

# Parameterized Distributed Algorithms\*

R. Krithika

Indian Institute of Technology Palakkad

Recent Trends in Algorithms

National Institute of Science Education and Research

Based on the manuscript titled Parameterized Distributed Algorithms by Ran Ben-Basat, Ken-ichi Kawarabayashi, Gregory Schwartzman [arXiv:1807.04900]

# Parameterized Algorithms

- \* Multidimensional analysis of the running time
  - \* Effect of secondary measurements on complexity
  - \* NP-hard problem: Exponential factor in running time is restricted to a **parameter** instead of input size

Instance: A graph  $G$  on  $n$  vertices and integer  $k$   
Question: Does  $G$  have a solution of size  $k$ ?

Parameter:  $k$

Design  $f(k)$  poly( $n$ ) algorithm

$2^{O(k^2)}$  poly( $n$ )       $2^{O(k \log k)}$  poly( $n$ )

fixed-parameter tractable (FPT)  
or  
parameterized algorithm

# Parameterized Algorithms

- \* Multidimensional analysis of the running time
  - \* Effect of secondary measurements on complexity
  - \* NP-hard problem: Exponential factor in running time is restricted to a **parameter** instead of input size

Instance: A graph  $G$  on  $n$  vertices and integer  $k$   
Question: Does  $G$  have a solution of size  $k$ ?

Parameter:  $k$

Design  $f(k)$  poly( $n$ ) algorithm

$2^{O(k^2)}$  poly( $n$ )       $2^{O(k \log k)}$  poly( $n$ )

fixed-parameter tractable (FPT)  
or  
parameterized algorithm

Model of Computation: Single Processor

# Distributed Algorithms

# Distributed Algorithms

- \* A network (graph) of  $n$  processors (nodes) perform computation

# Distributed Algorithms

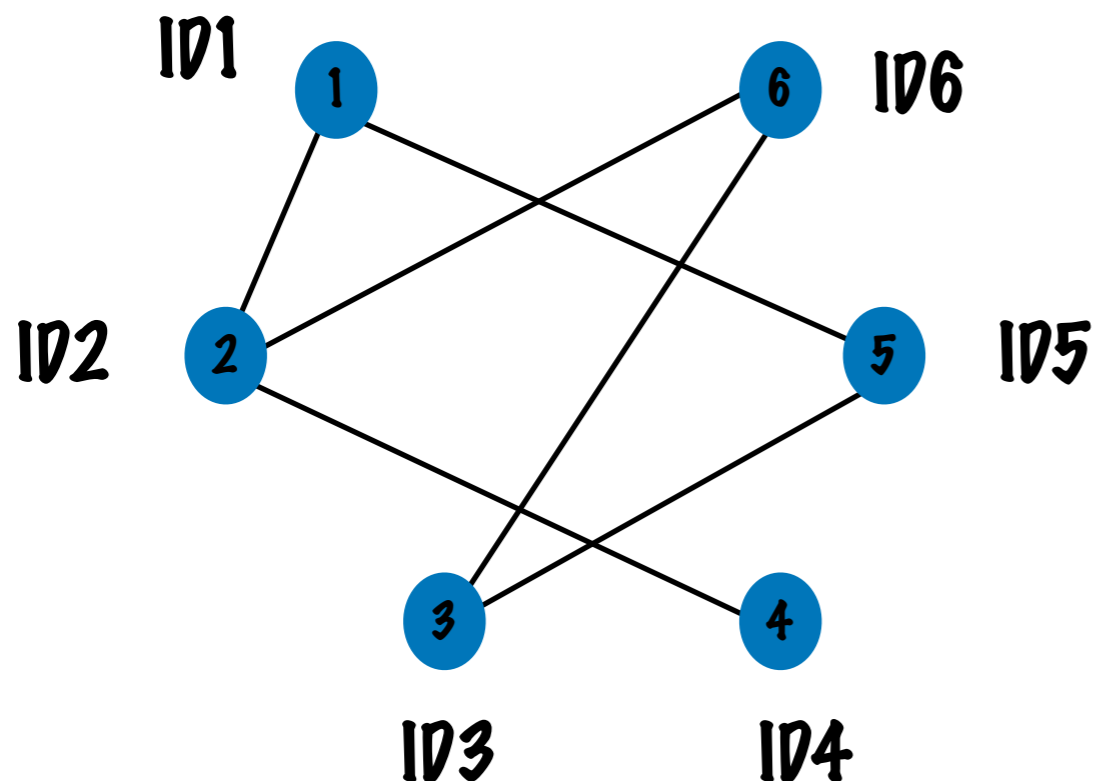
- \* A network (graph) of  $n$  processors (nodes) perform computation
  - \* Each node has an **identifier** ( $O(\log n)$  bits) and **local information** (neighbours)

# Distributed Algorithms

- \* A network (graph) of  $n$  processors (nodes) perform computation
- \* Each node has an **identifier** ( $O(\log n)$  bits) and **local information** (neighbours)
  - \* Each node knows about its incident edges and may not know anything about the ids of its neighbours

# Distributed Algorithms

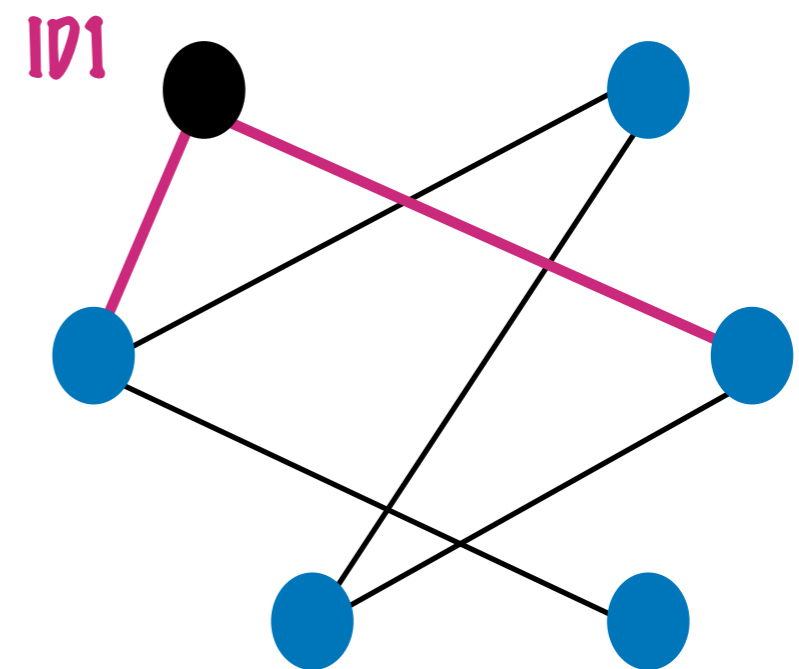
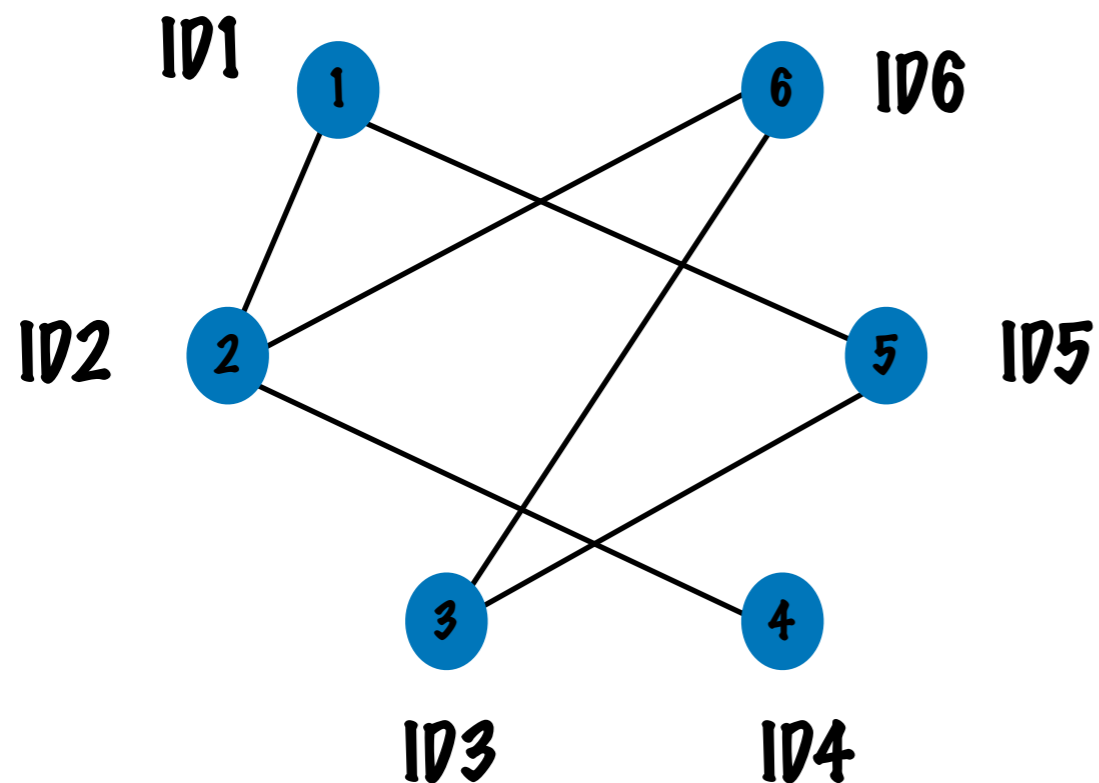
- \* A network (graph) of  $n$  processors (nodes) perform computation
  - \* Each node has an **identifier** ( $O(\log n)$  bits) and **local information** (neighbours)
    - \* Each node knows about its incident edges and may not know anything about the ids of its neighbours





# Distributed Algorithms

- \* A network (graph) of  $n$  processors (nodes) perform computation
  - \* Each node has an **identifier** ( $O(\log n)$  bits) and **local information** (neighbours)
    - \* Each node knows about its incident edges and may not know anything about the ids of its neighbours

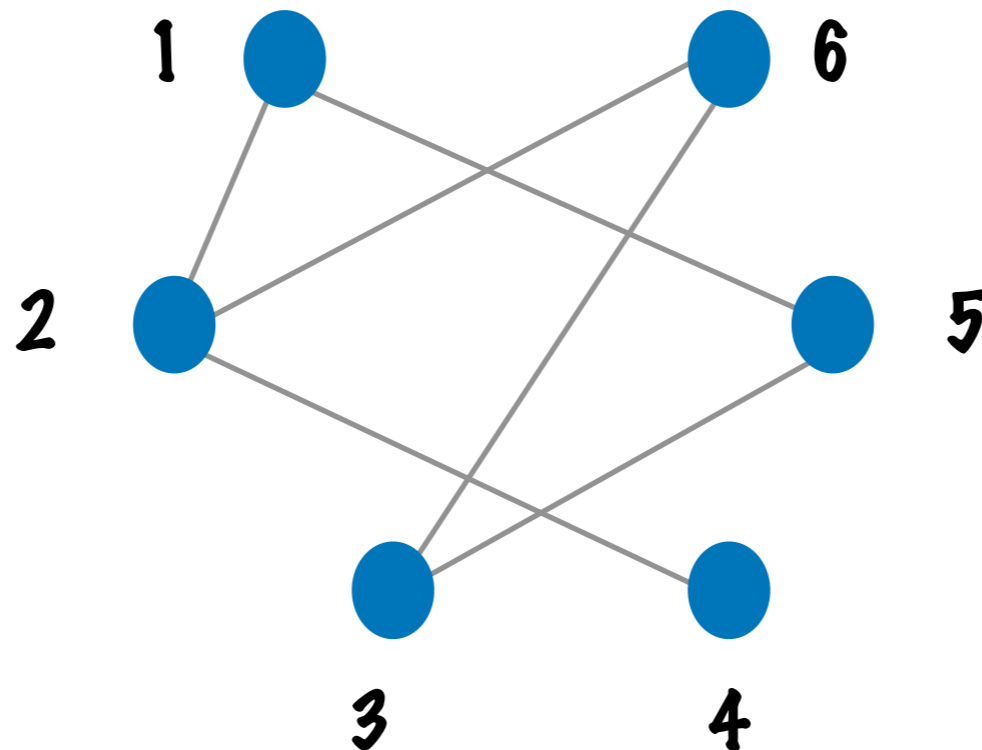


# Distributed Algorithms

- \* Nodes communicate by exchanging messages
- \* Computation proceeds in **synchronous** rounds - time steps partitioned into discrete rounds
- \* Running time: **no. of communication rounds**

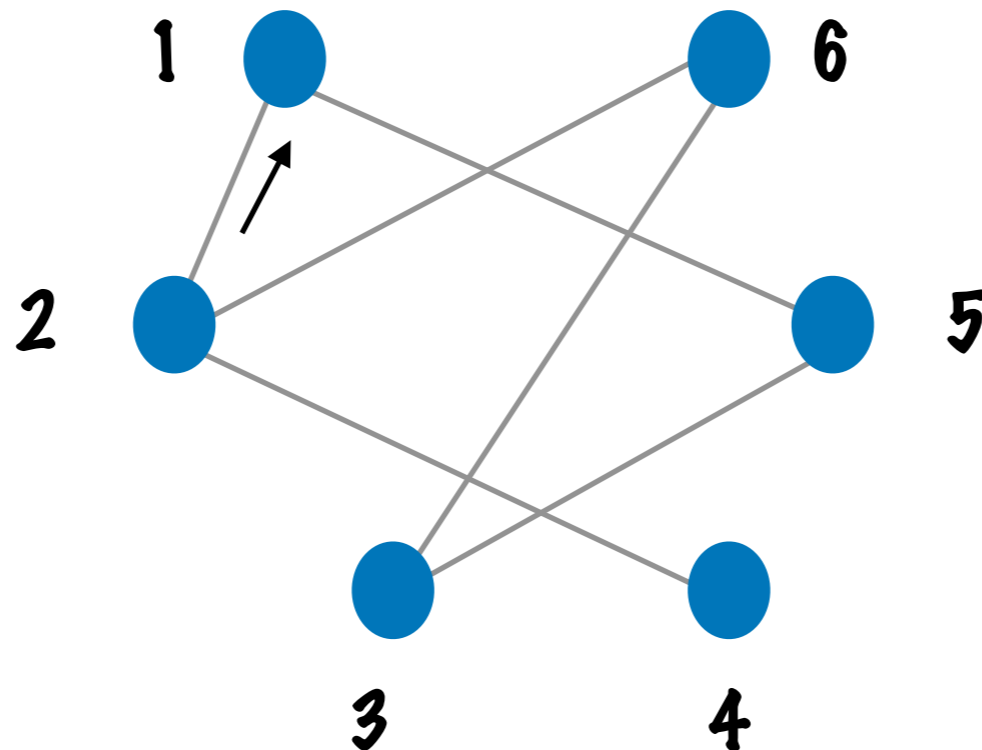
# Distributed Algorithms

- \* Nodes communicate by exchanging messages
- \* Computation proceeds in **synchronous** rounds - time steps partitioned into discrete rounds
- \* Running time: **no. of communication rounds**



