear.

## Multilinear Algebra.

Let V be a vector space and  $\mathfrak{T}^k(V)$  denote the space of k tensors over V.  $\Lambda^k(V) \subset \mathfrak{T}^k(V)$  is the subset of all alternating k tensors.

- 1. Show that  $\mathfrak{T}^k(V)$  forms a vector space and  $\Lambda^k(V)$  is a vector subspace.
- 2. Recall the tensor product; if  $S \in \mathfrak{T}^k(V)$  and  $T \in \mathfrak{T}^\ell(V)$  then  $S \otimes T \in \mathfrak{T}^{k+\ell}(V)$  is defined by

 $(S \otimes T)(v_1, \ldots, v_{k+\ell}) = S(v_1, \ldots, v_k)T(v_{k+1}, \ldots, v_{k+\ell}).$ 

Show that the tensor product satisfies the following properties:

- (a) (associativity)  $S \otimes (T \otimes U) = (S \otimes T) \otimes U;$
- (b) (distributivity)  $S \otimes (T_1 + T_2) = S \otimes T_1 + S \otimes T_2$  and  $(S_1 + S_2) \otimes T = S_1 \otimes T + S_2 \otimes T$ ;
- (c) (homogeneity)  $(cS) \otimes T = S \otimes (cT) = c(S \otimes T)$  for any  $c \in \mathbb{R}$ .

(d) Give an example where  $S \otimes T \neq T \otimes S$  (so commutativity fails).

Let the dimension of V be n and  $v_1, \ldots, v_n$  be a basis of V. If  $\phi_1, \ldots, \phi_n$  is the dual basis for  $V^* = \mathfrak{T}^1(V)$ . Then

$$\phi_{i_1} \otimes \cdots \otimes \phi_{i_k}, \quad 1 \le i_1, \dots, i_k \le n$$

is a basis for  $\mathfrak{T}^k(V)$ . Hence  $\mathfrak{T}^k(V)$  has dimension  $n^k$ .

3. Recall that a tensor  $T \in \mathfrak{T}^2(V)$  is called an inner product if T(v, w) = T(w, v) for all  $v, w \in V$  and T(v, v) > 0 for all  $v \in V$  and  $v \neq 0$ . Show that there is a basis  $v_1, \ldots, v_n$  of V such that

$$T(v_i, v_j) = \begin{cases} 1 & i = j, \\ 0 & \text{otherwise.} \end{cases}$$

Such a basis is called an orthonormal basis for T.

(a) Let  $w_1, \ldots, w_n$  be any basis of V. Define  $w'_1 = w_1, w'_2 = w_2 - \frac{T(w'_1, w_2)}{T(w'_1, w'_1)}w'_1$ ,

$$w'_{3} = w_{3} - \frac{T(w'_{1}, w_{3})}{T(w'_{1}, w'_{1})}w'_{1} - \frac{T(w'_{2}, w_{3})}{T(w'_{2}, w'_{2})}w'_{2} \text{ and so on. Then show that } T(w'_{i}, w'_{j}) = 0 \text{ if } i \neq j.$$

- (b) Let  $v_i = \frac{1}{\sqrt{T(w'_i, w'_i)}} w'_i$  then show that  $v_1, \ldots, v_n$  is an orthonormal basis for T.
- 4. Recall that if we have a linear transformation  $f: V \to W$  between vector spaces, then there is a map  $f^*: \mathfrak{T}^k(W) \to \mathfrak{T}^k(V)$ .
  - (a) Show that  $f^*$  is a linear transformation.
  - (b) Show that  $f^*\omega \in \Lambda^k(V)$  if  $\omega \in \Lambda^k(W)$ , So it gives a linear transformation  $f^* : \Lambda^k(W) \to \Lambda^k(V)$ . (Here there is a convenient abuse of notation.)
  - (c) If f is an isomorphism then show that  $f^*$  is also an isomorphism.
  - (d) If T is an inner product on V and  $v_1, \ldots, v_n$  and orthonormal basis for T, then define the linear transformation  $g: V \to \mathbb{R}^n$  given by  $g(v_i) = e_i$  where  $e_1, \ldots, e_n$  is the standard basis of  $\mathbb{R}^n$ . Show that  $T = f^* \langle , \rangle$ , where  $\langle , \rangle$  is the standard inner product on  $\mathbb{R}^n$ .
- 5. Recall that Alt :  $\mathfrak{T}^k(V) \to \mathfrak{T}^k(V)$  defined as follows, if  $T \in \mathfrak{T}^k(V)$  the tensor Alt(T) does the following

Alt 
$$T(v_1, \ldots, v_k) = \frac{1}{k!} \sum_{\sigma \in S_k} \operatorname{sgn}(\sigma) T(v_{\sigma(1)}, \ldots, v_{\sigma(k)}).$$