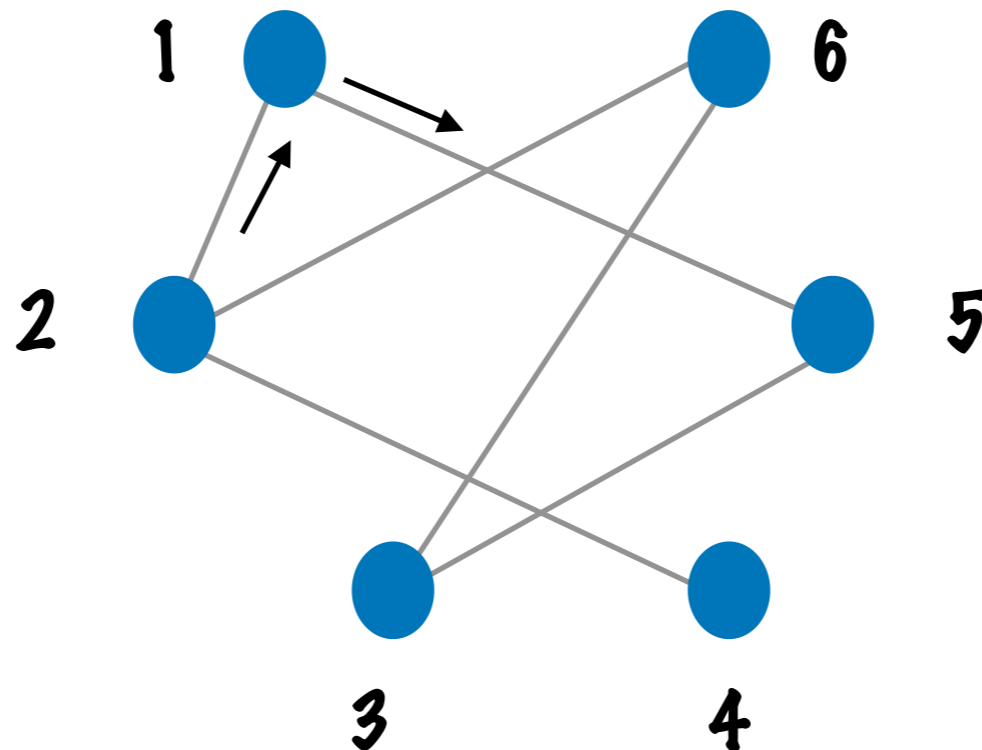
# Distributed Algorithms

- \* Nodes communicate by exchanging messages
- \* Computation proceeds in **synchronous** rounds - time steps partitioned into discrete rounds
- \* Running time: **no. of communication rounds**



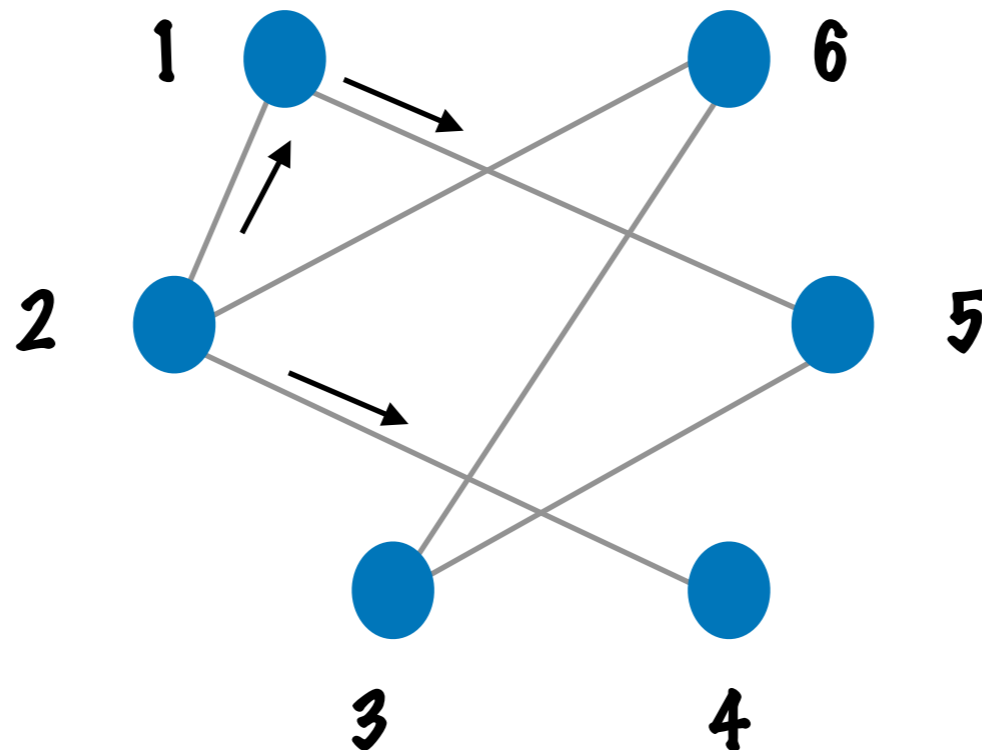
# Distributed Algorithms

- \* Nodes communicate by exchanging messages
- \* Computation proceeds in **synchronous** rounds - time steps partitioned into discrete rounds
- \* Running time: **no. of communication rounds**



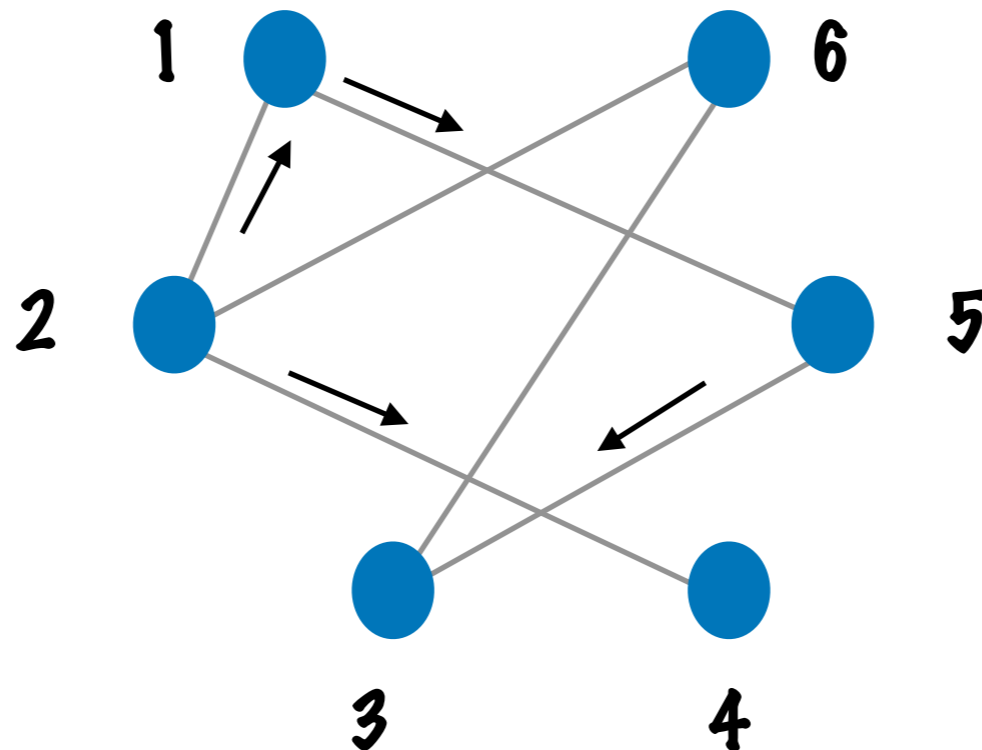
# Distributed Algorithms

- \* Nodes communicate by exchanging messages
- \* Computation proceeds in **synchronous** rounds - time steps partitioned into discrete rounds
- \* Running time: **no. of communication rounds**



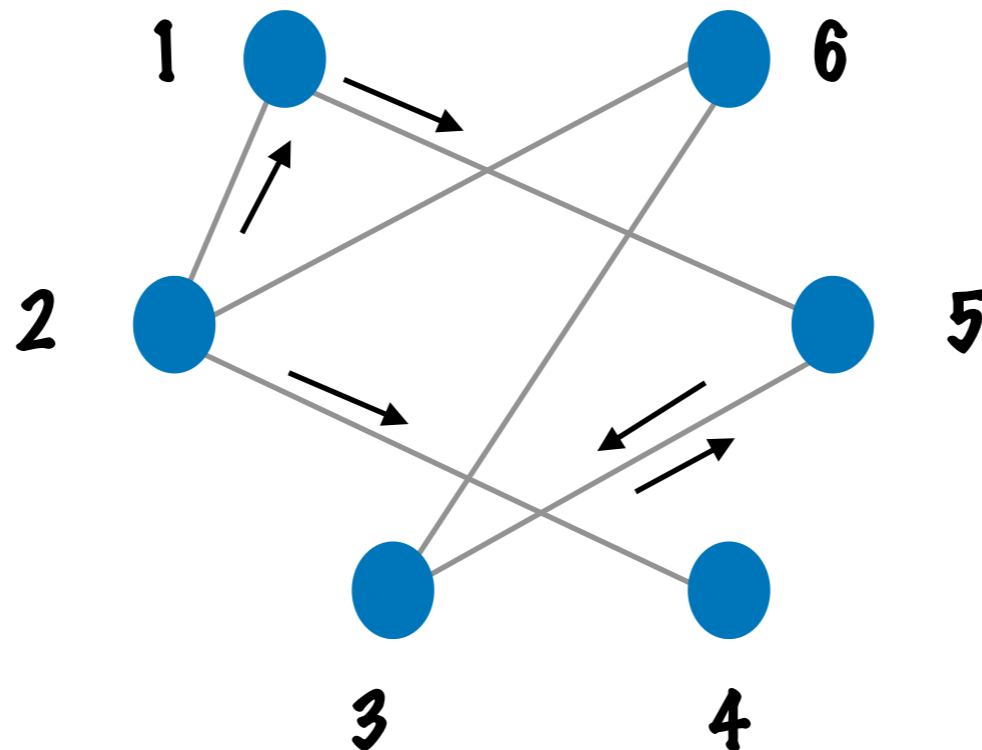
# Distributed Algorithms

- \* Nodes communicate by exchanging messages
- \* Computation proceeds in **synchronous** rounds - time steps partitioned into discrete rounds
- \* Running time: **no. of communication rounds**



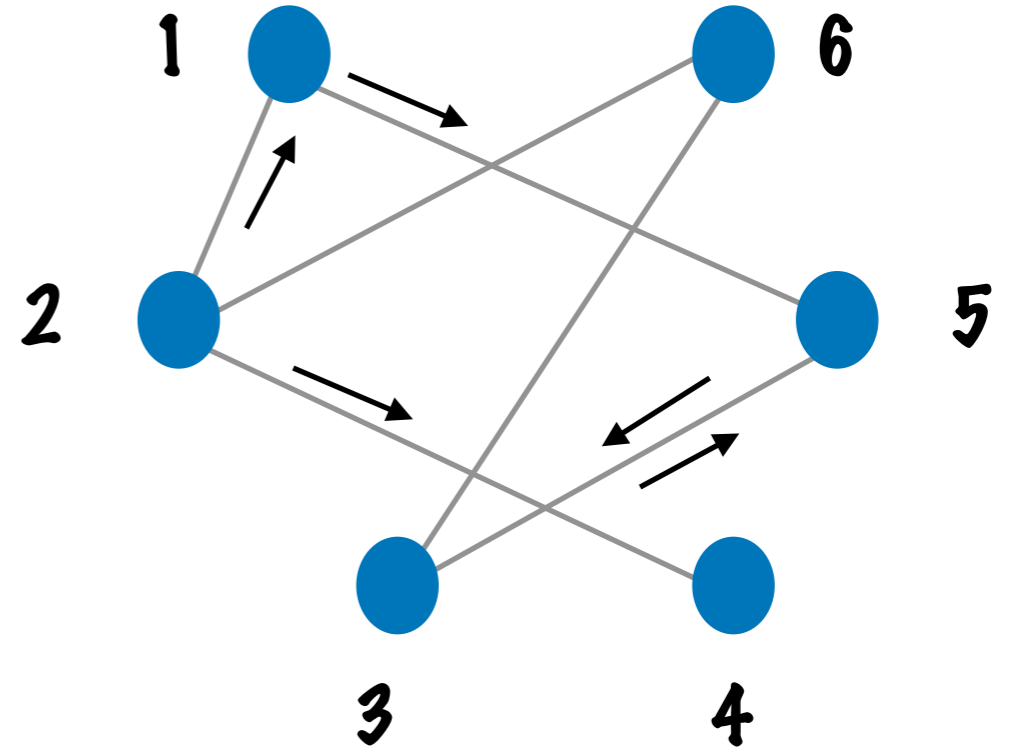
# Distributed Algorithms

- \* Nodes communicate by exchanging messages
- \* Computation proceeds in **synchronous** rounds - time steps partitioned into discrete rounds
- \* Running time: **no. of communication rounds**



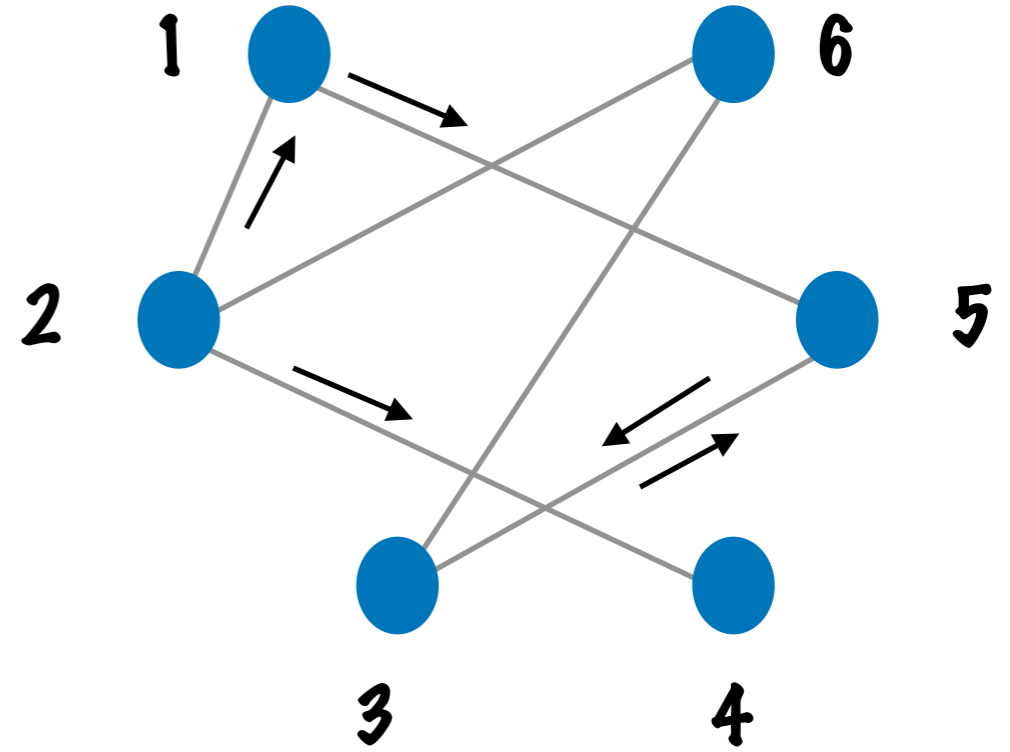


# Distributed Algorithms



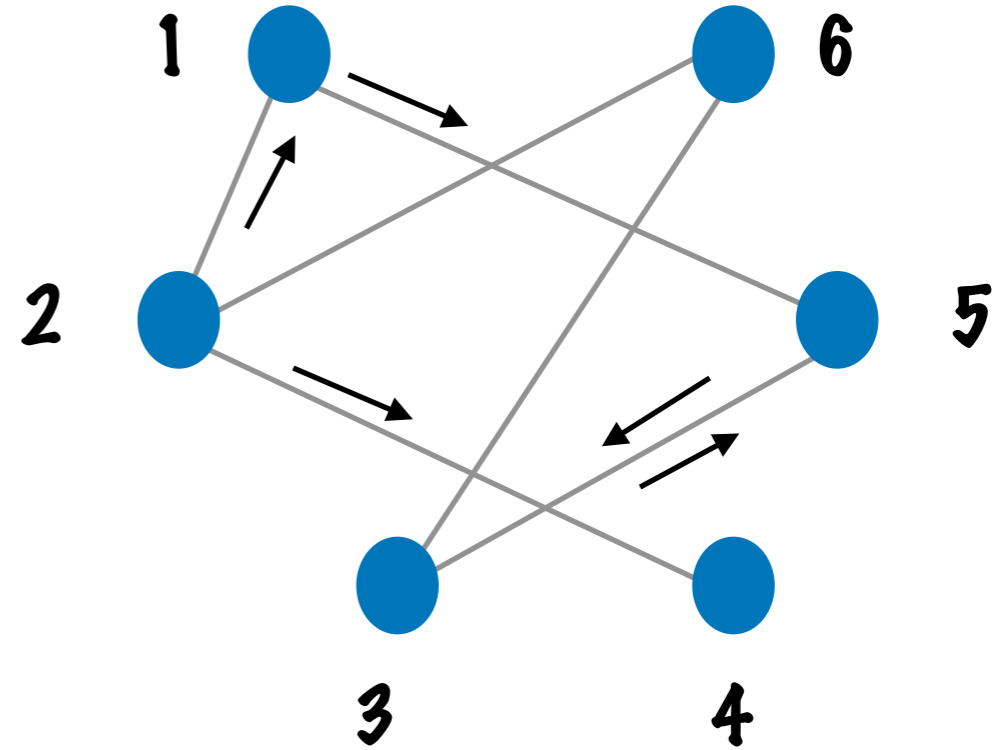
# Distributed Algorithms

- \* In one round, each vertex



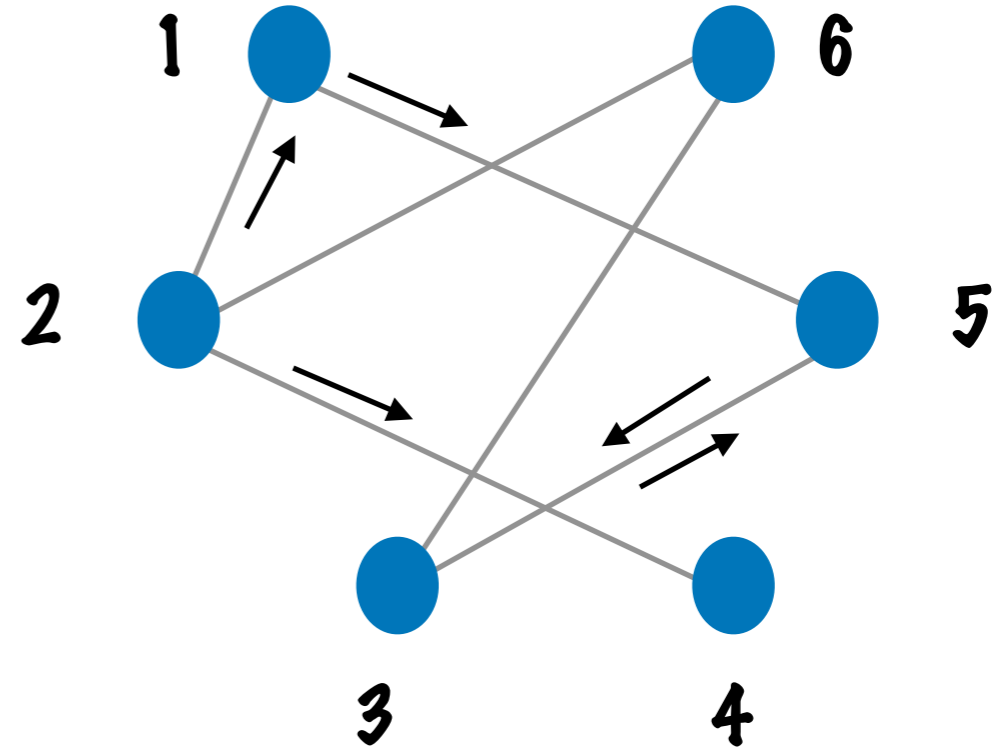
# Distributed Algorithms

- \* In one round, each vertex
- \* Computes



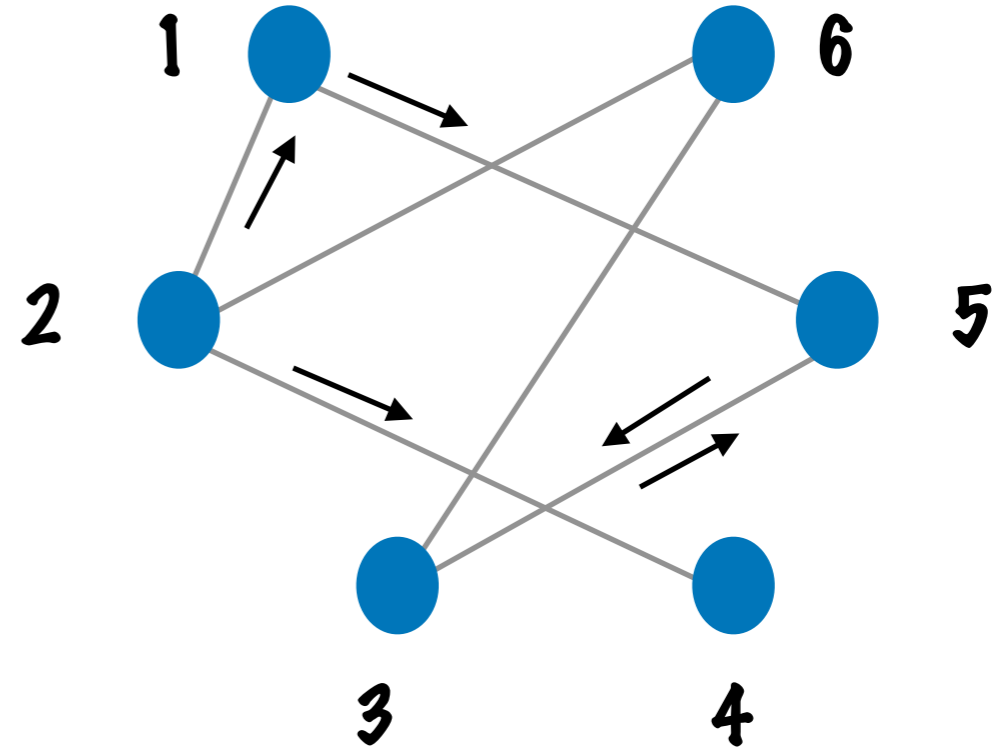
# Distributed Algorithms

- \* In one round, each vertex
- \* Computes
- \* Local computation is **unlimited**



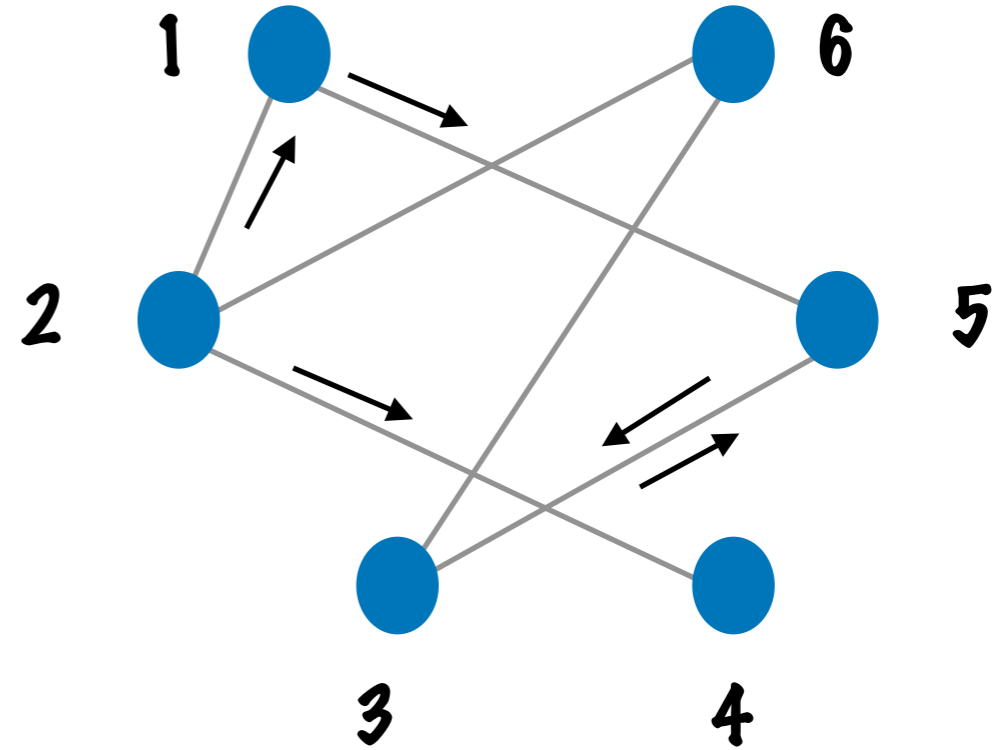
# Distributed Algorithms

- \* In one round, each vertex
  - \* Computes
    - \* Local computation is **unlimited**
  - \* Sends/receives messages



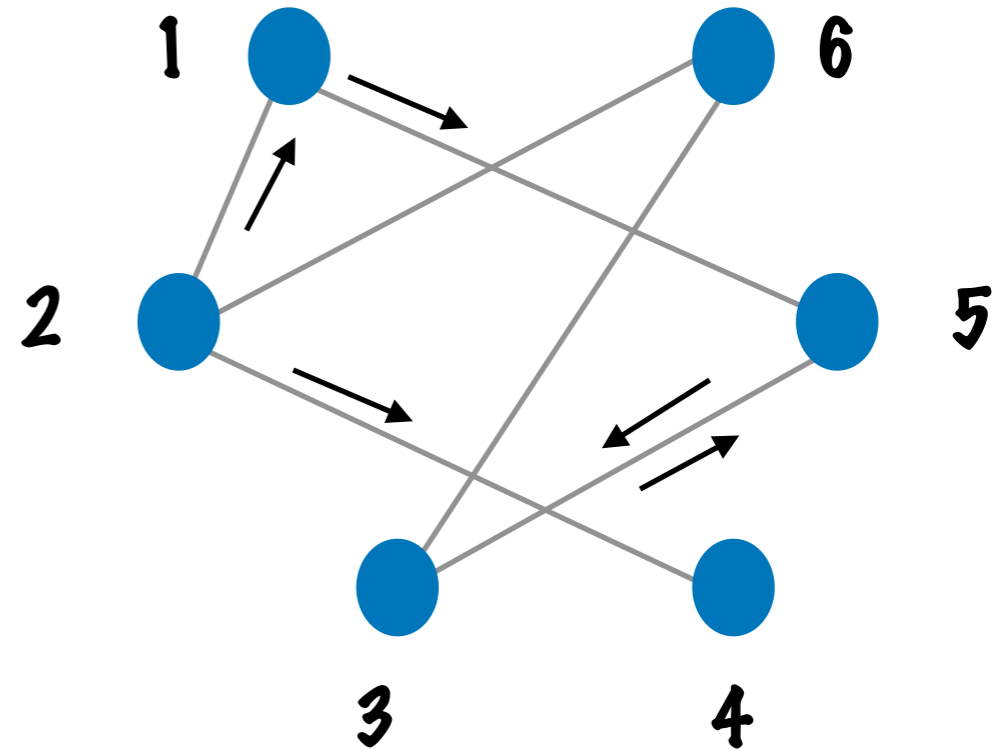
# Distributed Algorithms

- \* In one round, each vertex
  - \* Computes
    - \* Local computation is **unlimited**
  - \* Sends/receives messages
    - \* Msg sent to a nbr is assumed to be at the beginning of the round and is received by the nbr at the end of the same round with **no delay**



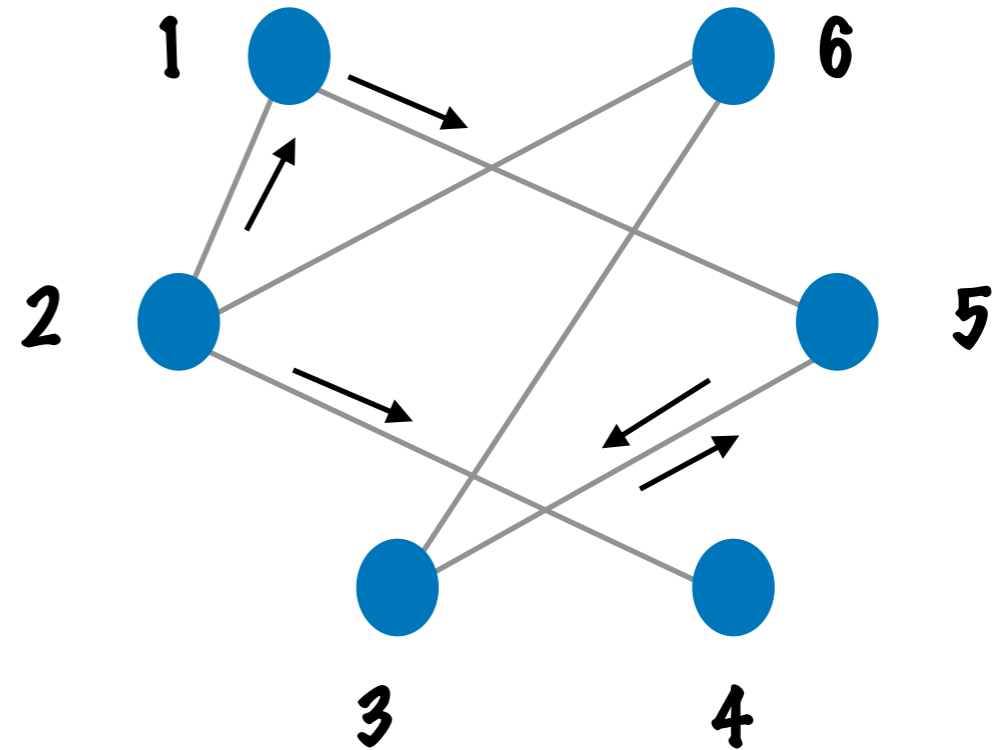
# Distributed Algorithms

- \* In one round, each vertex
  - \* Computes
    - \* Local computation is **unlimited**
  - \* Sends/receives messages
    - \* Msg sent to a nbr is assumed to be at the beginning of the round and is received by the nbr at the end of the same round with **no delay**
- \* **LOCAL** - **no bound on msg size**



# Distributed Algorithms

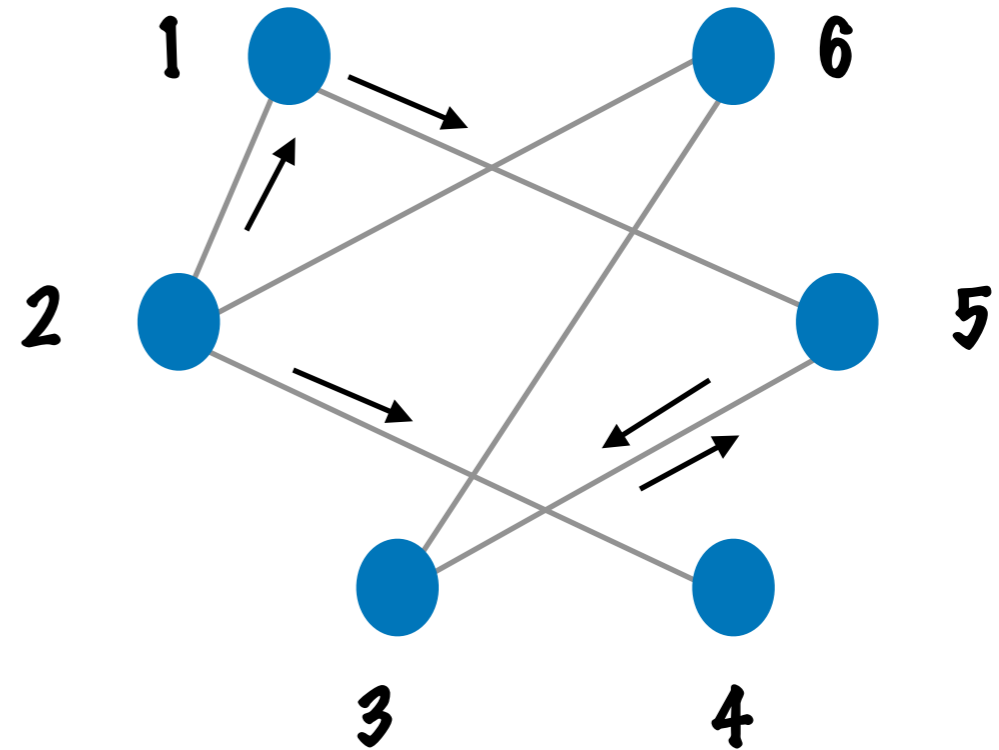
- \* In one round, each vertex
  - \* Computes
    - \* Local computation is **unlimited**
  - \* Sends/receives messages
    - \* Msg sent to a nbr is assumed to be at the beginning of the round and is received by the nbr at the end of the same round with **no delay**
- \* **LOCAL** - **no bound on msg size**
- \* **CONGEST** - **each msg is  $O(\log n)$  bits**