Show the following:

- (a)  $Alt(T) \in \Lambda^k(V)$ . (Hint. Composing a 2-cycle with a permutation changes the sign of the permutation.)
- (b)  $Alt(\omega) = \omega$  if  $\omega \in \Lambda^k(V)$ . (Hint. Show that all the summands of Alt are the same.)
- 6. If  $\omega \in \Lambda^k(V)$  and  $\eta \in \Lambda^\ell(V)$  then their wedge product is defined as follows

$$\omega \wedge \eta = \frac{(k+\ell)!}{k!\ell!} \operatorname{Alt}(\omega \otimes \eta)$$

Show that the wedge product satisfies the following properties: (a)  $\omega \wedge \eta = (-1)^{k\ell} \eta \wedge \omega$  (graded commutativity);

(b)  $\omega \wedge (\eta_1 + \eta_2) = \omega \wedge \eta_1 + \omega \wedge \eta_2$  and  $(\omega_1 + \omega_2) \wedge \eta = \omega_1 \wedge \eta + \omega_2 \wedge \eta$  (distributivity);

(c)  $(a\omega) \wedge \eta = \omega \wedge (a\eta) = a(\omega \wedge \eta)$  for any  $a \in \mathbb{R}$  (homogeneity);

The wedge product also satisfies associativity but it is a bit harder to prove. Refer to Theorem 4-4 on page 80 of Spivak.

Let the dimension of V be n and  $v_1, \ldots, v_n$  be a basis of V. If  $\phi_1, \ldots, \phi_n$  is the dual basis for  $V^* = \Lambda^1(V)$ . Then

$$\phi_{i_1} \wedge \dots \wedge \phi_{i_k}, \quad 1 \le i_1 < \dots < i_k \le n$$

is a basis for  $\mathfrak{T}^k(V)$ . Hence  $\mathfrak{T}^k(V)$  has dimension  $\binom{n}{k}$ . In particular  $\Lambda^n(V)$  is 1-dimensional and  $\Lambda^k(V)$  is trivial if k > n.

7. Prove the following for the wedge product:

(a) If  $\phi \Lambda^1(V)$  then  $\phi \wedge \phi = 0$ . (Hint. Use problem 6 (a).)

(b) If  $\phi_1, \ldots, \phi_k \in \Lambda^1(V)$  then

$$\phi_1 \wedge \ldots \wedge \phi_k = \sum_{\sigma \in S_k} \operatorname{sgn}(\sigma) \phi_{\sigma(1)} \otimes \cdots \otimes \phi_{\sigma(n)}$$

Recall that any non-zero element  $\omega$  of  $\Lambda^n(V)$  gives an orientation of V. If  $v_1, \ldots, v_n$  is a (ordered) basis of V then it is positively oriented if  $\omega(v_1, \ldots, v_n) > 0$  otherwise it is negatively oriented.

- 8. If  $\omega \in \Lambda^n(V)$  is non-zero then  $\omega(v_1, \ldots, v_n) \neq 0$  if and only if  $v_1, \ldots, v_n$  is a basis of V.
- 9. If  $e_1, \ldots, e_n$  is the standard basis of  $\mathbb{R}^n$  and  $\phi_1, \ldots, \phi_n$  is the dual basis of  $\Lambda^1(\mathbb{R}^n)$ , show that det =  $\phi_1 \wedge \ldots \wedge \phi_n$ , where det  $\in \Lambda^n(\mathbb{R}^n)$  is the determinant.
- 10. det is the standard orientation of  $\mathbb{R}^n$ . Show that for  $\mathbb{R}^2$  and  $\mathbb{R}^3$  it gives the same definition of orientation that we have in physics.
  - (a) If  $v_1, v_2$  is a orthornormal basis of  $\mathbb{R}^2$  (with respect to the standard inner product on  $\mathbb{R}^n$ ), then it is positively oriented if  $v_1$  has to be rotated by an angle of  $\pi/2$  in counter-clockwise direction to get  $v_2$ .
  - (b) If  $v_1, v_2, v_3$  is an orthonormal basis for  $\mathbb{R}^3$ , then it is positively oriented if it satisfies the right hand cork screw rule. (Hint. Use the cross product.)
  - (c) Notice that ordering of the basis elements is quite crucial for its orientation.  $e_1, e_2$  is a positively oriented basis of  $\mathbb{R}^2$  where as  $e_2, e_1$  is negatively oriented. Show that in general  $e_1, \ldots, e_n$  is always positively oriented basis for  $\mathbb{R}^n$  with respect to the standard orientation, and  $e_{\sigma(1)}, \ldots, e_{\sigma(n)}$  is positively oriented if  $\sigma \in S_n$  is an even permutation.