# Distributed Algorithms

- \* In one round, each vertex
  - \* Computes
    - \* Local computation is **unlimited**
  - \* Sends/receives messages
    - \* Msg sent to a nbr is assumed to be at the beginning of the round and is received by the nbr at the end of the same round with **no delay**
- \* LOCAL - **no bound on msg size**
- \* CONGEST - **each msg is  $O(\log n)$  bits**
  - \* Only  $O(\log n)$  sized message can be sent per edge per time step



**Broadcast**

**BFS Tree**

**Leader Election**

**Learning the Network**

# Broadcast

Given a network  $G$  and a vertex  $v$ , send a message from  $v$  to all nodes

# BFS Tree

# Leader Election

# Learning the Network

# Broadcast

Given a network  $G$  and a vertex  $v$ , send a message from  $v$  to all nodes

# BFS Tree

Construct a BFS tree of  $G$  rooted at a particular vertex  $s$

# Leader Election

# Learning the Network

# Broadcast

Given a network  $G$  and a vertex  $v$ , send a message from  $v$  to all nodes

# BFS Tree

Construct a BFS tree of  $G$  rooted at a particular vertex  $s$

# Leader Election

Elect an unique leader of the entire network

# Learning the Network

# Broadcast

Given a network  $G$  and a vertex  $v$ , send a message from  $v$  to all nodes

# BFS Tree

Construct a BFS tree of  $G$  rooted at a particular vertex  $s$

# Leader Election

Elect an unique leader of the entire network

# Learning the Network

Have all nodes learn the entire graph

# Broadcast

Given a network  $G$  and a vertex  $v$ , send a message from  $v$  to all nodes

CONGEST:  $O(\text{dia})$  rounds

# BFS Tree

Construct a BFS tree of  $G$  rooted at a particular vertex  $s$

CONGEST:  $O(\text{dia})$  rounds

# Leader Election

Elect an unique leader of the entire network

CONGEST:  $O(\text{dia})$  rounds

# Learning the Network

Have all nodes learn the entire graph

# Broadcast

Given a network  $G$  and a vertex  $v$ , send a message from  $v$  to all nodes

**CONGEST:**  $O(\text{dia})$  rounds

# BFS Tree

Construct a BFS tree of  $G$  rooted at a particular vertex  $s$

**CONGEST:**  $O(\text{dia})$  rounds

# Leader Election

Elect an unique leader of the entire network

**CONGEST:**  $O(\text{dia})$  rounds

# Learning the Network

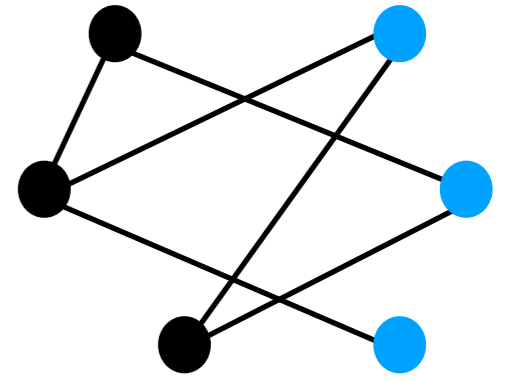
Have all nodes learn the entire graph

**CONGEST:**  $O(m)$  rounds

**LOCAL:**  $O(\text{dia})$  rounds



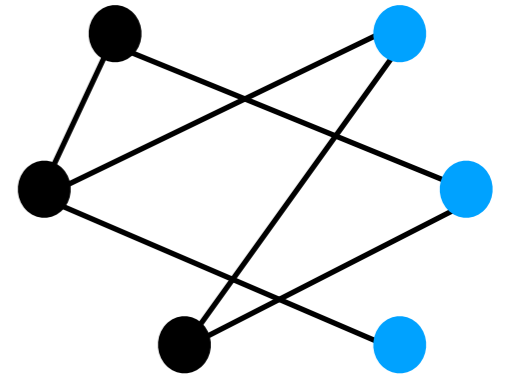
# Distributed Vertex Cover



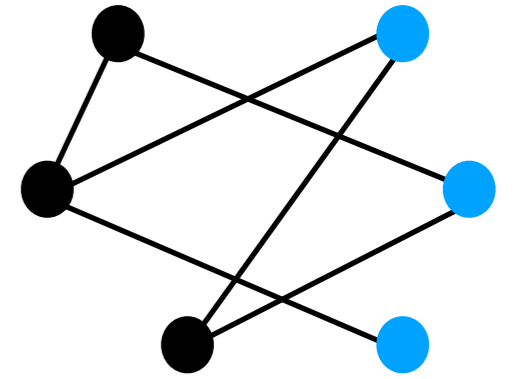
# Distributed Vertex Cover

**Input:** Graph  $G$  on  $n$  vertices  $m$  edges

**Question:** Find a minimum sized set  $S$  of vertices such that for each edge  $(u,v)$ , either  $u$  is in  $S$  or  $v$  is in  $S$



# Distributed Vertex Cover

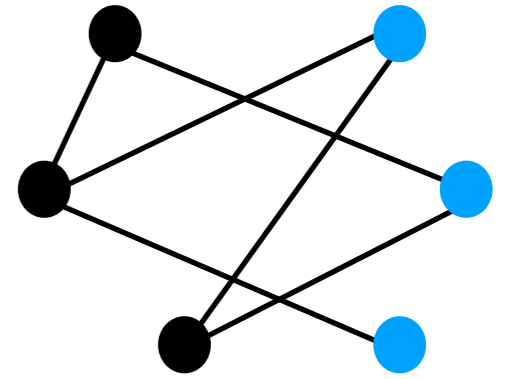


**Input:** Graph  $G$  on  $n$  vertices  $m$  edges

**Question:** Find a minimum sized set  $S$  of vertices such that for each edge  $(u,v)$ , either  $u$  is in  $S$  or  $v$  is in  $S$

- \* **Communication graph** is same as the graph on which the vertex cover is required
- \* At the end of the computation **each vertex knows if it is in the solution or not**

# Distributed Vertex Cover



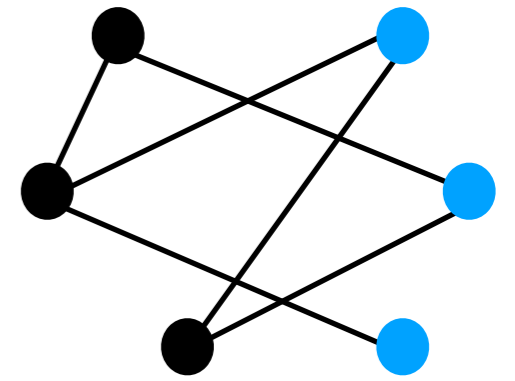
**Input:** Graph  $G$  on  $n$  vertices  $m$  edges

**Question:** Find a minimum sized set  $S$  of vertices such that for each edge  $(u,v)$ , either  $u$  is in  $S$  or  $v$  is in  $S$

- \* **Communication graph** is same as the graph on which the vertex cover is required
- \* At the end of the computation **each vertex knows if it is in the solution or not**

**An easy algorithm:** have the leader learn the entire graph

# Distributed Vertex Cover



**Input:** Graph  $G$  on  $n$  vertices  $m$  edges

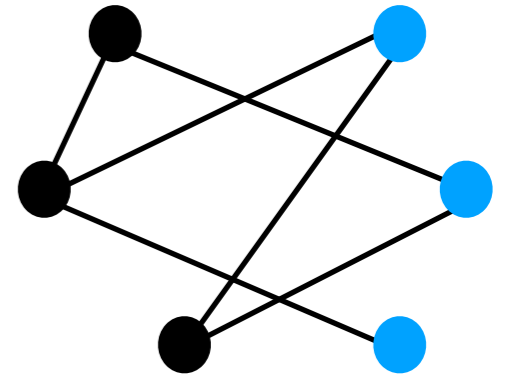
**Question:** Find a minimum sized set  $S$  of vertices such that for each edge  $(u,v)$ , either  $u$  is in  $S$  or  $v$  is in  $S$

- \* **Communication graph** is same as the graph on which the vertex cover is required
- \* At the end of the computation **each vertex knows if it is in the solution or not**

An easy algorithm: **have the leader learn the entire graph**

**LOCAL:**  $O(\text{diam})$  rounds **CONGEST:**  $O(m)$  rounds

# Distributed Vertex Cover



Input: Graph  $G$  on  $n$  vertices  $m$  edges

Question: Find a minimum sized set  $S$  of vertices such that for each edge  $(u,v)$ , either  $u$  is in  $S$  or  $v$  is in  $S$

- \* **Communication graph** is same as the graph on which the vertex cover is required
- \* At the end of the computation **each vertex knows if it is in the solution or not**

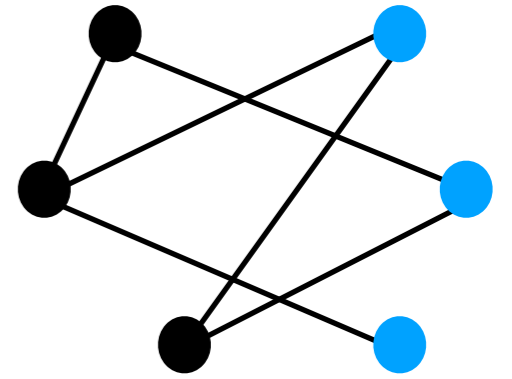
An easy algorithm: **have the leader learn the entire graph**

**LOCAL:**  $O(\text{diam})$  rounds **CONGEST:**  $O(m)$  rounds

## Lower Bounds

- \*  $\Omega(n^2/\log^2 n)$  rounds to compute min vertex cover in CONGEST [Censor-Hillel et al. 17]
- \*  $\Omega(\min \{(\log n / \log \log n)^{1/2}, \log \Delta / \log \log \Delta\})$  to compute constant factor approx. to min vertex cover in LOCAL [Kuhn et al. 16]

# Parameterized Distributed Vertex Cover

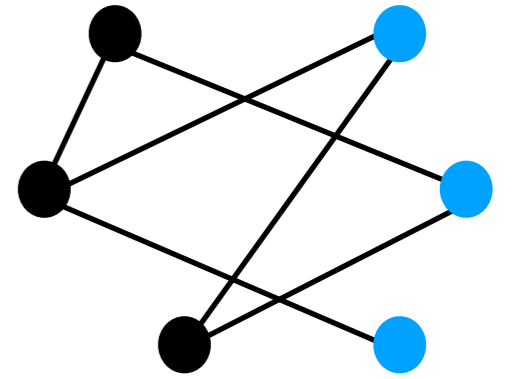


Input: Graph  $G$  and positive integer  $k$

Question: Does  $G$  have a set  $S$  of at most  $k$  vertices such that for each edge  $(u,v)$ , either  $u$  is in  $S$  or  $v$  is in  $S$

- \* **Communication graph** is same as the graph on which the vertex cover is required
- \* At the end of the computation
  - \* **NO instance:** Each vertex knows that no  $k$ -solution exists
  - \* **YES instance:** Each vertex knows if it is in the  $k$ -solution or not
    - \*  $\text{flag}(v) = 1$  if  $v$  is in the solution
    - \*  $\text{flag}(v) = 0$  if  $v$  is not in the solution

# Parameterized Distributed Vertex Cover



Input: Graph  $G$  and positive integer  $k$

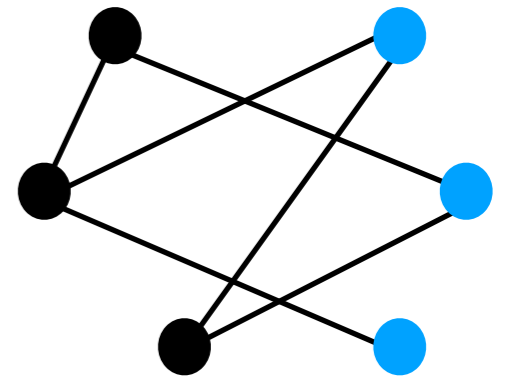
Parameter:  $k$

Question: Does  $G$  have a set  $S$  of at most  $k$  vertices such that for each edge  $(u,v)$ , either  $u$  is in  $S$  or  $v$  is in  $S$

- \* **Communication graph** is same as the graph on which the vertex cover is required
- \* At the end of the computation
  - \* **NO instance:** Each vertex knows that no  $k$ -solution exists
  - \* **YES instance:** Each vertex knows if it is in the  $k$ -solution or not
    - \*  $\text{flag}(v) = 1$  if  $v$  is in the solution
    - \*  $\text{flag}(v) = 0$  if  $v$  is not in the solution



# Parameterized Distributed Vertex Cover



Input: Graph  $G$  and positive integer  $k$

Parameter:  $k$

Question: Does  $G$  have a set  $S$  of at most  $k$  vertices such that for each edge  $(u,v)$ , either  $u$  is in  $S$  or  $v$  is in  $S$

- \* **Communication graph** is same as the graph on which the vertex cover is required
- \* At the end of the computation
  - \* **NO instance:** Each vertex knows that no  $k$ -solution exists
  - \* **YES instance:** Each vertex knows if it is in the  $k$ -solution or not
    - \*  $\text{flag}(v) = 1$  if  $v$  is in the solution
    - \*  $\text{flag}(v) = 0$  if  $v$  is not in the solution

Goal:  $O(f(k))$  rounds

# Parameterized Diameter Approximation

CONGEST

# Parameterized Diameter Approximation

CONGEST

- \*  $O(k)$  rounds algorithm that terminates with all vertices declaring

# Parameterized Diameter Approximation

CONGEST

- \*  $O(k)$  rounds algorithm that terminates with all vertices declaring
  - \* SMALL if diameter  $\leq k$

# Parameterized Diameter Approximation

CONGEST

- \*  $O(k)$  rounds algorithm that terminates with all vertices declaring
  - \* SMALL if diameter  $\leq k$
  - \* LARGE if diameter  $> 2k$

# Parameterized Diameter Approximation

CONGEST

- \*  $O(k)$  rounds algorithm that terminates with all vertices declaring
  - \* SMALL if diameter  $\leq k$
  - \* LARGE if diameter  $> 2k$
  - \* SMALL or LARGE unanimously if diameter is between  $k+1$  and  $2k$

# Parameterized Diameter Approximation

CONGEST

- \*  $O(k)$  rounds algorithm that terminates with all vertices declaring
  - \* SMALL if diameter  $\leq k$
  - \* LARGE if diameter  $> 2k$
  - \* SMALL or LARGE unanimously if diameter is between  $k+1$  and  $2k$
- \* Vertices report LARGE
  - \*  $\text{dia} \geq k+1$

# Parameterized Diameter Approximation

CONGEST

- \*  $O(k)$  rounds algorithm that terminates with all vertices declaring
  - \* SMALL if diameter  $\leq k$
  - \* LARGE if diameter  $> 2k$
  - \* SMALL or LARGE unanimously if diameter is between  $k+1$  and  $2k$

\* Vertices report LARGE

\*  $\text{dia} \geq k+1$

\* Vertices report SMALL

\*  $\text{dia} \leq 2k$



# Parameterized Distributed Vertex Cover

LOCAL

# Parameterized Distributed Vertex Cover

LOCAL

- \* Check if diameter is bounded by  $2k$  in  $O(k)$  rounds

# Parameterized Distributed Vertex Cover

LOCAL

- \* Check if diameter is bounded by  $2k$  in  $O(k)$  rounds
  - \* Vertices report LARGE:  $\text{dia} \geq 2k+1$

# Parameterized Distributed Vertex Cover

LOCAL

- \* Check if diameter is bounded by  $2k$  in  $O(k)$  rounds
  - \* Vertices report LARGE:  $\text{dia} \geq 2k+1$ 
    - \* No  $k$ -vertex cover exists

# Parameterized Distributed Vertex Cover

LOCAL

- \* Check if diameter is bounded by  $2k$  in  $O(k)$  rounds
  - \* Vertices report LARGE:  $\text{dia} \geq 2k+1$ 
    - \* No  $k$ -vertex cover exists
  - \* Vertices report SMALL:  $\text{dia} \leq 4k$

# Parameterized Distributed Vertex Cover

LOCAL

- \* Check if diameter is bounded by  $2k$  in  $O(k)$  rounds
  - \* Vertices report LARGE:  $\text{dia} \geq 2k+1$ 
    - \* No  $k$ -vertex cover exists
  - \* Vertices report SMALL:  $\text{dia} \leq 4k$ 
    - \* Learn the entire graph in  $O(k)$  rounds

# Parameterized Distributed Vertex Cover

LOCAL

- \* Check if diameter is bounded by  $2k$  in  $O(k)$  rounds
  - \* Vertices report LARGE:  $\text{dia} \geq 2k+1$ 
    - \* No  $k$ -vertex cover exists
  - \* Vertices report SMALL:  $\text{dia} \leq 4k$ 
    - \* Learn the entire graph in  $O(k)$  rounds
    - \* Elect a leader in  $O(k)$  rounds

# Parameterized Distributed Vertex Cover

LOCAL

- \* Check if diameter is bounded by  $2k$  in  $O(k)$  rounds
  - \* Vertices report LARGE:  $\text{dia} \geq 2k+1$ 
    - \* No  $k$ -vertex cover exists
  - \* Vertices report SMALL:  $\text{dia} \leq 4k$ 
    - \* Learn the entire graph in  $O(k)$  rounds
    - \* Elect a leader in  $O(k)$  rounds
    - \* Leader computes min VC and in  $O(k)$  rounds,



# Parameterized Distributed Vertex Cover

LOCAL

- \* Check if diameter is bounded by  $2k$  in  $O(k)$  rounds
  - \* Vertices report LARGE:  $\text{dia} \geq 2k+1$ 
    - \* No  $k$ -vertex cover exists
  - \* Vertices report SMALL:  $\text{dia} \leq 4k$ 
    - \* Learn the entire graph in  $O(k)$  rounds
    - \* Elect a leader in  $O(k)$  rounds
    - \* Leader computes min VC and in  $O(k)$  rounds,
      - \* Either notifies each vertex if it is in the  $k$ -solution or not

# Parameterized Distributed Vertex Cover

LOCAL

- \* Check if diameter is bounded by  $2k$  in  $O(k)$  rounds
  - \* Vertices report LARGE:  $\text{dia} \geq 2k+1$ 
    - \* No  $k$ -vertex cover exists
  - \* Vertices report SMALL:  $\text{dia} \leq 4k$ 
    - \* Learn the entire graph in  $O(k)$  rounds
    - \* Elect a leader in  $O(k)$  rounds
    - \* Leader computes min VC and in  $O(k)$  rounds,
      - \* Either notifies each vertex if it is in the  $k$ -solution or not
      - \* Or informs each vertex that no  $k$ -solution exists

# Parameterized Distributed Vertex Cover

LOCAL

- \* Check if diameter is bounded by  $2k$  in  $O(k)$  rounds
  - \* Vertices report LARGE:  $\text{dia} \geq 2k+1$ 
    - \* No  $k$ -vertex cover exists
  - \* Vertices report SMALL:  $\text{dia} \leq 4k$ 
    - \* Learn the entire graph in  $O(k)$  rounds
    - \* Elect a leader in  $O(k)$  rounds
    - \* Leader computes min VC and in  $O(k)$  rounds,
      - \* Either notifies each vertex if it is in the  $k$ -solution or not
      - \* Or informs each vertex that no  $k$ -solution exists

$O(k)$  rounds

# Parameterized Distributed Vertex Cover

LOCAL

- \* Check if diameter is bounded by  $2k$  in  $O(k)$  rounds
  - \* Vertices report LARGE:  $\text{dia} \geq 2k+1$ 
    - \* No  $k$ -vertex cover exists
  - \* Vertices report SMALL:  $\text{dia} \leq 4k$ 
    - \* Learn the entire graph in  $O(k)$  rounds
    - \* Elect a leader in  $O(k)$  rounds
    - \* Leader computes min VC and in  $O(k)$  rounds,
      - \* Either notifies each vertex if it is in the  $k$ -solution or not
      - \* Or informs each vertex that no  $k$ -solution exists

$O(k)$  rounds

Matching, Dominating Set, Edge Dominating Set, Feedback Vertex Set, Feedback Edge Set

# Parameterized Distributed Vertex Cover

CONGEST

- \* Check if diameter is bounded by  $2k$  in  $O(k)$  rounds
  - \* Vertices report LARGE:  $\text{dia} \geq 2k+1$ 
    - \* No  $k$ -vertex cover exists
  - \* Vertices report SMALL:  $\text{dia} \leq 4k$ 
    - \* Learn the entire graph in  $O(m)$  rounds
    - \* Elect a leader in  $O(k)$  rounds
    - \* Leader computes min VC and in  $O(k)$  rounds,
      - \* Either notifies each vertex if it is in the  $k$ -solution or not
      - \* Or informs each vertex that no  $k$ -solution exists

# Parameterized Distributed Vertex Cover

CONGEST

- \* Check if diameter is bounded by  $2k$  in  $O(k)$  rounds
  - \* Vertices report LARGE:  $\text{dia} \geq 2k+1$ 
    - \* No  $k$ -vertex cover exists
  - \* Vertices report SMALL:  $\text{dia} \leq 4k$ 
    - \* Learn the entire graph in  $O(m)$  rounds
    - \* Elect a leader in  $O(k)$  rounds
    - \* Leader computes min VC and in  $O(k)$  rounds,
      - \* Either notifies each vertex if it is in the  $k$ -solution or not
      - \* Or informs each vertex that no  $k$ -solution exists

# Parameterized Distributed Vertex Cover

CONGEST

- \* Check if diameter is bounded by  $2k$  in  $O(k)$  rounds
  - \* Vertices report LARGE:  $\text{dia} \geq 2k+1$ 
    - \* No  $k$ -vertex cover exists
  - \* Vertices report SMALL:  $\text{dia} \leq 4k$ 
    - \* Learn the entire graph in  $O(m)$  rounds
    - \* Elect a leader in  $O(k)$  rounds
    - \* Leader computes min VC and in  $O(k)$  rounds,
      - \* Either notifies each vertex if it is in the  $k$ -solution or not
      - \* Or informs each vertex that no  $k$ -solution exists

How to improve this step?

# Parameterized Distributed Vertex Cover

CONGEST

Guarantee Version



# Parameterized Distributed Vertex Cover

CONGEST

Guarantee Version

Suppose  $k$ -vertex cover exists

# Parameterized Distributed Vertex Cover

CONGEST

Guarantee Version

Suppose  $k$ -vertex cover exists

Diameter  $\leq 2k$

# Parameterized Distributed Vertex Cover

CONGEST

Guarantee Version

Suppose  $k$ -vertex cover exists

Diameter  $\leq 2k$

Algorithm  $k$ -VC Guarantee

# Parameterized Distributed Vertex Cover

CONGEST

Guarantee Version

Suppose  $k$ -vertex cover exists

Diameter  $\leq 2k$

Algorithm  $k$ -VC Guarantee

\* Find a leader vertex  $v$  in  $O(k)$  rounds

# Parameterized Distributed Vertex Cover

CONGEST

## Guarantee Version

Suppose  $k$ -vertex cover exists

Diameter  $\leq 2k$

## Algorithm $k$ -VC Guarantee

- \* Find a leader vertex  $v$  in  $O(k)$  rounds
- \* If a vertex is of degree  $> k$ 
  - \* Sets its flag to 1 and terminates after informing its neighbours (1 round)

# Parameterized Distributed Vertex Cover

CONGEST

## Guarantee Version

Suppose  $k$ -vertex cover exists

Diameter  $\leq 2k$

## Algorithm $k$ -VC Guarantee

- \* Find a leader vertex  $v$  in  $O(k)$  rounds
- \* If a vertex is of degree  $> k$ 
  - \* Sets its flag to 1 and terminates after informing its neighbours (1 round)
- \* If a vertex is of degree 0
  - \* Sets its flag to 0 and terminates after informing its neighbours (1 round)

# Parameterized Distributed Vertex Cover

CONGEST

## Guarantee Version

Suppose  $k$ -vertex cover exists

Diameter  $\leq 2k$

### Algorithm $k$ -VC Guarantee

- \* Find a leader vertex  $v$  in  $O(k)$  rounds
- \* If a vertex is of degree  $> k$ 
  - \* Sets its flag to 1 and terminates after informing its neighbours (1 round)
- \* If a vertex is of degree 0
  - \* Sets its flag to 0 and terminates after informing its neighbours (1 round)
- \* Any vertex that has not yet terminated has degree at most  $k$

# Parameterized Distributed Vertex Cover

CONGEST

Guarantee Version



# Parameterized Distributed Vertex Cover

CONGEST

Guarantee Version

Algorithm  $k$ -VC Guarantee (contd.)

# Parameterized Distributed Vertex Cover

CONGEST

Guarantee Version

Algorithm  $k$ -VC Guarantee (contd.)

- \* Any vertex that has not yet terminated has degree at most  $k$

# Parameterized Distributed Vertex Cover

CONGEST

## Guarantee Version

### Algorithm $k$ -VC Guarantee (contd.)

- \* Any vertex that has not yet terminated has degree at most  $k$
- \* Graph has  $O(k^2)$  (active) edges

# Parameterized Distributed Vertex Cover

CONGEST

## Guarantee Version

### Algorithm $k$ -VC Guarantee (contd.)

- \* Any vertex that has not yet terminated has degree at most  $k$
- \* Graph has  $O(k^2)$  (active) edges
- \* Learn the entire graph in  $O(k^2)$  rounds

# Parameterized Distributed Vertex Cover

CONGEST

## Guarantee Version

### Algorithm $k$ -VC Guarantee (contd.)

- \* Any vertex that has not yet terminated has degree at most  $k$
- \* Graph has  $O(k^2)$  (active) edges
- \* Learn the entire graph in  $O(k^2)$  rounds
- \* Leader computes min VC and in  $O(k)$  rounds

# Parameterized Distributed Vertex Cover

CONGEST

## Guarantee Version

### Algorithm $k$ -VC Guarantee (contd.)

- \* Any vertex that has not yet terminated has degree at most  $k$
- \* Graph has  $O(k^2)$  (active) edges
- \* Learn the entire graph in  $O(k^2)$  rounds
- \* Leader computes min VC and in  $O(k)$  rounds
  - \* Either notifies each vertex if it is in the  $k$ -solution or not

# Parameterized Distributed Vertex Cover

CONGEST

## Guarantee Version

### Algorithm $k$ -VC Guarantee (contd.)

- \* Any vertex that has not yet terminated has degree at most  $k$
- \* Graph has  $O(k^2)$  (active) edges
- \* Learn the entire graph in  $O(k^2)$  rounds
- \* Leader computes min VC and in  $O(k)$  rounds
  - \* Either notifies each vertex if it is in the  $k$ -solution or not
  - \* Or informs each vertex that no  $k$ -solution exists

# Parameterized Distributed Vertex Cover

CONGEST

## Guarantee Version

### Algorithm $k$ -VC Guarantee (contd.)

- \* Any vertex that has not yet terminated has degree at most  $k$
- \* Graph has  $O(k^2)$  (active) edges
- \* Learn the entire graph in  $O(k^2)$  rounds
- \* Leader computes min VC and in  $O(k)$  rounds
  - \* Either notifies each vertex if it is in the  $k$ -solution or not
  - \* Or informs each vertex that no  $k$ -solution exists

Complexity:  $ck^2$  rounds where  $c$  is a constant



# Parameterized Distributed Vertex Cover

CONGEST

# Parameterized Distributed Vertex Cover

CONGEST

Check if diameter is bounded by  $2k$  in  $O(k)$  rounds

# Parameterized Distributed Vertex Cover

CONGEST

Check if diameter is bounded by  $2k$  in  $O(k)$  rounds

\* Vertices report LARGE:  $\text{dia} \geq 2k+1$

# Parameterized Distributed Vertex Cover

CONGEST

Check if diameter is bounded by  $2k$  in  $O(k)$  rounds

- \* Vertices report LARGE:  $\text{dia} \geq 2k+1$ 
  - \* No  $k$ -vertex cover exists

# Parameterized Distributed Vertex Cover

CONGEST

Check if diameter is bounded by  $2k$  in  $O(k)$  rounds

- \* Vertices report LARGE:  $\text{dia} \geq 2k+1$ 
  - \* No  $k$ -vertex cover exists
- \* Vertices report SMALL:  $\text{dia} \leq 4k$

# Parameterized Distributed Vertex Cover

CONGEST

Check if diameter is bounded by  $2k$  in  $O(k)$  rounds

- \* Vertices report **LARGE**:  $\text{dia} \geq 2k+1$

- \* No  $k$ -vertex cover exists

- \* Vertices report **SMALL**:  $\text{dia} \leq 4k$

- \* Compute a leader and a **BFS** tree rooted at it in  $O(k)$  rounds

# Parameterized Distributed Vertex Cover

CONGEST

Check if diameter is bounded by  $2k$  in  $O(k)$  rounds

\* Vertices report LARGE:  $\text{dia} \geq 2k+1$

\* No  $k$ -vertex cover exists

\* Vertices report SMALL:  $\text{dia} \leq 4k$

\* Compute a leader and a BFS tree rooted at it in  $O(k)$  rounds

\* Run Algorithm  $k$ -VC Guarantee for  $ck^2$  rounds

# Parameterized Distributed Vertex Cover

CONGEST

Check if diameter is bounded by  $2k$  in  $O(k)$  rounds

- \* Vertices report LARGE:  $\text{dia} \geq 2k+1$

- \* No  $k$ -vertex cover exists

- \* Vertices report SMALL:  $\text{dia} \leq 4k$

- \* Compute a leader and a BFS tree rooted at it in  $O(k)$  rounds

- \* Run Algorithm  $k$ -VC Guarantee for  $ck^2$  rounds

- \* Not yet terminated: no  $k$ -vertex cover exists



# Parameterized Distributed Vertex Cover

CONGEST

Check if diameter is bounded by  $2k$  in  $O(k)$  rounds

\* Vertices report LARGE:  $\text{dia} \geq 2k+1$

\* No  $k$ -vertex cover exists

\* Vertices report SMALL:  $\text{dia} \leq 4k$

\* Compute a leader and a BFS tree rooted at it in  $O(k)$  rounds

\* Run Algorithm  $k$ -VC Guarantee for  $ck^2$  rounds

\* Not yet terminated: no  $k$ -vertex cover exists

\* Terminated: determine if the size of the vertex cover computed is indeed at most  $k$  in  $O(k)$  rounds

# Parameterized Distributed Vertex Cover

CONGEST

Check if diameter is bounded by  $2k$  in  $O(k)$  rounds

\* Vertices report LARGE:  $\text{dia} \geq 2k+1$

\* No  $k$ -vertex cover exists

\* Vertices report SMALL:  $\text{dia} \leq 4k$

\* Compute a leader and a BFS tree rooted at it in  $O(k)$  rounds

\* Run Algorithm  $k$ -VC Guarantee for  $ck^2$  rounds

\* Not yet terminated: no  $k$ -vertex cover exists

\* Terminated: determine if the size of the vertex cover computed is indeed at most  $k$  in  $O(k)$  rounds

Complexity:  $O(k^2)$  rounds

# Parameterized Diameter Approximation

CONGEST

- \*  $O(k)$  rounds algorithm that terminates with all vertices declaring
  - \* SMALL if diameter  $\leq k$
  - \* LARGE if diameter  $> 2k$
  - \* SMALL or LARGE unanimously if diameter is between  $k+1$  and  $2k$

\* Vertices report LARGE

\*  $\text{dia} \geq k+1$

\* Vertices report SMALL

\*  $\text{dia} \leq 2k$

# Parameterized Diameter Approximation

CONGEST

# Parameterized Diameter Approximation

CONGEST

Phase 1:  $k$  rounds

# Parameterized Diameter Approximation

CONGEST

Phase 1:  $k$  rounds

\* In each round,

# Parameterized Diameter Approximation

CONGEST

Phase 1:  $k$  rounds

- \* In each round,
  - \* Every vertex sends the min ID that it has seen so far to its neighbours

# Parameterized Diameter Approximation

CONGEST

Phase 1:  $k$  rounds

- \* In each round,

- \* Every vertex sends the min ID that it has seen so far to its neighbours

At the end of Phase 1, each vertex  $v$  has the **min ID  $x(v)$**  in its  $k$ -hop neighbourhood



# Parameterized Diameter Approximation

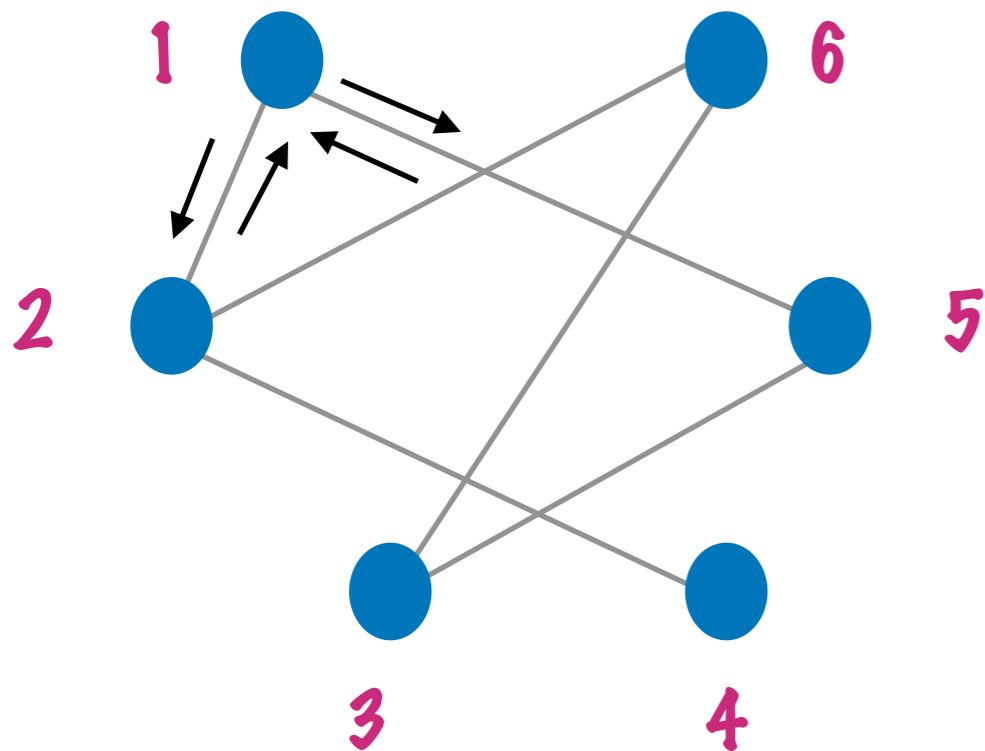
CONGEST

Phase 1:  $k$  rounds

\* In each round,

\* Every vertex sends the  $\min ID$  that it has seen so far to its neighbours

At the end of Phase 1, each vertex  $v$  has the  $\min ID x(v)$  in its  $k$ -hop neighbourhood



# Parameterized Diameter Approximation

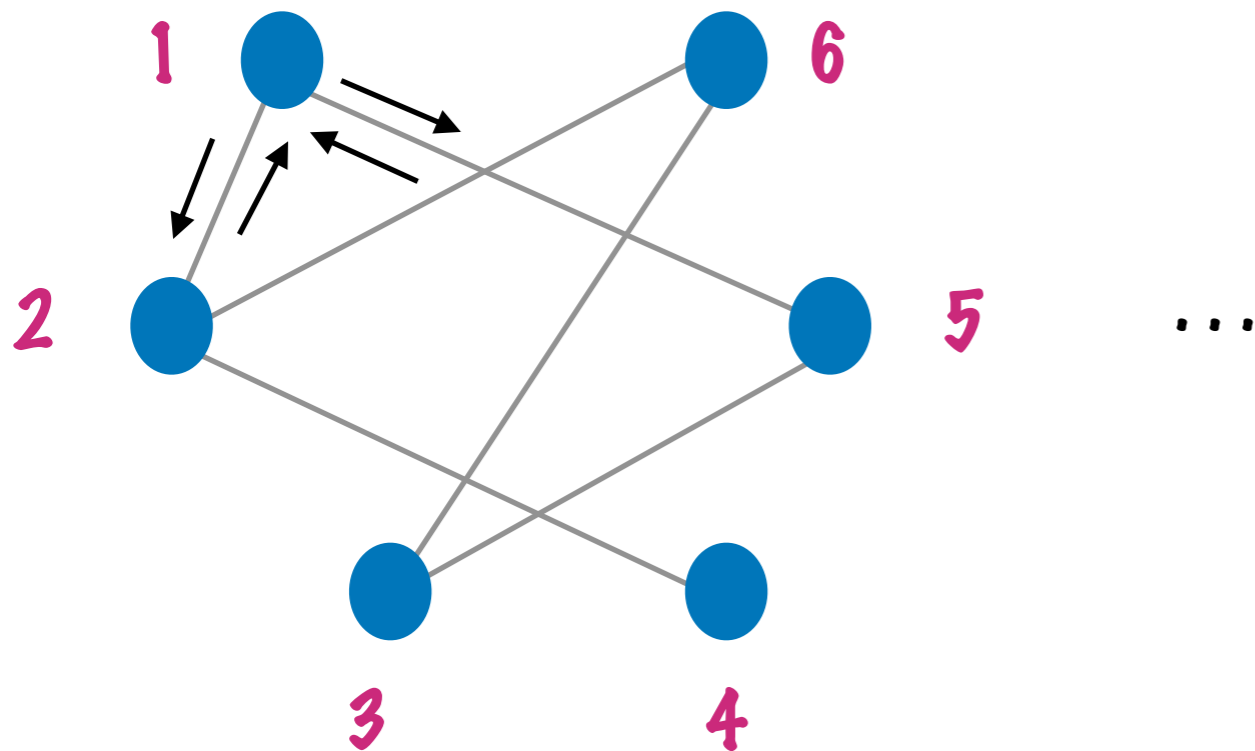
CONGEST

Phase 1:  $k$  rounds

\* In each round,

\* Every vertex sends the  $\min ID$  that it has seen so far to its neighbours

At the end of Phase 1, each vertex  $v$  has the  $\min ID x(v)$  in its  $k$ -hop neighbourhood



# Parameterized Diameter Approximation

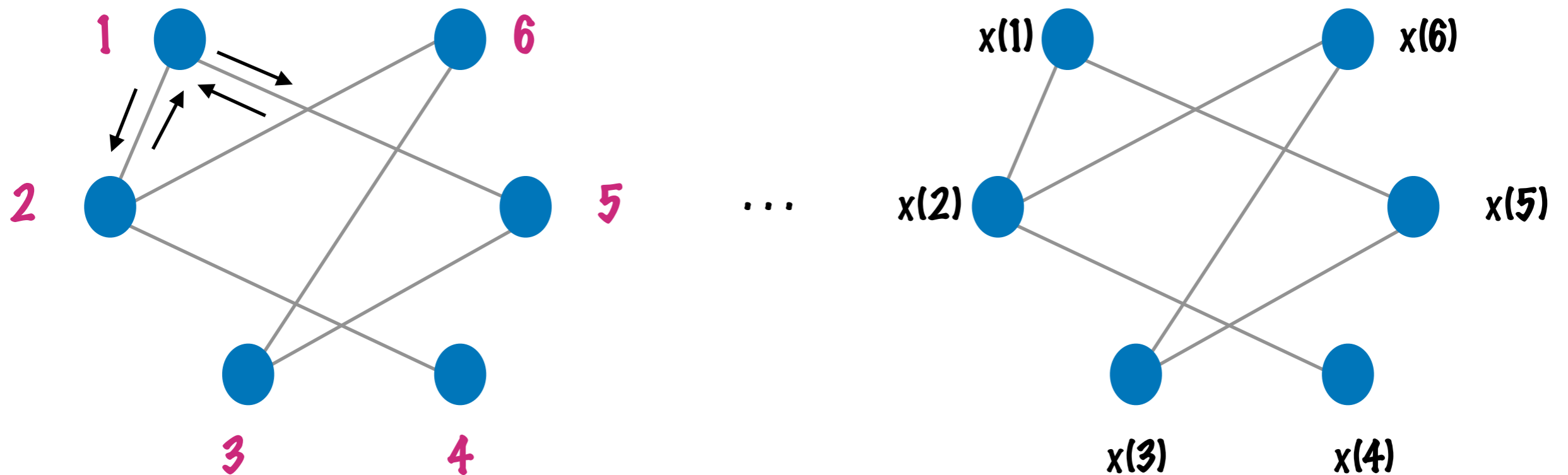
CONGEST

Phase 1:  $k$  rounds

\* In each round,

\* Every vertex sends the **min ID** that it has seen so far to its neighbours

At the end of Phase 1, each vertex  $v$  has the **min ID**  $x(v)$  in its  $k$ -hop neighbourhood



# Parameterized Diameter Approximation

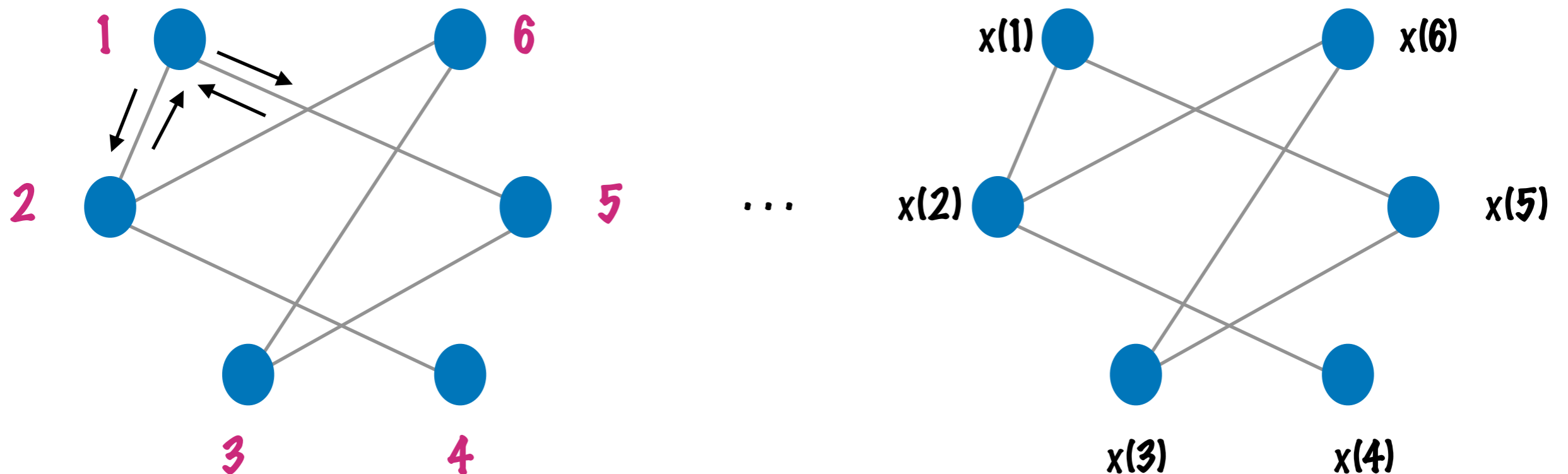
CONGEST

Phase 1:  $k$  rounds

\* In each round,

\* Every vertex sends the min ID that it has seen so far to its neighbours

At the end of Phase 1, each vertex  $v$  has the min ID  $x(v)$  in its  $k$ -hop neighbourhood



If  $\text{dia} \leq k$ , then  $x(v)$ s are identical

# Parameterized Diameter Approximation

CONGEST

# Parameterized Diameter Approximation

CONGEST

Phase 2:  $2k+1$  rounds

# Parameterized Diameter Approximation

CONGEST

Phase 2:  $2k+1$  rounds

\* In each round,

# Parameterized Diameter Approximation

CONGEST

Phase 2:  $2k+1$  rounds

- \* In each round,
  - \* Every vertex  $v$  sends  $y(v)$  (the min  $x(u)$ ) and  $z(v)$  (the max  $x(u)$ ) that it has seen so far to its neighbours

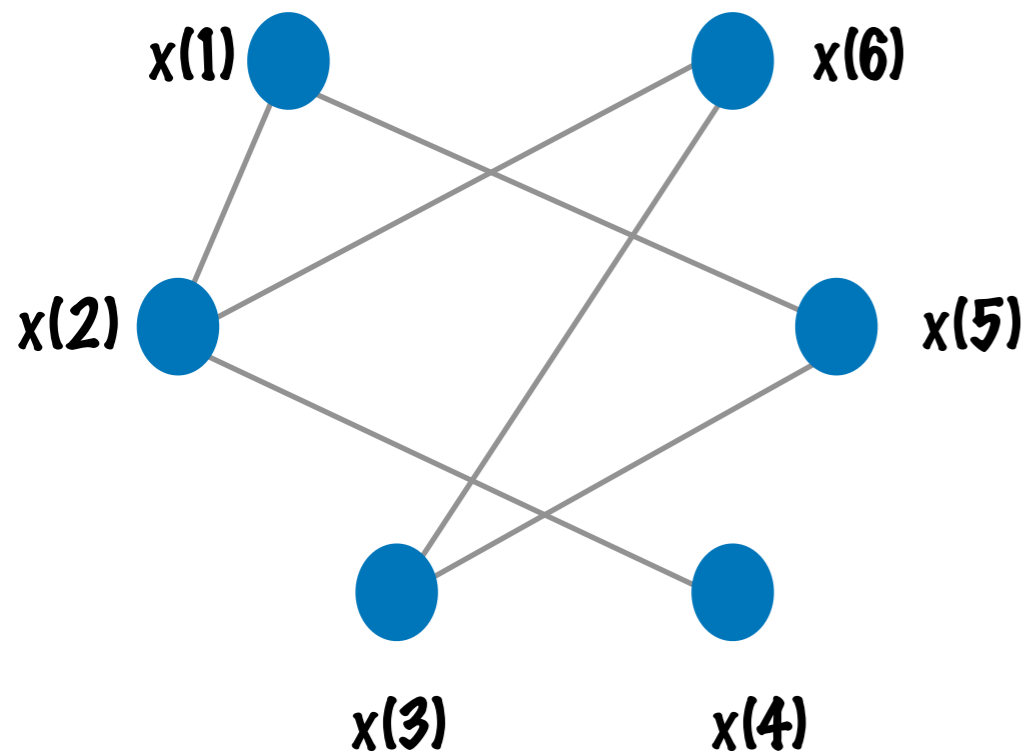


# Parameterized Diameter Approximation

CONGEST

Phase 2:  $2k+1$  rounds

- \* In each round,
  - \* Every vertex  $v$  sends  $y(v)$  (the min  $x(u)$ ) and  $z(v)$  (the max  $x(u)$ ) that it has seen so far to its neighbours

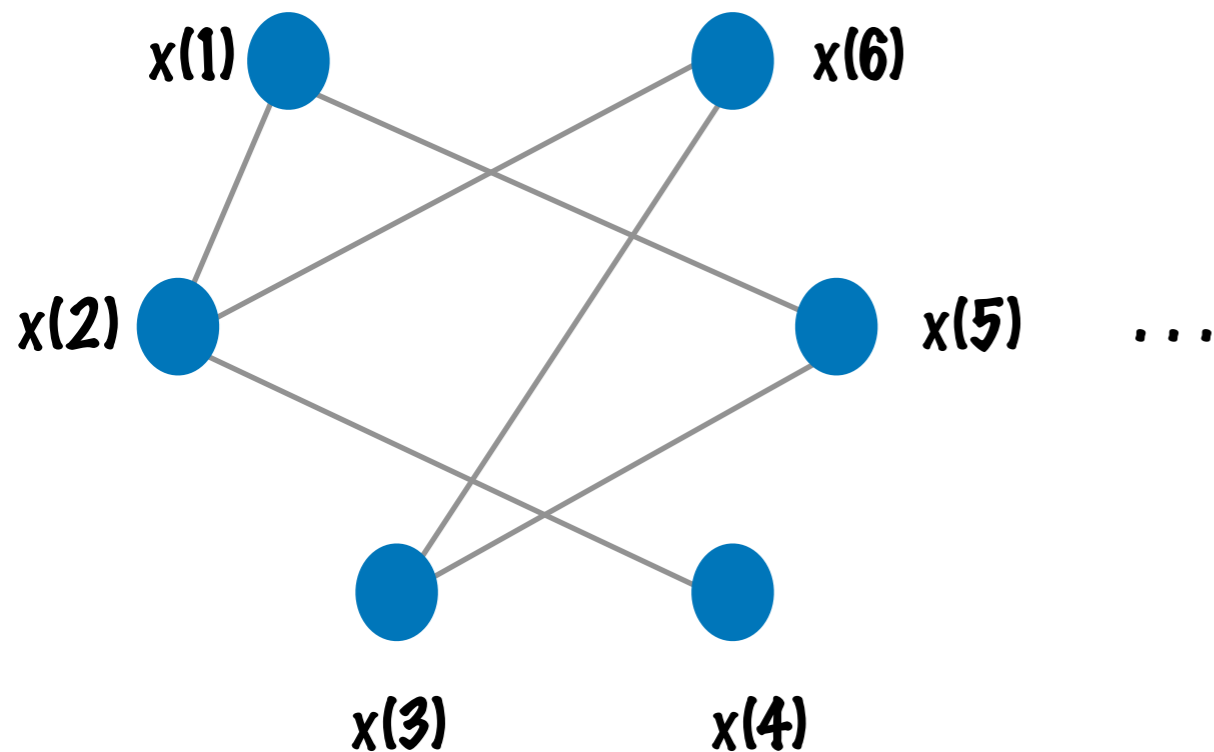


# Parameterized Diameter Approximation

CONGEST

Phase 2:  $2k+1$  rounds

- \* In each round,
  - \* Every vertex  $v$  sends  $y(v)$  (the min  $x(u)$ ) and  $z(v)$  (the max  $x(u)$ ) that it has seen so far to its neighbours

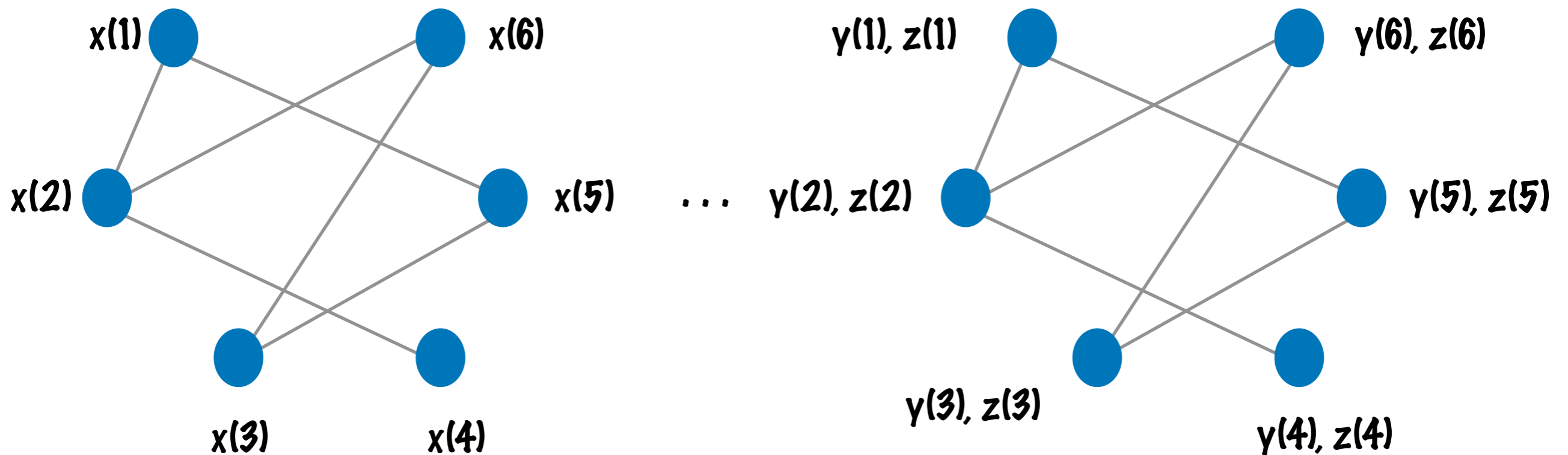


# Parameterized Diameter Approximation

CONGEST

Phase 2:  $2k+1$  rounds

- \* In each round,
  - \* Every vertex  $v$  sends  $y(v)$  (the min  $x(u)$ ) and  $z(v)$  (the max  $x(u)$ ) that it has seen so far to its neighbours

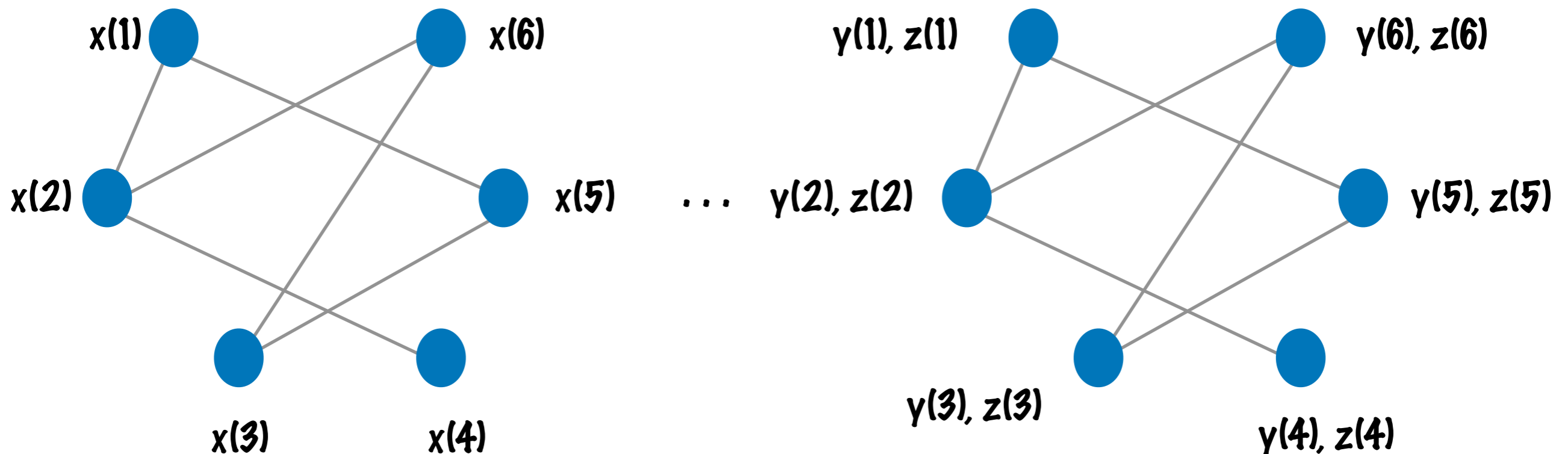


# Parameterized Diameter Approximation

CONGEST

Phase 2:  $2k+1$  rounds

- \* In each round,
  - \* Every vertex  $v$  sends  $y(v)$  (the min  $x(u)$ ) and  $z(v)$  (the max  $x(u)$ ) that it has seen so far to its neighbours



After the end of Phase 2, each vertex  $v$  returns

- \* **SMALL** if  $y(v) = z(v)$  and **LARGE** if  $y(v) \neq z(v)$

# Parameterized Diameter Approximation

CONGEST

# Parameterized Diameter Approximation

CONGEST

Phase 1:  $k$  rounds

\* In each round, every  $v$  sends  $\min ID$

At end of Phase 1, each  $v$  has  $\min ID$   $x(v)$  in its  $k$ -hop neighbourhood

Phase 2:  $2k+1$  rounds

\* In each round, every  $v$  sends  $y(v)$  ( $\min x(u)$ ) and  $z(v)$  ( $\max x(u)$ )

After the end of Phase 2, each  $v$  returns **SMALL** if  $y(v) = z(v)$  & **LARGE** if  $y(v) \neq z(v)$

# Parameterized Diameter Approximation

CONGEST

Phase 1:  $k$  rounds

\* In each round, every  $v$  sends  $\min ID$

At end of Phase 1, each  $v$  has  $\min ID$   $x(v)$  in its  $k$ -hop neighbourhood

Phase 2:  $2k+1$  rounds

\* In each round, every  $v$  sends  $y(v)$  ( $\min x(u)$ ) and  $z(v)$  ( $\max x(u)$ )

After the end of Phase 2, each  $v$  returns **SMALL** if  $y(v) = z(v)$  & **LARGE** if  $y(v) \neq z(v)$

$O(k)$  rounds

# Parameterized Diameter Approximation

CONGEST

Phase 1:  $k$  rounds

\* In each round, every  $v$  sends  $\min ID$

At end of Phase 1, each  $v$  has  $\min ID$   $x(v)$  in its  $k$ -hop neighbourhood

Phase 2:  $2k+1$  rounds

\* In each round, every  $v$  sends  $y(v)$  ( $\min x(u)$ ) and  $z(v)$  ( $\max x(u)$ )

After the end of Phase 2, each  $v$  returns **SMALL** if  $y(v) = z(v)$  & **LARGE** if  $y(v) \neq z(v)$

$O(k)$  rounds

\* If  $\text{dia} \leq k$ , then  $x(v)$ s are identical



# Parameterized Diameter Approximation

CONGEST

Phase 1:  $k$  rounds

\* In each round, every  $v$  sends  $\min ID$

At end of Phase 1, each  $v$  has  $\min ID$   $x(v)$  in its  $k$ -hop neighbourhood

Phase 2:  $2k+1$  rounds

\* In each round, every  $v$  sends  $y(v)$  ( $\min x(u)$ ) and  $z(v)$  ( $\max x(u)$ )

After the end of Phase 2, each  $v$  returns **SMALL** if  $y(v) = z(v)$  & **LARGE** if  $y(v) \neq z(v)$

$O(k)$  rounds

\* If  $\text{dia} \leq k$ , then  $x(v)$ s are identical

\* All vertices report **SMALL**

# Parameterized Diameter Approximation

CONGEST

Phase 1:  $k$  rounds

\* In each round, every  $v$  sends  $\min ID$

At end of Phase 1, each  $v$  has  $\min ID$   $x(v)$  in its  $k$ -hop neighbourhood

Phase 2:  $2k+1$  rounds

\* In each round, every  $v$  sends  $y(v)$  ( $\min x(u)$ ) and  $z(v)$  ( $\max x(u)$ )

After the end of Phase 2, each  $v$  returns **SMALL** if  $y(v) = z(v)$  & **LARGE** if  $y(v) \neq z(v)$

$O(k)$  rounds

- \* If  $\text{dia} \leq k$ , then  $x(v)$ s are identical
  - \* All vertices report **SMALL**
- \* If  $k+1 \leq \text{dia} \leq 2k$ , then  $y(v)$ s are identical,  $z(v)$ s are identical

# Parameterized Diameter Approximation

CONGEST

Phase 1:  $k$  rounds

\* In each round, every  $v$  sends  $\min ID$

At end of Phase 1, each  $v$  has  $\min ID$   $x(v)$  in its  $k$ -hop neighbourhood

Phase 2:  $2k+1$  rounds

\* In each round, every  $v$  sends  $y(v)$  ( $\min x(u)$ ) and  $z(v)$  ( $\max x(u)$ )

After the end of Phase 2, each  $v$  returns **SMALL** if  $y(v) = z(v)$  & **LARGE** if  $y(v) \neq z(v)$

$O(k)$  rounds

- \* If  $\text{dia} \leq k$ , then  $x(v)$ s are identical
  - \* All vertices report **SMALL**
- \* If  $k+1 \leq \text{dia} \leq 2k$ , then  $y(v)$ s are identical,  $z(v)$ s are identical
  - \* All vertices report **SMALL** or all vertices report **LARGE**

# Parameterized Diameter Approximation

CONGEST

Phase 1:  $k$  rounds

\* In each round, every  $v$  sends  $\min ID$

At end of Phase 1, each  $v$  has  $\min ID$   $x(v)$  in its  $k$ -hop neighbourhood

Phase 2:  $2k+1$  rounds

\* In each round, every  $v$  sends  $y(v)$  ( $\min x(u)$ ) and  $z(v)$  ( $\max x(u)$ )

After the end of Phase 2, each  $v$  returns **SMALL** if  $y(v) = z(v)$  & **LARGE** if  $y(v) \neq z(v)$

$O(k)$  rounds

# Parameterized Diameter Approximation

CONGEST

Phase 1:  $k$  rounds

\* In each round, every  $v$  sends  $\min ID$

At end of Phase 1, each  $v$  has  $\min ID$   $x(v)$  in its  $k$ -hop neighbourhood

Phase 2:  $2k+1$  rounds

\* In each round, every  $v$  sends  $y(v)$  ( $\min x(u)$ ) and  $z(v)$  ( $\max x(u)$ )

After the end of Phase 2, each  $v$  returns **SMALL** if  $y(v) = z(v)$  & **LARGE** if  $y(v) \neq z(v)$

$O(k)$  rounds

\* If  $\text{dia} \geq 2k+1$ , consider a vertex  $v$

# Parameterized Diameter Approximation

CONGEST

Phase 1:  $k$  rounds

\* In each round, every  $v$  sends  $\min ID$

At end of Phase 1, each  $v$  has  $\min ID$   $x(v)$  in its  $k$ -hop neighbourhood

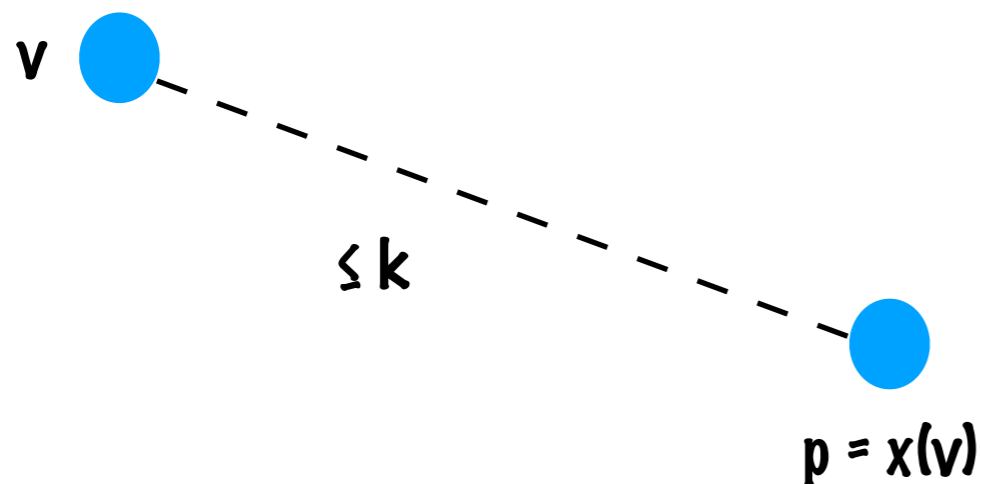
Phase 2:  $2k+1$  rounds

\* In each round, every  $v$  sends  $y(v)$  ( $\min x(u)$ ) and  $z(v)$  ( $\max x(u)$ )

After the end of Phase 2, each  $v$  returns **SMALL** if  $y(v) = z(v)$  & **LARGE** if  $y(v) \neq z(v)$

$O(k)$  rounds

\* If  $\text{dia} \geq 2k+1$ , consider a vertex  $v$



# Parameterized Diameter Approximation

CONGEST

Phase 1:  $k$  rounds

\* In each round, every  $v$  sends  $\min ID$

At end of Phase 1, each  $v$  has  $\min ID$   $x(v)$  in its  $k$ -hop neighbourhood

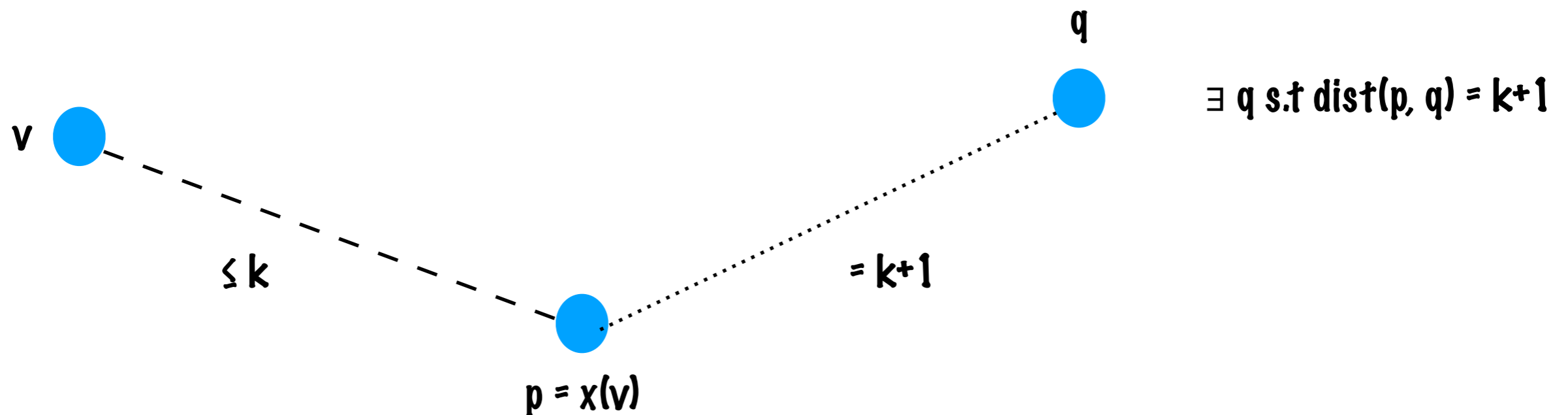
Phase 2:  $2k+1$  rounds

\* In each round, every  $v$  sends  $y(v)$  ( $\min x(u)$ ) and  $z(v)$  ( $\max x(u)$ )

After the end of Phase 2, each  $v$  returns **SMALL** if  $y(v) = z(v)$  & **LARGE** if  $y(v) \neq z(v)$

$O(k)$  rounds

\* If  $\text{dia} \geq 2k+1$ , consider a vertex  $v$



# Parameterized Diameter Approximation

CONGEST

Phase 1:  $k$  rounds

\* In each round, every  $v$  sends  $\min ID$

At end of Phase 1, each  $v$  has  $\min ID\ x(v)$  in its  $k$ -hop neighbourhood

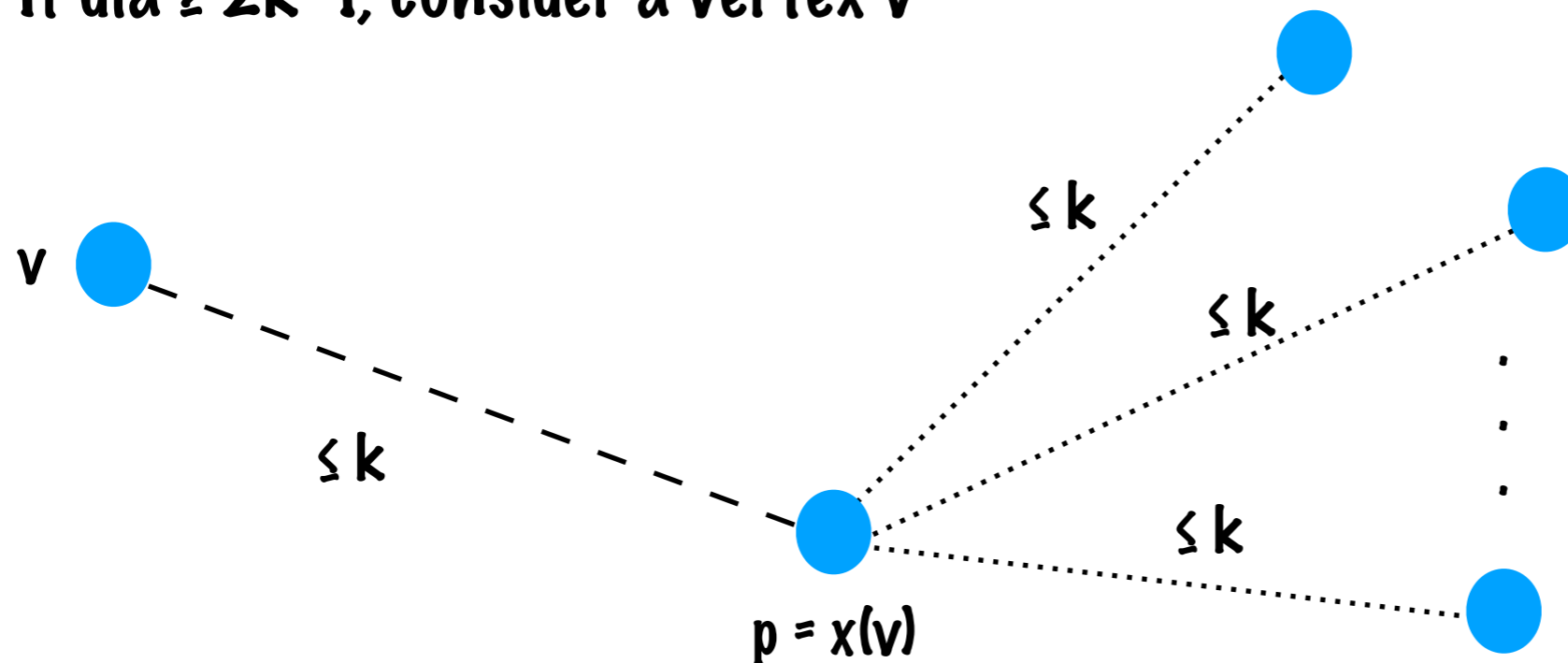
Phase 2:  $2k+1$  rounds

\* In each round, every  $v$  sends  $y(v)$  ( $\min x(u)$ ) and  $z(v)$  ( $\max x(u)$ )

After the end of Phase 2, each  $v$  returns **SMALL** if  $y(v) = z(v)$  & **LARGE** if  $y(v) \neq z(v)$

$O(k)$  rounds

\* If  $\text{dia} \geq 2k+1$ , consider a vertex  $v$



$\text{dia} \leq 2k+1$



# Parameterized Diameter Approximation

CONGEST

Phase 1:  $k$  rounds

\* In each round, every  $v$  sends  $\min ID$

At end of Phase 1, each  $v$  has  $\min ID$   $x(v)$  in its  $k$ -hop neighbourhood

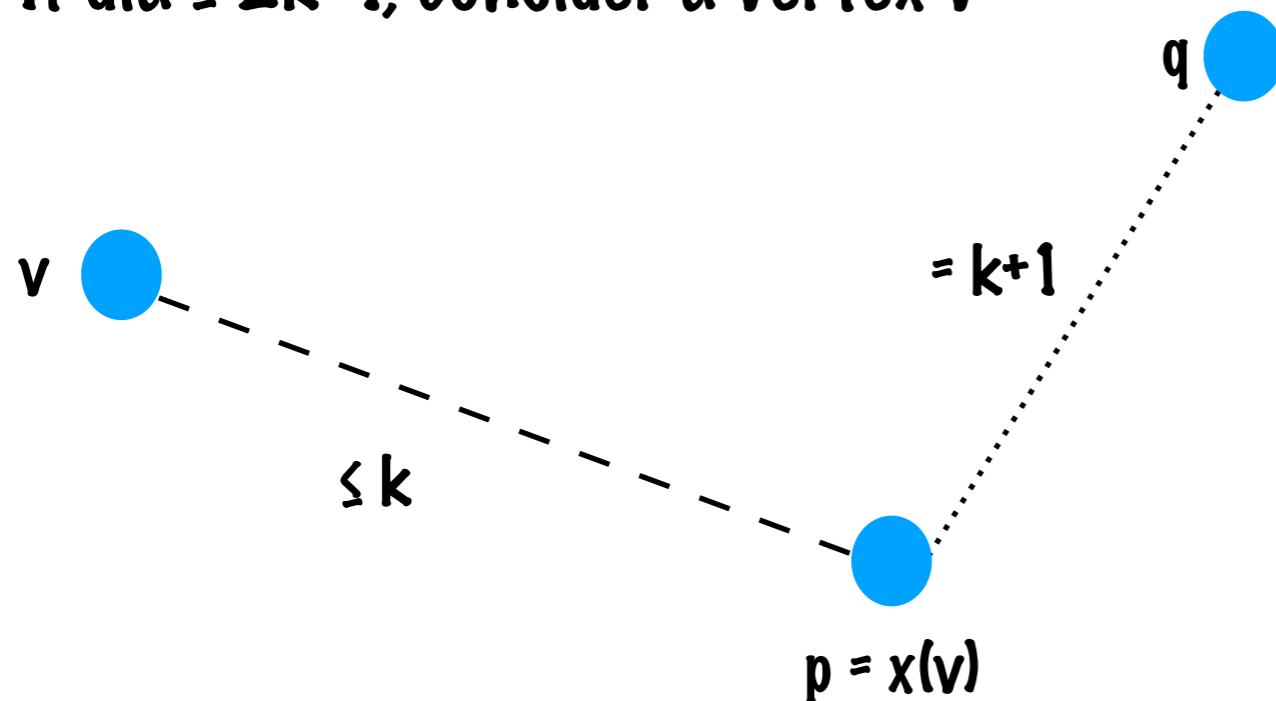
Phase 2:  $2k+1$  rounds

\* In each round, every  $v$  sends  $y(v)$  ( $\min x(u)$ ) and  $z(v)$  ( $\max x(u)$ )

After the end of Phase 2, each  $v$  returns **SMALL** if  $y(v) = z(v)$  & **LARGE** if  $y(v) \neq z(v)$

$O(k)$  rounds

\* If  $\text{dia} \geq 2k+1$ , consider a vertex  $v$



# Parameterized Diameter Approximation

CONGEST

Phase 1:  $k$  rounds

\* In each round, every  $v$  sends  $\min ID$

At end of Phase 1, each  $v$  has  $\min ID$   $x(v)$  in its  $k$ -hop neighbourhood

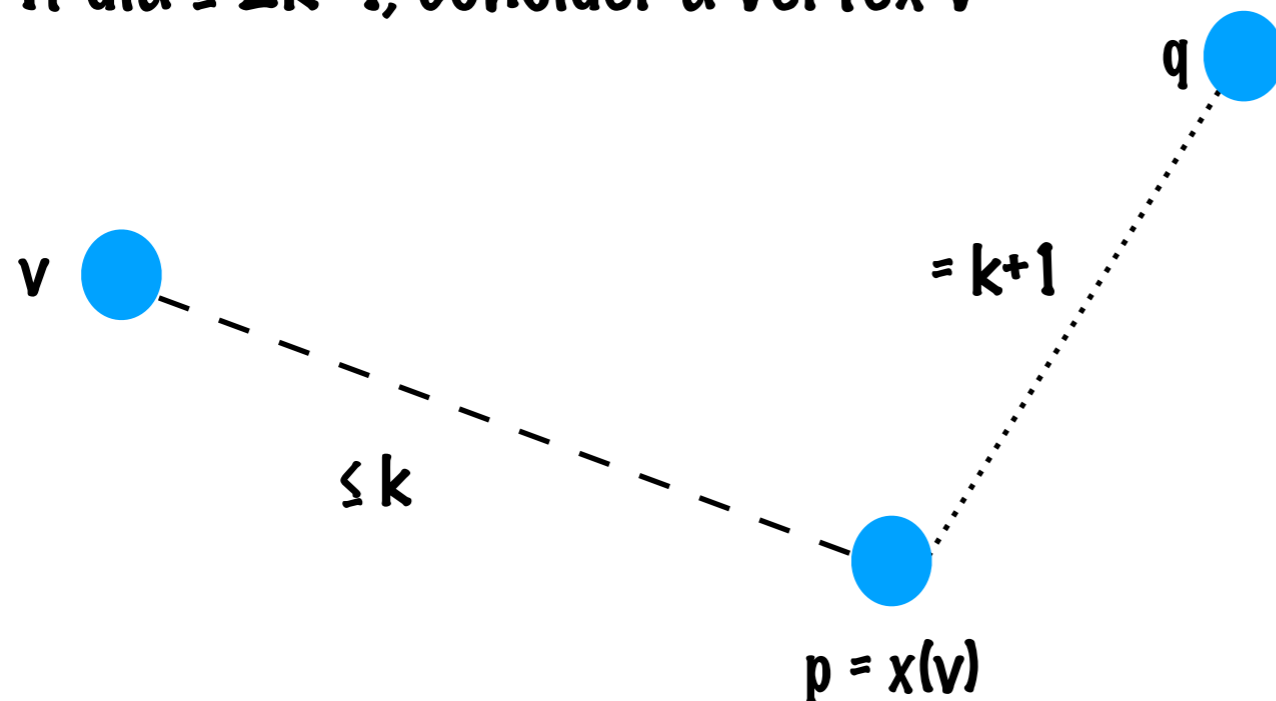
Phase 2:  $2k+1$  rounds

\* In each round, every  $v$  sends  $y(v)$  ( $\min x(u)$ ) and  $z(v)$  ( $\max x(u)$ )

After the end of Phase 2, each  $v$  returns **SMALL** if  $y(v) = z(v)$  & **LARGE** if  $y(v) \neq z(v)$

$O(k)$  rounds

\* If  $\text{dia} \geq 2k+1$ , consider a vertex  $v$



\* After  $k$  rounds of Phase 1,  $x(q) \neq p$

\* After  $k+1$  rounds of Phase 2,

\*  $y(p) \neq z(p)$

\* After next  $k$  rounds of Phase 2,

\*  $y(v) \neq z(v)$

\*  $v$  outputs **LARGE**

# Concluding Remarks

Problem	Model	Upper Bound	Lower Bound
Vertex Cover	CONGEST	$O(k^2)$	$\Omega(k^2/\log k \log n)$
	LOCAL	$O(k)$	$\Omega(k)$
Independent Set	CONGEST	$O(n^2)$	$\Omega(n^2/\log^2 n)$
	LOCAL	$O(k)$	$\Omega(k)$

Note: Lower bounds hold even when  $n$  is arbitrarily larger than  $k$

**Thank you!**

**Questions?**